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# An exploration into the sparse representation of Spectra



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A dissertation submitted to the Department of Electrical  
Engineering, University of Cape Town, in partial fulfillment of the  
requirements for the degree of Master of Science in Engineering

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## Declaration

I know the meaning of plagiarism and declare that all the work in the dissertation, save for that which is properly acknowledged, is my own. It is being submitted for the degree of Master of Science in Engineering in the University of Cape Town, Rondebosch, Cape Town. It has not been submitted before for any degree or examination in any other university.

Signature of Author ..... 

Signed on the 13<sup>th</sup> of February 2007, Cape Town

## Abstract

This thesis describes an exploration in achieving sparse representations of objects, with special focus on spectral data. Given a database of objects one would like to know the actual aspects of each class that distinguish it from any other class in the database. We explore the hypothesis that simple abstractions (descriptions) that humans normally make, especially based on the visual phenomenology or physics on the problem, can be helpful in extracting and formulating useful sparse representations of the observed objects. In this thesis we focus on the discovery of such underlying features, employing a number of recent methods from machine learning.

Firstly we find that an approach to automatic feature discovery recently proposed in the literature (Non Negative Matrix Factorization) is not as it seems. We show the limitations of this approach and demonstrate a more efficient method on a synthetic problem. Secondly we explore a more empirical approach to extracting visually attractive features of spectra from which we formulate simple re-representation of spectral data and show that the identification and discovery of certain intuitive features at various scales can be sufficient to describe a spectrum profile. Finally we explore a more traditional and principled automatic method of analyzing a spectrum at different resolutions (Wavelets). We find that certain classes of spectra can easily be discriminated between by a simple approximation of the spectrum profile while in other cases only the finer profile details are important.

Throughout this thesis we employ a measure called the separability index as our measure of how easy it is to discriminate objects in a database with the proposed representations.

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Thesis Supervisor : John Greene, Associate Professor in the Electrical

Engineering Department, UCT

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## Notation and Abbreviations

$n$  - Number of features or dimensions

$m$  - Number of instances/observations/objects.

$r$  - Number of basis

FOI - Features of interest

ICA - Independent Component Analysis.

NMF - Non-Negative Matrix Factorization

MRA - Multi Resolution Analysis

ANN – Artificial Neural Networks

MLP – Multi layer perceptrons

SI - Separability Index

SP- Sensitivity Parameter

TC – Target Class

NTC -Non Target Class

# Chapter 1

## Introduction

### 1.1 The need for sparse representation

The field of computational intelligence has come a long way over the past two to three decades producing such focus areas as Neural networks, Bayesian analysis and Support vector machines. In most of these architectures an object or a situation is represented in a vector form; for example the pixels in images, the wavelength intensities in spectrum and player's current positions on a board game. But it is well known that *most* of the sensory measurements are not relevant when one needs to describe an object especially in relation to other objects and naive vector representations tend to be highly redundant. A human, having sensed the whole object, would subsequently try and find only a small subset of salient features to describe the object by possibly asking the following questions:

- what is interesting (striking/appealing etc) about this object
- what could be the governing or the basic underlying structure

especially when given other objects in the domain. The agent would then try and use these features to form a concise re-description of the object. We propose that in machine-based pattern recognition it is worth the researcher's time to explore such underlying-structure-seeking descriptors or representations. This might improve the interpretability of the processing in the above architectures.

Inductive logic systems (as those mentioned above) have little to say about the underlying structure of the objects they are dealing with; what makes these objects different or whether the representations we used are the best for the particular problem. These types of advanced inductive algorithms have yielded improved results but often not significantly more than simpler systems [13]. Indeed algorithms such as k-means, Decision trees, Case Based Reasoning etc, that are based on simple geometric reasoning are still very common and are still often considered to be fundamentally the most significant algorithms in machine learning. Researchers have built systems with many tuning parameters that will tune the algorithm to produce slightly better results but still do not reveal much about the underlying patterns, relationships or important features of the data objects.

This we hypothesize is what a learning agent initially should try to discover in any situation or problem: it should try to compress the situation/object information and maybe store it as little "factoids" for future reference. The hypothesis explored in this thesis is that better results, understanding and design of simple learning systems could be achieved if they were based on the *explicit* discovery, capturing and re-representation of intuitive notions of objects. Most modern techniques in machine learning have not really focused on this aspect of dealing with data.

Some recent research has tended in this direction [12,19,21,32], where parts or features of the given object set are discovered and used to distinguish objects between each other [11,12 25,27]. This approach has the added advantage of discovering the parts that make an object and also revealing the intrinsic differences between the features that discriminate the objects. In this thesis we explore a number of ways of discovering and using these features to form alternative descriptions or representations of our original objects and investigate their potential value in machine-based inductive learning.

### 1.1.1 Sensor representation of spectra

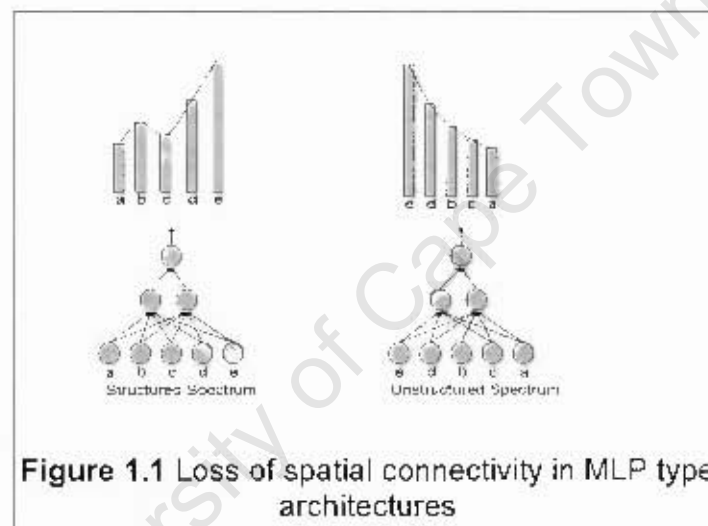
Spectra are usually described by a number of sensory measurements (for example the intensity at specific wavelengths) or variables called features. This description of an object is normally in vector form, thus an  $m$ -feature object can be taken as a point in  $m$ -dimensional space. The feature space dimensionality can be very high, as for example in images, where a 32x32 pixel sized image will be represented as a point in 1024 dimensional space. The 1024 dimension representation is often achieved by simply stringing together the pixels into one long vector, row by row.

Intuitively, of the 1024 'new' features, only a *small fraction* can be deemed to capture the essence of the actual object and the rest can be discarded. Indeed this problem is encountered in many instances of high dimensional data e.g. biotechnology (genome data), Internet text documents, movies, satellite imagery etc. This problem has been termed the curse of dimensionality [6]. Similarly, in spectral data only a few aspects/parts of the spectrum profile are important in isolating a particular spectrum from a group of spectra.

These parts are often announced by various visually obvious characteristic features, for example peaks and dips as well as the general trend of the profile. Thus by representing each spectrum measurement as a point in vector space one does not focus on the actual important discriminatory features but 'hides' them in the feature space. In images the *intrinsic structure* is also lost, for example the pixels that formed an eye in the 32x32 representation do not necessarily need to be next to each other (in the  $m = 1024$  representation) but could be intermingled with the nose pixels which could be next to background pixels and the resultant vector-string would still be considered an image from which the system is to determine coherent object-structure from.

Vector representation for the above domains has a major disadvantage when it is used in recent architectures such as MLP. The importance of the *intrinsic shape* of the object is lost – the connectivity between a series of successive sensory measurements in a spectrum is lost in the feature space representation. This is shown in figure 1.1 below where the order of the sensory inputs( $\lambda$ ) is randomized in the "unstructured spectrum" as compared to the measured "structured spectrum".

The order of the inputs is not important in these architectures but in the actual physics of the problem it is! In a classifier using vector represented spectra, classification performance would be completely unaffected by an arbitrary permutation applied to all the data objects – a transformation which would totally destroy all the features on which a human expert would rely on. The same observation applies to an image classification system in which images are represented by vectors formed by row-concatenation. In this case all the information in the vertical relations between rows would be lost. The immunity of machine classifiers to transformations which would be disastrous for human classifiers may point to a severe deficiency in this form of representation. This loss of spatial connectivity [30] can have a number of repercussions:



- *interpretability* of the learning process and the end results may be lost.
- The clustering/classification algorithms-(many of which rely on the statistics of the data) are trying to learn from a 'meaningless' representation. This can unnecessarily increase the classifier *complexity*, which will be trying to find the structure which was lost in the original representation itself.

- Processing *speed* is reduced in learning and searching from information from which relevant information has been lost

It appears that an alternative, more intuitive, object description could be advantageous. We would prefer a method or methods that can capture the underlying structure of an object while making as few assumptions as possible. In spectral data we would like to discover intuitive patterns for example: a spectrum's peaks and other irregularities, and their locations. This is analogous to a method that can discover the eyes, mouths and hair in facial images.

## 1.2 Finding structure

The above sections can be seen as proposing a focus on finding structure whilst staying more true to the physics or phenomenology of the problem. This means we explore how one may be able to find the underlying structure (parts) such that with this new compressed and intuitive form of spectrum representation one will be able to reveal the physical *causal* structure of the different spectral classes or objects. We explore the applicability of three different methods that can be used to discover intrinsic structure in data via completely different approaches.

We explore the applicability of the recent Non negative Matrix Factorization (NMF) [19],[20], that has provided promising results in images [14,19,21], to spectral data. Of particular interest is its non-negativity constraints on the way we approximate the input objects. This constraint is most significant to the interpretability of the method's discovered structural parts. It allows us to find a purely *additive* combination of positive matrix elements, in this way the positive elements sum to form a whole object. In the second section we explore simple representations of spectra based on salient features in the spectrum. These methods do not, per se, discover the underlying structure of a spectrum but expose what could be sufficient features to describe such objects. In the third section we consider the slightly older Wavelet [5], [16] method which is capable of representing objects to varying degrees of refinement. This refinement should lead to the identification and location of potential discriminatory parts of spectra through stochastic search using a genetic algorithm. The main difference between the above approaches is that in NMF one is trying to determine the spectrum structure in *relation* to other different spectra in the input database while in the other two approaches one

analyzes an *individual* spectrum to gain insights to its underlying structure. By re-representing these objects by their underlying features/parts we hope to obtain better discrimination ability as measured by a simple separability index [9]. The basic idea of this measure is to calculate the average number of data objects that have a similarly labeled nearest neighbor. The closer this value is to one, the easily separable is the data. The separability index has been shown to be closely related to the ease and/or difficulty of data classification [39,9].

### 1.3 Chapter 1 Summary

Unstructured vector representation of objects (for example movie clips, pictures and curves) is highly inadequate. An alternative method of representing these objects is to discover their underlying structure thereby describing them in terms of it. A recent line of research approaches is the representation of objects by their parts. We have motivated the reason for this in a number of domains where this might be useful or advantageous.

### 1.4 Thesis Layout

**Chapter 1** We motivate the need for a sparse representation of data in general and give tentative ideas on the type of features that can be used to efficiently represent objects in two different domains.

**Chapter 2** Covers the background to this work. We discuss related methods as well as the differences between our work and these. We introduce the Non Negative Matrix factorization concept. We formally describe this approach to the sparse representation of data and provide a motivating example for its application to spectral type data.

**Chapter 3** We experiment with NMF on real spectral data, analyze the results obtained by the method and discuss the limitations of the algorithm. To explain the limitations implied by the results, we do a detailed analysis of NMF in the context in which it is introduced - i.e image processing. This reveals some subtleties and complexities not evident at first sight and cast doubts on a naive interpretation of NMF as a simple decomposition into parts. This is in fact realized only in rather special( and contrived) circumstances.

**Chapter 4** We explore two simple intuitive representations of spectral data that are formulated from the physics of the problem (spectrum sensory measurements and resultant profile). We choose features that might perhaps be adequate to explain a spectrum. We model the transition between these features in two logically consistent ways.

**Chapter 5** We introduce the concept of Wavelets and genetic algorithms and motivate their combined application in this problem. The motivation for using wavelets is two fold; we would like to experiment with multiresolutional analysis in selecting appropriate features for discriminating spectra in different representations and to compare the performance of wavelet functions given two slightly different descriptions of the same object.

**Chapter 6** We consolidate all the spectrum sparsity approaches presented in the thesis. We highlight each method's advantages and disadvantages. Our contributions are noted and we conclude with possible future work.

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# Chapter 2

## 2. Background

In this chapter we review some of the most common approaches to the sparse representation of spectral data. The Non negative matrix factorization algorithm and its recent advances is introduced. The database to be used throughout the thesis is presented.

### 2.1 Alternative Approaches to sparse spectrum representation

Most of the common approaches to the re-representation of spectral data can be said to address the following questions:

- What *makes* two spectra from different classes to be classified differently? And having found these features/parts;
- Can we *use only* these features to describe spectra in a more efficient way? Closely linked to this question is the question -How can we model spectra with this information?

The new representation is further often required to have the following characteristics over the original representation of an object: it should be

- More intuitive - *Simple* and should capture what a human would easily look for.
- More Informative - reveal more of the discriminative features of the spectrum profile.
- More Condensed - it has to explain the spectrum in a *concise* and direct way.

### 2.1.1 Feature selection

The first obvious approach to the sparse representation of objects is feature selection where we select the features or attributes that when combined in a new representation maximize or minimize some criterion function. Substantial research has been done on different ways to achieve the best features; these vary from randomly selecting features from the initial feature set to structured methods e.g. Sequential forward/backward searching to exhaustive search [22,31] this can be done via the filter or wrapper approaches [22,31]. In the filter approach the criterion function is not linked to the classifier as in the wrapper approach.

In [26] a wrapper approach to feature selection is performed after a number of sub-intervals (parts) of a spectrum have been selected. The spectra were divided into  $x$  sub-intervals of equal sizes and a number of search strategies were employed to discover the most discriminating intervals. The authors concluded that a parts-based representation does produce better results. There are a number of known limitations of feature selection [31,22]. One of these we will just mention: the disregard for correlation and or mutual occurrence of features. This would be most pertinent in images and spectrum. In spectra consecutive sensory measurements are not random but lead to a specific profile (with particular transients) for each class of spectra thus a blind selection of features can destroy this interrelation between features.

This is also significant in images where each feature (pixel) has meaning only in relation to other pixels. Feature selection is usually not designed to discover the structural parts of objects but the lowest dimensional space that can represent a particular object for a particular goal (for example to visualize object class distribution) . The consensus in the literature seems to be that "there is no universally optimal method of feature selection", every problem is different [22].

## 2.1.2 Functional Models

Spectral data has been studied for a long time especially in remote-sensing and spectroscopic imaging [17,35]. A common approach in trying to discover the structure in such data has been to use a linear mixture model [17,28,29]. This approach assumes a given spectrum object is made up of known pure substances whose spectra is known. This is an unsupervised approach [29]. The pure substances are often called *endmembers*. The linear model is expressed as follows:

$$Y = E \times A + N \dots \dots \dots (1)$$

where for one object,  $Y$  ( $n \times 1$ ) is the unknown spectrum substance, the  $E$  ( $n \times p$ ) matrix consists of the assumed  $p$ -endmembers,  $A$  ( $p \times 1$ ) is the abundance/quantities of the endmembers and  $N$  ( $n \times 1$ ) is the noise model matrix. By approximating the unknown spectrum using spectra of known pure spectra, it is assumed one can identify and determine the proportions of each endmember [28,29]. A number of disadvantages of this modeling approach are known

- A huge library of potential pure spectra has to exist for each unknown input spectrum.
- The spectrum measurement range of the endmembers has to be the same as the measurements of the unknown spectra.
- The application scenario must be at the same measuring angles, atmospheric conditions as the library endmember spectra were.

A recent modification to the linear model approach has been to constrain the model by having statistically independent endmembers [28]. This is the Independent Component Analysis [15,36] paradigm. The only constraint placed on the components to be discovered is that they are to be statistically independent, thus they can be negative [15]. This means we can have subtractive 'additions' of elements which is not an intuitive concept and is inconsistent with parts-based representations. Furthermore as in the above model, the endmembers are assumed to be known. The objective of the method is to calculate the  $A$  matrix (often called the mixing matrix as in (1)) from the given observation matrix  $Y$ . In this

thesis we do not assume we have such a database but instead use the actual corpus of spectra to discover and identify prominent and characteristic parts. We use the actual spectra to tell us how they are made up.

In [1] a non linear functional approximation of a spectrum is proposed. Each spectrum is modeled by what the authors call a peak parameter representation (PPR); where a spectrum is described by just three features of a peak: its height (H), location (L) and width (W). A non-linear combination of  $n$  Gaussian or Lorentzian functions is assumed, where  $n$  is the number of predetermined significant peaks. We thus have:

$$\text{spectrum}_k = \sum_j^n \text{peak}_j(x) ,$$

where each  $\text{peak}_k(x)$  is any function we can associate with a concept of a peak. Thus a full spectrum can be described by a parameter vector  $p_k = [ (H_1, L_1, W_1), (H_2, L_2, W_2), \dots, (H_n, L_n, W_n) ]$ . This form of spectrum representation has the advantage of providing a highly compressed representation of spectra (in this case using only three features per peak). The *interpretation* of the resulting description can be very useful in understanding the interrelation amongst the features [1] and possibly between classes of spectra.

Different software packages exist for approximating such data. In [1] MATLAB<sup>(R)</sup>'s curve fitting toolbox using Levenberg & Marquardt approximation algorithm was used and the user is required to estimate/specify:

- the number of peaks in a spectrum (a separate script was written to identify these)
- the modeling function to be used (Spline/Gaussian/Lorentzian etc)
- the starting parameters[ H,L,W] of the model

Our approaches to be presented in chapter 4 follow a similar format of identifying the features of interest, modeling them and also incorporating a sensitivity parameter. The difference between this approach and ours is that we follow a very simple, explicit and

intuitive analogy making paradigm that a non-expert human might make in describing a spectrum.

### 2.1.3 Projection Approaches

Other approaches that somewhat estimate an object's underlying structure are the following: Principal Component Analysis (PCA) [40], Local Linear Embedding [34], Isomap [18], Manifold Embedding [3]. Most of these methods approach the problem by finding the lowest projection of the high dimensional data while preserving the relational structure of the objects in question. One of the concerns of this thesis is the physical interpretability of proposed representations. This is usually lost in these methods, mainly due to the projection techniques (e.g. PCA) employed which result in the resultant projected vectors losing their interpretability since for example *no non negative* constraints are set on the projection operators (e.g. in Eigenanalysis). This means data that was originally positive (be it financial, text, musical pitch measurements) can take on negative values. The positive objects that one could be working with do not have any intelligible meaning after such projections.

Indeed the features that are obtained by the PCA method tend to be distorted holistic images of the original objects [19,40] and not the intuitive parts one might expect. What these methods offer is dimension reduction but not an intelligible interpretation of the same object in this lower dimensional space. These geometric techniques do not make available the actual parts/features that capture/represent this lower dimension. To address the shortcomings of some of these approaches a method, Non negative matrix factorization (NMF), based on introducing non-negativity constraints on the features to be found has recently been proposed [19,20]. Section 2.3 presents this method. In order to facilitate a clearer picture of the features we are interested in in spectra, section 2.2 introduces a change in spectrum representation.

NMF was introduced primarily for its evident applicability to image processing and interpretation, and it is in this context that we will first study it, in the hope of clearly elucidating some of its more subtle features and conclusions. We will then consider its application to spectra (which are really a one dimensional image).

## 2.2 Database and experiment setup

The spectral database we use has 42 classes consisting of 7657 spectra each with 1024 sensory measurements. We combined the classes as follows: Class 1 = [Class 1 and class 2], Class 2 = [3 to 12] and class 3 = [13 to 14]. The non target classes were [15-42] now relabeled as classes [4-31]<sup>1</sup>. We selected the class pair comparisons shown in table 2.1 as class 1's non target classes we selected classes that had a separability index less than 98% and kept two easily separable classes (26 and 31) as 'controls'. Class 2 and 3's non target classes have a separability index less than 99% each with one 'control' (see table 2.1 below). The controls would be used to determine if this clear separability can be maintained by the new proposed representations.

TC	NTC	SI
1	5	0.972
	15	0.939
	16	0.962
	17	0.974
	20	0.949
	21	0.958
	26	1.000
	31	1.000

TC	NTC	SI
2	10	0.979
	12	0.981
	13	0.984
	18	0.987
	21	0.998
	22	0.989
	30	0.986
	31	1.000

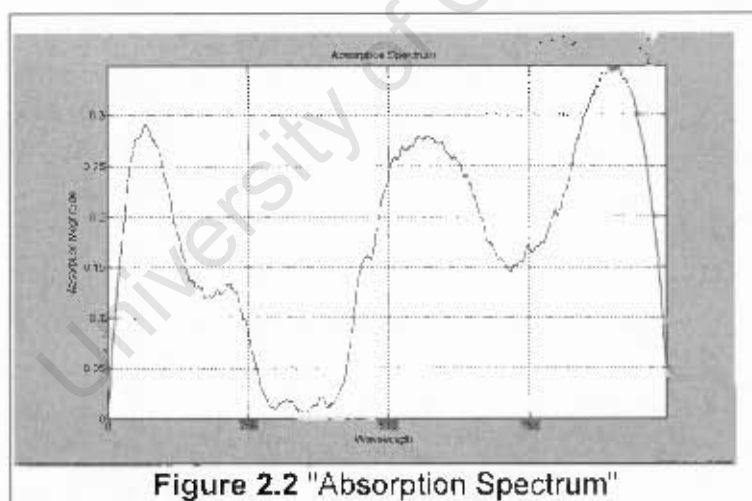
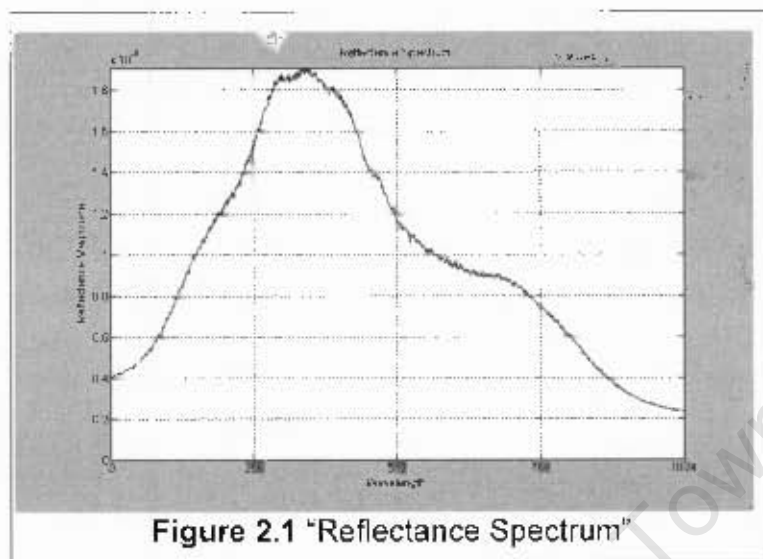
TC	NTC	SI
3	5	0.987
	7	0.999
	14	0.989
	16	0.983
	25	0.983
	26	1.000
	28	0.965

**Table 2.1** Selected Target and Non target classes for reflectance representation

We initially reformulate the spectrum representation by removing the convex hull. This is a common starting point in the processing of spectral data in spectroscopy research [17,38]. This makes it easier to obtain potentially interesting parts of each spectrum and specifically reveals the absorption peaks, an attractive conceptual category in terms of which humans experts can discriminate spectra. However it needs to be established whether this (nonlinear) transformation assists or impairs the categorization of the spectra. To determine how this new formulation changes the separability of the classes as compared to the given measuring instrument formulation a comparison between the two is shown in table 2.2 (see Appendix B for a full tabulation). Each class is split into 5 'training sets', the separability index calculated

<sup>1</sup>The separability index between all the class comparisons is shown in appendix A

and an average of these five runs is used as the final S.I value in the table. In the rest of the thesis the original representation (figure 2.1) will be known as the "Reflectance" spectrum and figure 2.2 (with the convex hull removed) will be known as the "Absorption" spectrum.



It is clear from the above figures that a much more visually appealing information is available in figure 2.2 after the convex hull removal. As can be seen from table 2.2 and appendix B the change in representation from reflectance to absorption does not significantly lower the separability indices between classes but often improves it.

Reflectance Data			Reflectance Data			Reflectance Data		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.972	2	10	0.9786	3	16	0.9834
1	15	0.9389	2	12	0.9814	3	18	0.9868
1	26	1	2	31	1	3	26	1
Absorption Data			Absorption Data			Absorption Data		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.971	2	10	0.981	3	16	0.9829
1	15	0.967	2	12	0.9809	3	18	0.9889
1	26	1	2	31	0.9997	3	26	1

**Table 2.2** Effects of changing from reflectance to absorption representation on Separability index(*S.I*)between target (*TC*) and non target classes (*NTC*)<sup>2</sup>

This is the form of spectrum formulation that will be used in the Non Negative Matrix Factorization (NMF) analysis. In the next section we introduce the NMF theory and devise a motivation example for the applicability of NMF to the discovery of constituent parts of a spectra database. In this way we hope to discover which parts (if possible, distinct parts) can be attributed for the different spectral class. This would then allow us to formulate a new sparse representation of all the spectral classes.

## 2.3 Non Negative Matrix Factorization

### 2.3.1 NMF Theory

Non negative matrix factorization (NMF) is a recently introduced concept [19,20]. The basic idea of NMF is that given a positive matrix *V* we approximate it by a product of two non negative matrices *W* and *H*. The non negativity constraint on the approximation matrices is the core of the algorithm. It leads to only additive combinations of the matrix elements since there will be no negative elements.

<sup>2</sup> A separability index of 1 means the classes are clearly separable.

Formally: Given a non negative  $n \times m$  matrix  $V$  ( $m$  vectors, each with  $n$  elements/features), NMF finds a non negative  $n \times r$  matrix  $W$  and a non negative  $r \times m$  matrix  $H$  such that  $V \approx WH$ . This leads to the interpretation of the constant  $W$  columns as being the general features present in all the input vectors ( $m$ ) but they occur in different amounts (accounted for by the elements of  $H$ ). The columns of  $W$  are called the basis or parts and the row elements of the  $H$  are the abundances or coefficients.

Since we do not know how many general parts the input matrix can be minimally factorized into we have a user specified parameter  $r$  which also controls how much dimensional reduction we can achieve, it is limited by:

$$r < \frac{(n \times m)}{(n + m)} \text{ see [19,20].}$$

To determine the approximation accuracy of the decomposition an objective function has to be defined, the Euclidian or the Divergence objective functions have been used in the literature (see Section 2.33). The problem is then simplified to:

*Minimizing the objective function under the non-negativity constraints.*

The original NMF algorithm [20] used the multiplicative update learning rule in contrast to the gradient descent updating technique normally employed in function minimization. The Euclidian objective function is minimized via the following update scheme:

$$W_{ic} \leftarrow W_{ic} \frac{(VH^T)_{ic}}{(WHH^T)_{ic}}$$

$$H_{cj} \leftarrow H_{cj} \frac{(W^T V)_{cj}}{(W^T W H)_{cj}}$$

Where the  $i$  refers to a particular row element, the  $c$  to a column element in  $W$  whereas the  $j$  refers to a column element in  $H$ . The  $c$  is common to both matrices since the number of rows

in  $H$  is the same as the number of columns in  $W$ . The multiplication and divisions in the above and subsequent equations are performed element by element. In the updating of  $W$ 's element at position (2,3) for example, the current value of  $W$  at (2,3) on the right hand side is multiplied by the current quality of decomposition matrix factor  $[VH' / WHH']$  at the corresponding positions, (2,3) of this matrix. The closer the  $WH$  approximation is to  $V$  the more this factor approaches unity. A similar explanation can be given for the updating of  $H$ 's elements. Subsequent to [19,20] a number of alternative updating schemes and objective function have been presented (see Section 2.3.3). Most of this work on NMF has been mainly on facial images [10,14,21,32]. The results obtained in this domain have been encouraging but little research in other domains has been done. Thus we explore the applicability of NMF in spectral data!

### 2.3.2 The promise of NMF

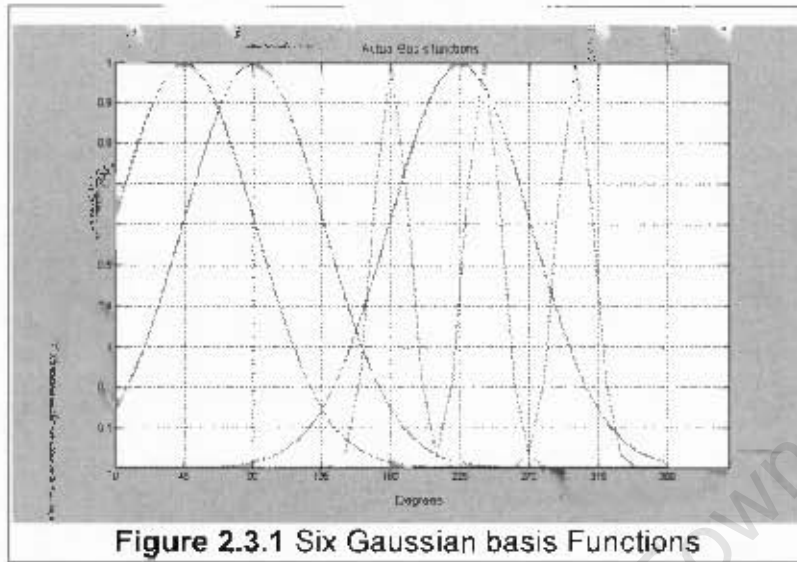
In this section we present a simple synthetic example to motivate the potential applicability of non negative matrix factorization for the decomposition of spectral data into intuitive parts. We specifically show that NMF can discover the underlying parts, with approximately correct locations and profiles, of a number of spectral profiles. We setup two sets of exponential Gaussian functions;

$$e^{-\frac{(x-x_0)^2}{2\sigma^2}}$$

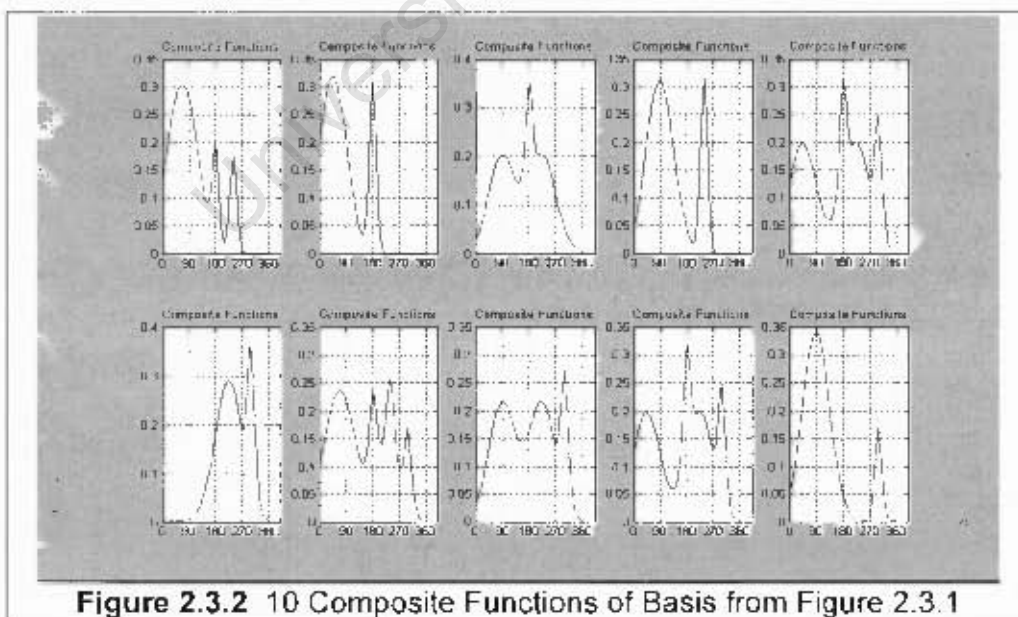
The first has a sigma ( $\sigma$ ) or width parameter of 0.8 centred ( $x_0$ ) at 45 degree intervals and the second with a  $\sigma$  value of 0.2 centred at 60 degree intervals. We randomly combine these basis Gaussian functions, sampled at 10 degree intervals in the range from 0 to 360 degrees, to form  $m = 10$  composite spectra. Our spectra input matrix is thus  $V$ , (37x10). For factorization we can determine the upper bound for  $r$ , which is given in [19],[20] by:

$$r < \frac{(n \times m)}{(n + m)}, \quad r < \frac{(37 \times 10)}{(37 + 10)}, \quad r < 7.87.$$

This means the maximum number of basis we can search for is 7. So the number of basis/parts that reasonably constitute the input objects is smaller than 7.



Note the widths of the basis functions in figure 2.3.1 are not the same. For clarity and simplicity we equated the amplitudes of the exponential functions. Figure 2.3.2 shows the L2 normalized input composite functions formed by randomly combining the basis functions in figure 2.3.1. We applied all the algorithms given in Section 2.3.3 and the typical results of the Non negative matrix factorization with sparseness constraint (NMFSC) algorithm by P.Hoyer [14] are shown below in figure 2.3.3



We set the number of basis vectors to be discovered to  $r=6$  since we know that 6 basis were used in the formation of the input dataset. In a practical problem setting we would have to search for a reasonably good looking basis set by experimenting with different values of  $r$  less than 7 as explained above

The  $sW$  and  $sH$  specify the amount of sparsity each of the matrices should have. A high value (values vary between 0 and 1) indicates that we want the corresponding matrix to have few components active and vice versa. In this setting we would want a few bases (gaussian functions) to be active with an unconstrained or slightly sparse (meaning many active) coefficient elements to account for the abundances or effects of the basis contribution in the input matrix. After a number of combinations of these parameters were explored the results presented in figure 2.3.3 presented the best<sup>3</sup> basis.

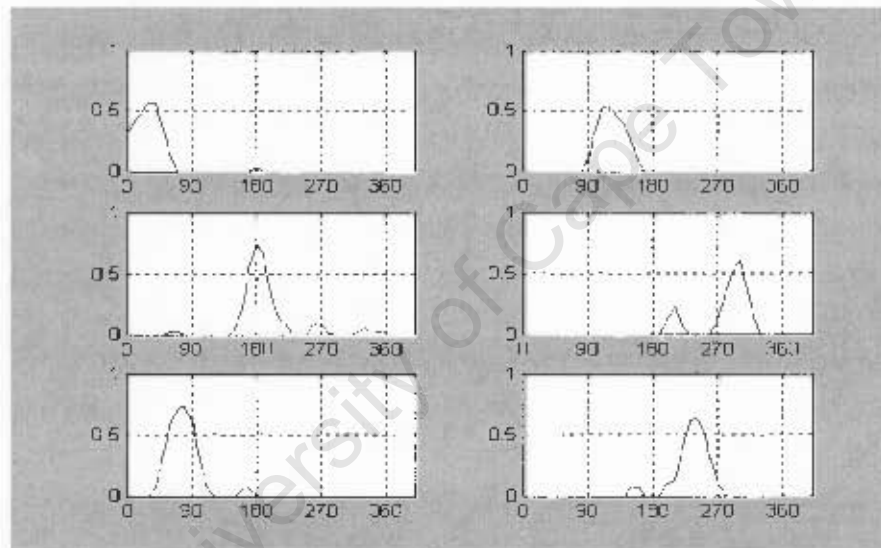


Figure 2.3.3 NMFSC results at  $sW=0.70$  &  $sH=0.10$

Most of the basis found by NMF in this example are not well defined in terms of the correct profiles and locations. Some of the basis found look somewhat like composite functions.

<sup>3</sup> The quality of bases discovered is initially a subjective matter. Obviously classification (an objective form of evaluation) etc can be applied at a later stage. But to narrow the search for a good bases set it seems user subjectivity is required.

In general the results found by NMF on this example are not as we expected from the encouraging though imperfect results in facial images in the literature (see section 3.2). Besides the lack of high decomposition accuracy of the method some form of differences (especially the profiles) is notable in the bases found but one is not clear whether this is as a result of the factorization approximation or it is a definite 'intended' solution. But the method seems to exhibit potential and to further explore its capability we explore its applicability on real datasets of spectral data. We first introduce the different variations of the non negative matrix factorization algorithm before experimenting with real datasets.

### 2.3.3 Recent NMF advances

In this section we introduce as well as describe the differences between recent popular non-negative matrix factorization algorithms these are:

- a) Local NMF by Li.S et al. [21]
- b) Sparse NMF by Liu W et al [23]
- c) NMF with sparseness constraint by P.Hoyer [14]

#### a) Local Non-Negative Matrix Factorization (LNMF)

LNMF was introduced to mitigate the limitations of the applicability of the original NMF[19] algorithm on some databases. When the original NMF algorithm was applied to a different database, of the same domain, which was not as heavily pre-processed as the one in [19] NMF discovered holistic basis. It was noted in [21] that the pre-processing (e.g alignment and rotations) of input objects can drastically influence the results obtained by NMF. This algorithm offers a much better set of bases in both datasets as compared to the NMF algorithm from [19].

This method uses a multi-constrained Divergence objective function:

$$D(V||WH) = \sum (V \log \frac{V}{WH} - V + WH) + \alpha \sum W^T W - \beta \sum H^T H$$

with  $\alpha$  and  $\beta$  being user specified parameters and where the  $\alpha \sum W^T W$  and the  $\beta \sum H^T H$  components of the objective function constrains the basis to be:

- mostly non-zero.
- as different as possible, that is, be orthogonal.
- and the bases are to be as expressive as possible

This method implements the multiplicative approach in finding the minimum of the objective function. This results in the following update strategy:

$$H_{al} \leftarrow \sqrt{H_{al} \sum_i W_{ia}^T \frac{V_{il}}{(WH)_{il}}}$$

$$W_{ia} \leftarrow W_{ia} \sum \frac{V_{il}}{(WH)_{il}} H_{al}^T$$

Then the bases are normalized to have unit length

$$W_{ia} \leftarrow \frac{W_{ia}}{\sum_l W_{ia}}$$

Where again the  $[\cdot]_{ia}$  indicate the element by element multiplications and divisions of the matrices.

#### b) Sparse Non Negative Matrix Factorization (SNMF)

Another method introduced to provide sparsity in the basis to be discovered is SNMF. This method uses the following divergence objective function:

$$D(V||WH) = \sum (V \log \frac{V}{WH} - V + WH) + \alpha \sum H$$

with the multiplicative updating of the coefficients and basis.

$$W_{ia} \leftarrow \frac{W_{ia} \sum_l \frac{V_{il}}{(WH)_{il}} H_{al}^T}{\sum_l H_{al}^T}$$

$$H_{au} \leftarrow \frac{H_{au} \sum_a W_{ia}^T \frac{V_{iu}}{(WH)_{iu}}}{(1 + \alpha)}$$

There is also a basis normalization step

$$w_{ia} = \frac{w_{ia}}{\sum_j w_{ja}}$$

and  $\alpha$  is a user specified parameter. The main difference between these methods is the way they incorporate the sparsity factor in their objective functions.

### c) Non Negative Matrix Factorization with sparseness constraint (NMFSC)

A more powerful and general method of NMF is NMFSC. This algorithm incorporates open parameters to control the amount of sparsity one may deem necessary in both the  $W$  and the  $H$  matrices. This is important as one may have situations where prior information has a bearing on what needs to be sparse. An example would be in audio recordings one may know that only a certain few notes dominate and that these notes occupy most of the music segments. Here you would want to have the  $W$  matrix sparse to find those few notes but the  $H$  matrix unconstrained as the abundances of the notes is quite high in the time segments taken.

This method uses the Euclidean objective function

$$\frac{1}{2} \|V - WH\|^2$$

that is optimized via the gradient descent approach. *Updating W*: If the sparsity of  $W$  is specified

$$W \leftarrow W - \mu(WH - V)H^T$$

where  $\mu$  is the gradient step size, then you implement the projection step (see projection step below). If the sparsity of the basis is not specified then the algorithm uses the standard [19] multiplicative update rule

$$W_{ic} \leftarrow W_{ic} \frac{(VH^T)_{ic}}{(WHH^T)_{ic} + eps}$$

*Updating H*

If the sparsity of  $H$  is given, the following update rule is used

$$H \leftarrow H - \eta(W^T(WH - V))$$

where  $\eta$  is the gradient step size then the projection step below is implemented and if the sparsity of the coefficients is not specified, the multiplicative update is used

$$H_{cj} \leftarrow H_{cj} \frac{(W^T V)_{cj}}{(W^T WH)_{cj} + eps}$$

where  $eps = 1 \times 10^{-9}$ . Normalize the rows of  $H$  on a unit sphere and multiply each element in the  $i^{\text{th}}$  column of each basis by the normalized,  $i^{\text{th}}$  row of  $H$ . The updating of the  $W$  &  $H$  components are such that a constantly decreasing objective function is achieved. The sparsity is incorporated in the updating step of the basis and the coefficient matrices. This is done via a projection step [14].

## Projection function

When the sparsity of the basis is specified the projection step updates the basis by restricting the L1-norm (columns) of the  $W$  to achieve the specified sparsity. The L2-norm is

to be unchanged. If the sparsity of the rows of  $H$  is specified, then the L2 norm is restricted to a unit sphere and the L1-norm (rows of  $H$ ) is set to achieve the specified sparsity. In both cases the problem is then to solve for the equivalence of the projected L1 norm and the L2 norm, i.e. the sum constraint plane and the unit sphere.

This therefore requires the user to experiment with  $s_W$  and  $s_H$  according to what one wants to sparsify, do we want as few as possible parts/basis or do we need their abundances (coefficient matrix elements) to be maximized?

### 2.3.4 User Parameters

There are several parameters that a user needs to specify in the NMF algorithms these are:

- the number of columns  $r$  or basis to be discovered
- the algorithm termination criterion and
- in the case of NMFSC and LNMF the sparsity factors have to be specified before hand. These factors are generally considered classic model selection parameters in that there are no definite rules for approximating them.

## 2.4 Chapter 2 Discussion

Non negative matrix factorization promises to discover the parts that constitute the input vectors *without* the user specifying *what* these parts are or what to look for! The parts discovered can be understood as the underlying structure or constituents of the input objects. The various modifications to the original non-negative matrix factorization algorithm have added sparsity control parameters. These in effect allow the user to constrain the algorithm to certain types of bases e.g. in NMFSC [14] the sparsity parameters control the size and resolution of the bases discovered when the number of bases is a given. The synthetic example has somewhat motivated the applicability of the method to functional type data. The sparsity parameters have proven to be of critical importance in achieving any reasonable bases set .

In the next chapter we experiment on real spectra with some of the above algorithms. Our main focus will be on the application of the different sparsity factors and determining their results on our real spectral dataset. We analyze the behavior of the algorithm at different parameter settings to get a clearer interpretation of the basis and coefficient matrices.

University of Cape Town

Where we experiment and analyze NMF on real spectra and show its limitations

## Chapter 3

### 3. Non negative matrix analysis

#### 3.1 Non-Negative Matrix Factorization on real spectra

The aim of the experiments in this section is to determine whether the NMF algorithm can factorize an input database of real spectra into an interpretable bases set. As motivated in section 2.3.2 NMF does seem to discover parts of synthetic spectrum, see figure 2.3.3 when given input like in figure 2.3.2. In the first experiment we select a random set of 10 spectra from each class, as described in section 2.2 and form an input matrix  $V$ . The maximum rank of the NMF decomposition value ( $r$ ) is given by

$$r < \frac{(n \times m)}{(n + m)},$$

in this case  $r < (1024 \times 10) / (1024 + 10) < 9.9$ . We normalize the input matrix  $V$  by the L2 norm. The first target class is class 1 and its non target classes are 15, 16, 17, 20, 21, 25, 31. Figure 3.1 shows each classes' 10 spectra thus we have 80 input spectra in the  $V$  matrix. Figure 3.2 illustrates the NMF input matrix  $V$  for these classes and target class 1. The bases found by NMF for  $r = 6$  are displayed in figure 3.3 at a basis sparsity factor ( $sW$ ) of 75%, with no sparsity set for the coefficient matrix ( $sH$ ). It is not clear how one should interpret these highly discrete bases. Figure 3.4 illustrates another bases set discovered by NMF on the same input matrix  $V$  when  $sW=0.55$  and  $sH=0.3$ <sup>4</sup>

<sup>4</sup> All the experiments in this section used the NMFSC algorithm which we terminated when the objective function started stabilizing.

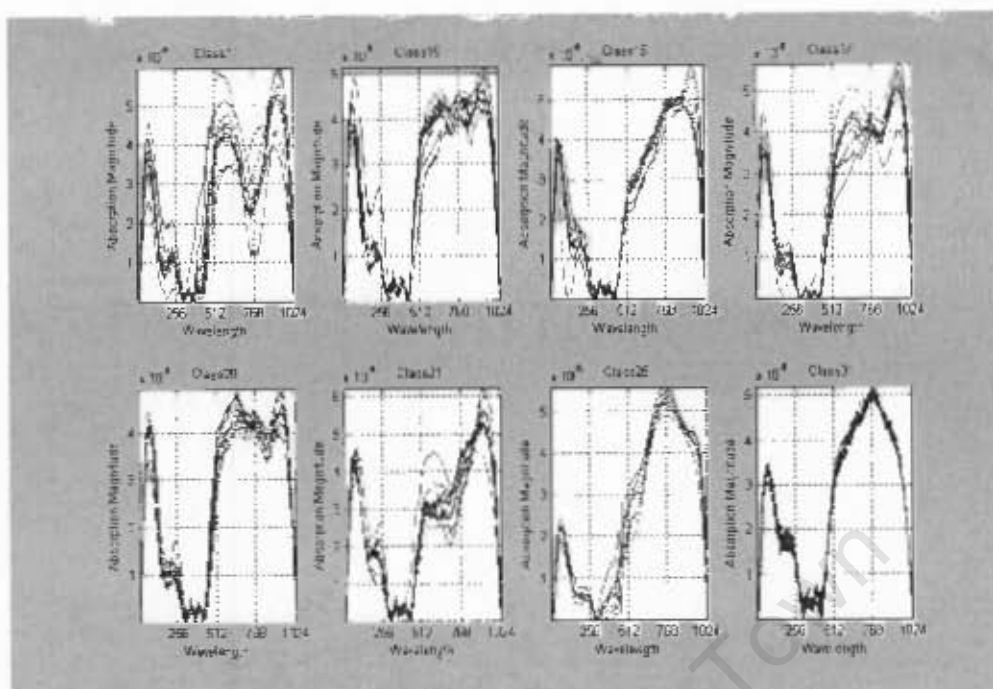


Figure 3.1 Each of the 10 spectra from each class

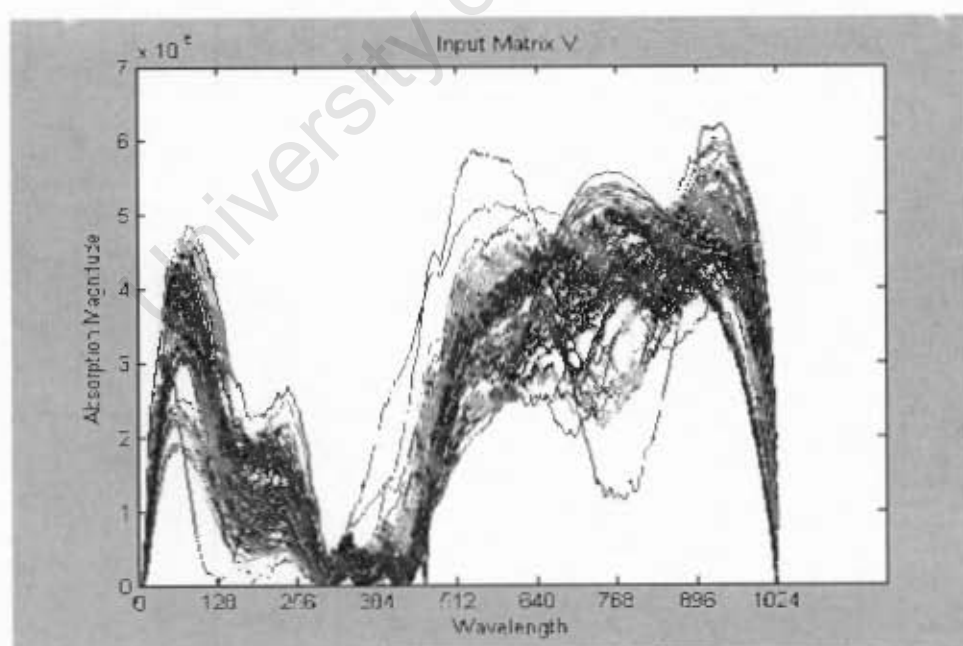
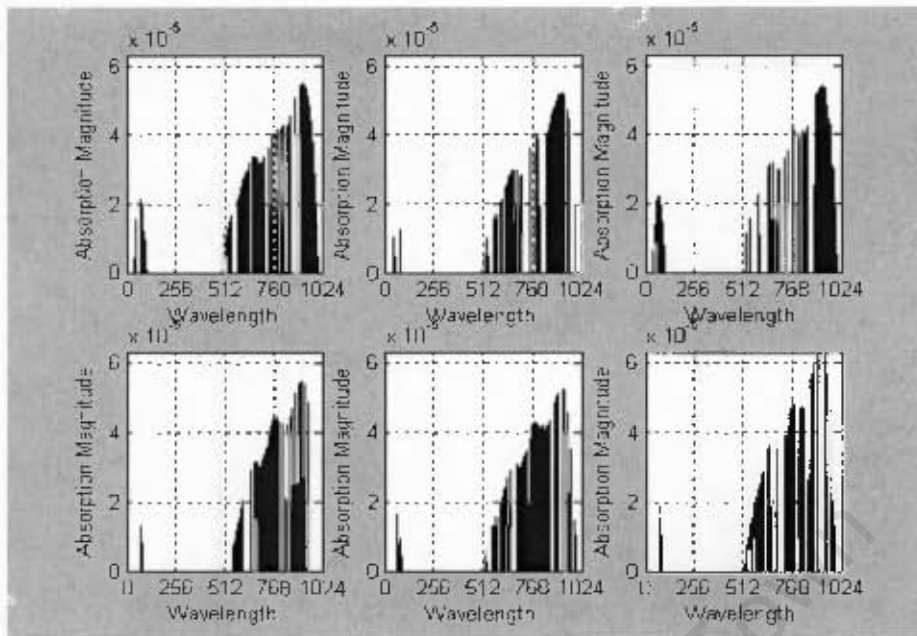
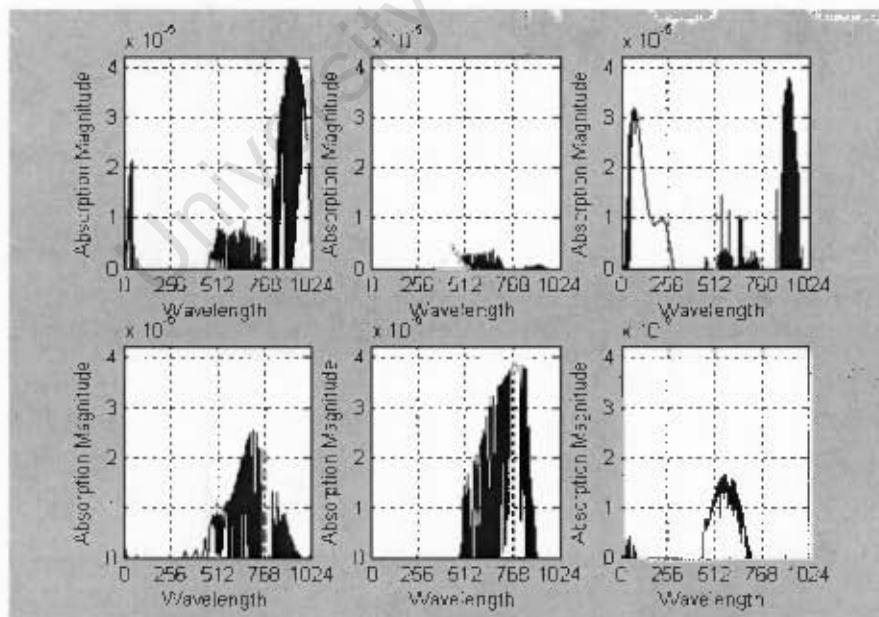


Figure 3.2 TC 1 and NTC 15,16,17,20,21,25,31 as input V



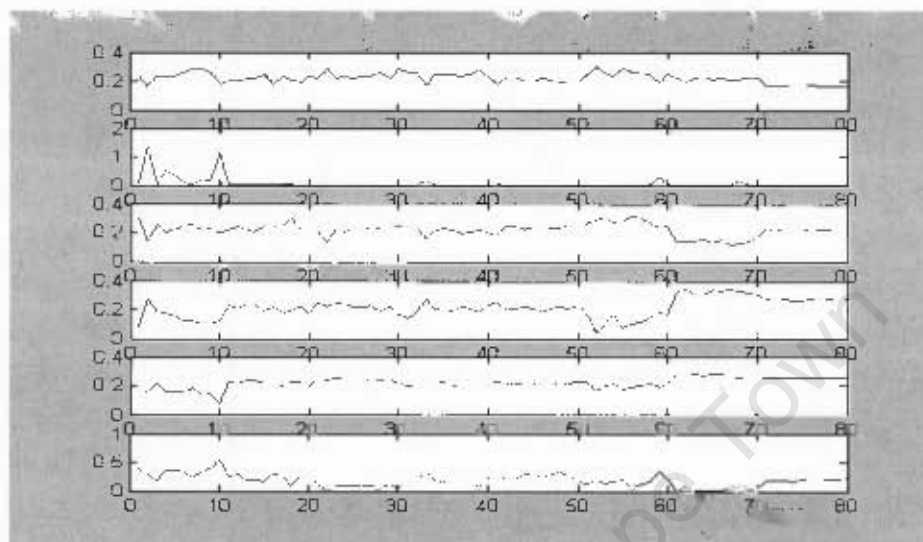
**Figure 3.3** Bases discovered by NMFSC for  $r=6$  at  $sW=0.75$   $sH=0$ ;

When the sparsity of the basis matrix ( $sW$ ) is decreased, the algorithm tends to factorize the input matrix into bases that occupy certain sharp subregions of the full spectrum measurement range. Some of these bases seem to overlap and considering the additive nature of the factorization it is not exactly clear what the individual discovered bases really mean but some sort of underlying structure is beginning to become visible.



**Figure 3.4** Basis discovered by NMFSC for  $r=6$  at  $sW=0.55$   $sH=0$ ;

The coefficient matrix of the bases in figure 3.4 is shown in figure 3.5. It reveals that the discovered bases occur in most of the input spectra except for the second basis which does not seem to occur in a number of input spectra. The interpretation of this basis is not simple as other bases found also occupy the same wavelength range. The fact that most of the bases occur in almost all the input spectra means the sparsity settings are not optimal.



**Figure 3.5** Coefficient matrix for basis discovered in figure 3.4

When the basis sparsity is furthermore decreased as in figure 3.6 spectra segments are found. The bases vary from sharp discrete segments to respectable short-segmented ones. The coefficient matrix, figure 3.7, somewhat better explains how to interpret figure 3.6. The coefficients in figure 3.7 signify the presence or abundances of the basis thus the bottom middle basis in figure 3.6 occurs in the input spectra from *some* of class 26's spectra, spectra 60 -70 in the input matrix and *constantly* in class 31 (spectra 70-80 in the input V).

This basis occurs with highest abundance in class 26 as indicated by the higher values in the 5<sup>th</sup> row of figure 3.7. It does not occur anywhere else in the input matrix. The first (left hand corner of figure 3.6), third and last basis look like full spectra. The coefficient matrix does not illustrate their occurrence in classes 26 and 31. One would at least expect the peak between 0 - 256 wavelengths to be found in these spectra as it occurs in the class input figures 3.1. We increased the number of basis to be discovered in this example but segment (0 - 250) of the spectrum was not identified as a unique basis. This introduces some uncertainty in the meaning of NMF results.

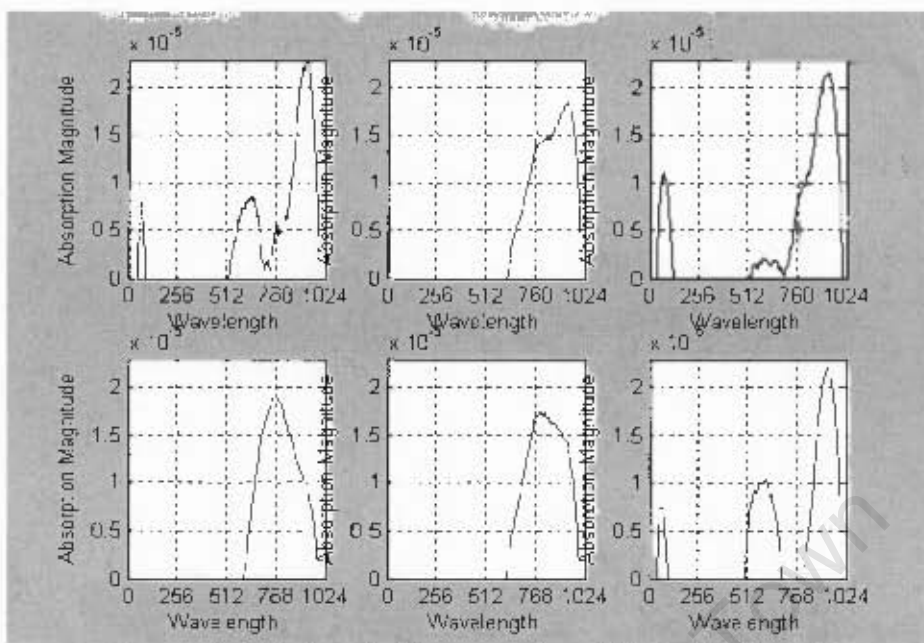


Figure 3.6 Six basis discovered at  $sW=0.45$   $sH=0.75$

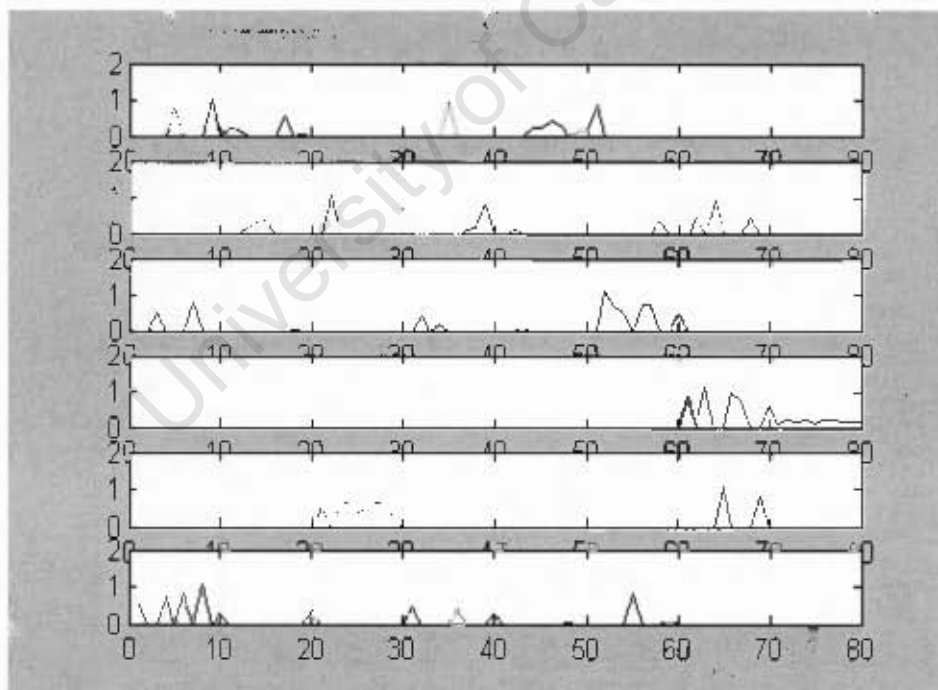


Figure 3.7 Coefficient Matrix for figure 3.6's basis

The above experiments have highlighted a number of questions that need to be addressed in order to understand and better interpret **NMF** results.

- When does one know that the discovered basis set is optimal?
- What does it mean if a potential (intuitive) part is not identified as a basis?
- Why do some basis appear holistic, for example basis 1, 3 and 6 in figure 3.7 and not as unique segments?
- What input regularities does **NMF** actually exploit in data?

We address the above questions by experimenting with the algorithm in a more intuitive and familiar domain, that of images. This we believe is easier to interpret and critical insights can be gleaned from such explorations.

### 3.2 The limitations of NMF

To gain better understanding into how **NMF** discovers the parts it does we explore the algorithm with different input settings with objects from the same domain. We make use of another algorithm (Local NMF) provided in the **NMF** package by [14] and introduced in [21] for result comparison.

#### 3.2.1 What NMF cannot do

- Non-Negative Matrix Factorization cannot decompose one object's multiple occurrences in the input. When we are given a number of copies of the same object as input **NMF** does not decompose these into constituent bases. The bases decomposition achieved by **NMF** algorithms for such an input is holistic since the same parts are present at the same positions in all the input objects.

This is shown below in figure 3.8 (input) and LNMF and NMFSC results in figure 3.9 for a large number of iterations are similar.

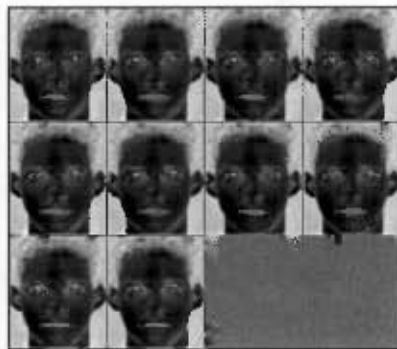


Figure 3.8 One individual's same ten images as input  $V$

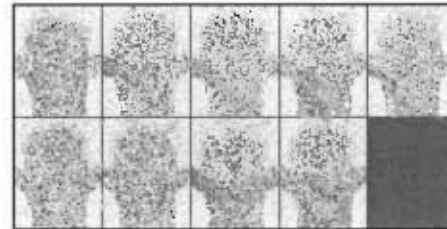


Figure 3.9 LNMF result at  $r=9$  or less after 1500 iterations

- NMF could possibly be a method for factorizing multiples of one object's two different images. NMF is not able to find convincing parts when given essentially similar objects as in figure 3.10 but note that as soon as we start to have a slight variation in the input images (figure 3.10) then some forms of parts are evident as basis, figure 3.11.

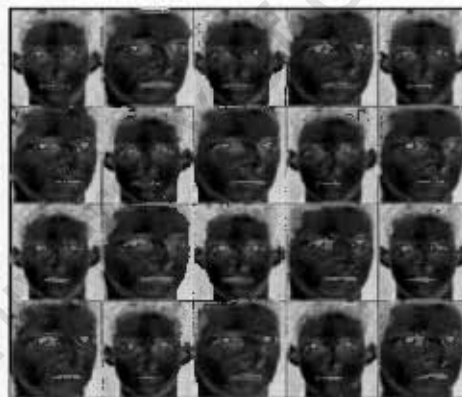
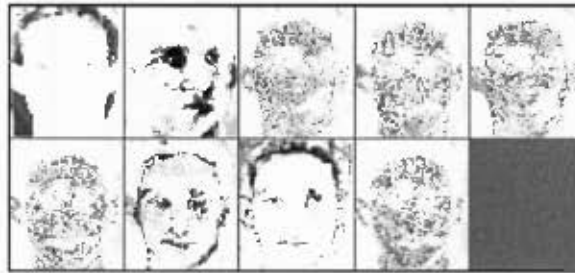


Figure 3.10 One individual's two different images



**Figure 3.11** LNMF result at  $r=9$  after 1500 iterations

These are the parts that differ significantly between the input objects. This then raises the question - under what conditions will NMF provide us with the ideal basis, that is eyes, ears and mouths etc as separate and possibly unique bases?.

### 3.3 Ideal basis & Limitations of NMF

In the literature non-negative matrix factorization has been presented as a method that discovers object parts. It would seem the interpretability of the parts has not been a major concern for researchers but rather the sparsity and classification results that are obtainable after the factorization. Indeed the majority of subsequent papers (14,21) to the original NMF[19] all focused on the sparsity of the bases to be discovered via changing the factorization constrains. In light of the above results of NMF analysis (sections 3.1 and 3.2) the meaning and achievability of the ideal NMF basis is questionable!

A number of recent papers have started to highlight similar concerns and have in fact questioned the interpretation of the basis discovered [4,7]. [4] gives an example of NMF applied to a database of eyes images, from this paper it is clear that the interpretation of NMF can be very difficult even for a simple object like this. In [7] the conditions for the ideal performance of NMF is presented. The basic outcome is that the input database has to have a specific pattern for NMF to produce clearly interpretable and optimum parts

### 3.4 Extension to interpretation of NMF

In this section we seek to extend on the interpretation of NMF factorization ability as hinted in [4] and [7]. We create a database with characteristics similar to the swimmer database in [7], which we call the sticks database in figure 3.12 below. This dataset will allow us to explore why and perhaps what the NMF algorithms discovers to be parts of an input set. This is a hypothetical input set made up of 16 (4 rows x 4 columns) objects in different poses. There are actually two sticks that vary their positions from the initial two sides of a triangle to the fully open triangle position on the last object. This input like the swimmer database in [7] consists of all the combinations of how these two sticks can be oriented between images 1 and 16. Note that there is a non position varying part (at the bottom of each object) in the database.

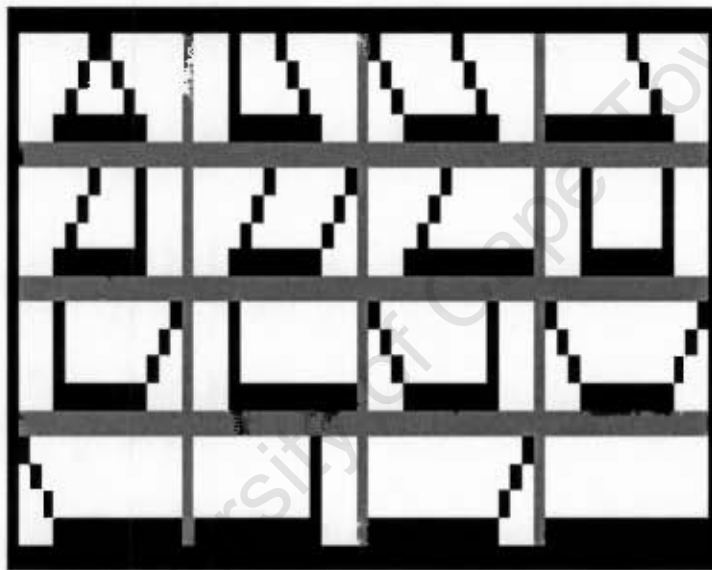


Figure 3.12 The sticks database

Often one cannot look through a typical input database to find the parts that can be described as making-up the data. We thus seek an automatic method of finding the number of parts that constitute all or most of the input. When the standard NMF algorithm is applied one must empirically guess a reasonable value of  $r$  to factorize the input to (see section 2.3.1). If we arbitrarily choose  $r = 2, 5, 8$  the NMF algorithm obtains figures 3.13 3.14 and 3.15 below respectively.



Figure 3.13 NMF  $r=2$



Figure 3.14 NMF  $r=5$

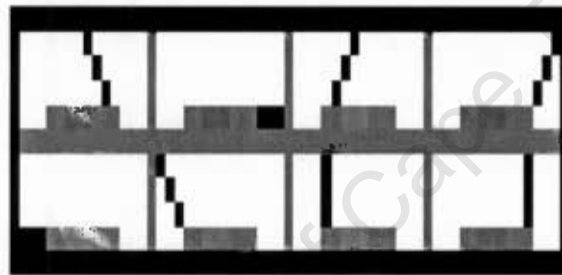


Figure 3.15 NMF  $r=8$  Best Decomposition

Note in figure 3.15, NMF discovers 8 bases/parts that are really 2 parts at different positions. The bottom of the object is common in all bases. Figure 3.15 shows us that NMF does not really discover the fundamental parts of a database (Here actually 2) but the parts that show the most variation (that are the most different amongst the objects) in the database. This then explains why NMF cannot factorize one or multiples of an object as posed in section 3.2. This explains why [7] refers to the fact that better results are possible with a larger database. We should add that the database should consist of as many slightly differently posed objects as possible for any reasonable bases to be found!

### 3.5 Approximating the best $r$

In the above type of problem setting it is possible to eliminate the guessing of the best rank ( $r$ ) for the factorization. One can compare each object to all the other objects and note the differences. Then count the differences that have been noted the most from each object, as compared to the other objects. The pseudocode of the above argument is presented below:

Given data  $V = [n \times m]$  where  $n$  is the number of pixels in each object and  $m$  is the number of objects, 16 in this case.

1. Compare each object in the database with every other object.
2. Note the *differences*<sup>6</sup> for each object.
3. Extract only the differences that occur the *most* for each object. Call these *max\_occur*.
4. compare each object's *max\_occur* with every other object's *max\_occur*.
  - 4.1 Store only *max\_occur* s that are unique.
  - 4.2 Count the number of *max\_occur*s obtained.

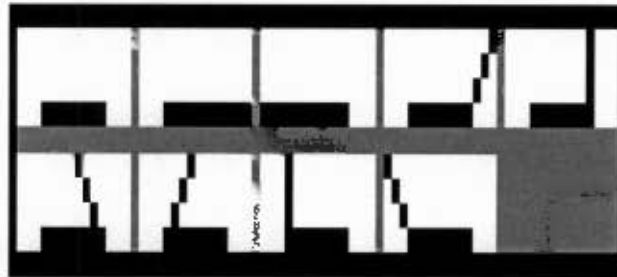
Figure 3.16 below shows the results discovered by this algorithm.



Figure 3.16 Pseudo code results for **different** parts

<sup>6</sup> We can look at the *differences* or the number of *equal* 'parts' in the objects. See Fig.3.16 & 3.17.

Note that the bottom of the triangle does not appear in figure 3.16 due to step 2 (*differences*) of the algorithm. The above result shows the parts that differ the most. This is why we argue that the presentation of NMF as a technique for discovering parts of objects is somewhat misleading.

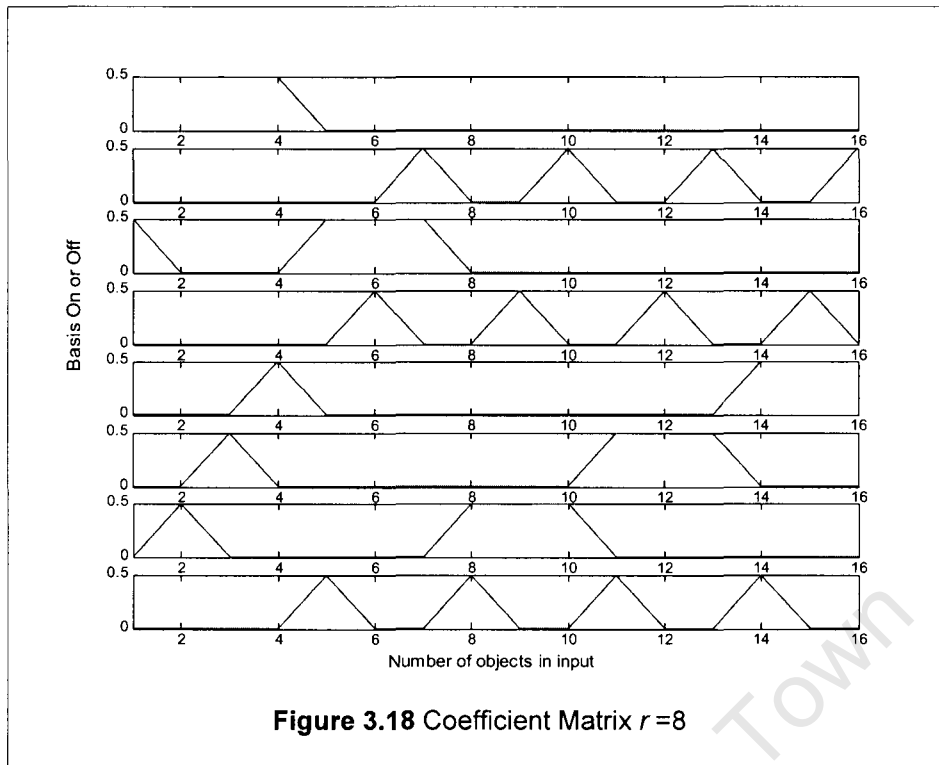


**Figure 3.17** Pseudo code for **equal** parts

Figure 3.17 shows the results obtained by changing step 2 in the pseudocode to the number of *equal* aspects. Note that the common part from the input is discovered as a separate basis as compared to figure 3.16's results. This is a more ideal result as compared to figure 3.16 where we would never know that there is a constant common feature in all the objects in the database.

### 3.6 Interpretation of the Coefficient Matrix

The synthetic problem modeled above shows well how one can interpret the coefficient matrix. This simple setting shows when or where in the input matrix a particular part observed in the basis matrix occurs. The first row in figure 3.18 models the first basis function discovered in fig 3.15 NMF's best decomposition, subsequent rows model the corresponding bases in figure 3.15. As it can be seen the first basis/part found by NMF occurs in all the first four input objects (figure 3.12) of the sticks database in the same position. This is the right arm at that particular position.



The seventh row of figure 3.18 shows where the 7<sup>th</sup> basis occurs in the same position in the sticks database; input objects 2,8,9,10. This is the left arm in a vertical position. This part in this particular position does not occur anywhere else in the sticks input. Note that in this synthetic problem a basis is either present or not, that is why we do not have fractions in the coefficient matrix. It is either on or off.

### 3.7 Relation to spectral data

The above argument somewhat explains why in the motivation example (see section 2.3.2) NMF tentatively decomposed the input synthetic spectra into the correct basis. *This was an example of a functional form of the sticks database!* As explained in section 3.4; there are essentially six parts that are combined in some fashion, some composite input spectra have certain bases some do not, to produce the input. Thus by applying the above proposed algorithm (see section 3.5) one would also obtain the required basis<sup>6</sup>. This analysis leads us

<sup>6</sup> Note: The algorithm would have to be modified slightly to accommodate functional data.

to conclude that if spectra from different classes have common parts but these parts occur in certain arrangements NMF might discover them as bases. This means if most spectral classes have the *same* part in the *same location* and different parts which have to be similar in some spectra, occur in the same range of the profile, NMF could discover them. Then the common parts would be identified as bases since they occur in the same location and the other parts will form the other bases since some of them will be common to other spectra.

The observation that NMF factorization can result in holistic spectrum basis is also explained by what the algorithm searches for in the input. In figure 3.6 the first, third and sixth basis are almost holistic, this means in each of these bases the peak spectrum segments (0 -256 and the 512-1024 segments in those forms) always occur together, NMF cannot separate them to form unique basis out of them. This is similar to the bottom, non varying part in the sticks dataset in figure 3.12 as explained in sections 3.3 & 3.4.

As a further step if one could discover or explain the relationships between the parts (the fact that two of the parts in figure 3.12 have moved) we could reveal the fact that there are only three fundamental parts in the sticks dataset.

### 3.8 Chapter 3 Discussion

This chapter has explored the applicability of non negative matrix factorization (NMF) in the factorization of real spectral data into constituent parts and we have subsequently noted fundamental limitations of NMF paradigm in general. Real object parts through NMF seem to be only attainable if the input data is arranged in a specific pattern. The input objects firstly have to be generally similar but will also have to have certain parts occurring at the same locations in a number of objects and have some other parts that occur in other objects not occur in the first set of objects. Such a permutation of object parts is unlikely to occur in real spectral datasets. A few domains such as music often exhibit such behavior where certain musical notes are played in a certain segment and are not present in others [37].

Whereas chapter 3 focused on the experimentation with the sparsity factor of non negative matrix factorization algorithms in the next chapter we formulate another approach to discovering a sparse expression of spectra. This approach is based on the few aspects of spectra that seem to be intuitively appealing or attractive to the human eye. We use this

information to devise a new sparse description of spectra. Unlike NMF the following chapters' approaches to attaining sparsity do not analyze the spectra as one input but as individual spectrum.

University of Cape Town

*Where we hypothesize that simple, intuitive, sparse empirical features of spectrum can be sufficient to capture the physics of sensory representations of spectra*

## Chapter 4

### 4. Proposed Representations

#### 4.1 Motivation for Alternative representation

In solving or explaining a problem humans can normally consider different perspectives, those that include details and those that don't. If one particular view-point can be further simplified then usually that new perspective is preferred. The new perspective has a strict constraint: it still has to capture the core/essence of the problem at hand. By identifying what seems to be the bare essentials of a problem one would like to wrap these up in a more simple and intuitive package - "Saying more with less complexity".

Humans can quickly identify certain aspects or features that can be deemed to be discriminatory just by looking at objects (e.g. Spectra). The general profiles of a number of spectra might be similar but there are at least certain features of the spectra that are different thus leading to different classes of spectra. One would thus like to capture and characterize these aspects as possible sufficient *descriptors* of whole spectra.

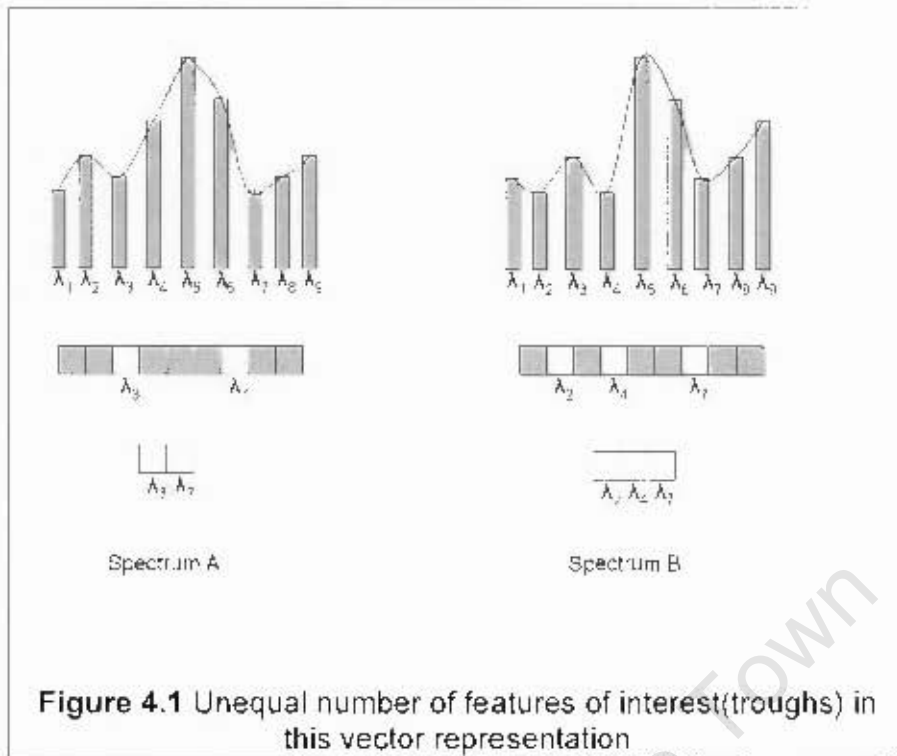
In [30] Paclik et al. have proposed *describing* a particular spectrum by its similarity (dissimilarity) distances between it and every other spectrum in the dataset. This description of a spectrum captures well what seems to be of interest when one needs to cluster or characterize objects but this only occurs if we treat spectra as points in some high dimensional space. Another relatively simple sparse representation (discussed in section 2.1.2) of spectra is proposed in [1]. Here a particular feature (peaks) was found to be visually prominent in spectra. This feature's location, height and width form the basis of the compressed representation of the spectrum. But unlike in [1] we do not try to discover the possible *causes* of the profile but we capture what is *visually* perceptible and form a sparse

representation from it. The main purpose of exploring these representations then is to determine if such sparse features will be sufficient to capture the basic *structure* of the spectrum profiles. This was argued (see section 1.1.1) to be important if we want to stay true to the physics of the problem.

This chapter is arranged as follows: in the next section we explain how we capture the features we deem to be of intuitive interest in spectra. We formulate two compact descriptions of spectrum based on these features. To convey the new formulations clearer we graphically show how they would appear in function form. We are not, per se, interested in the visualization of the new descriptions but in their ability to capture the whole spectrum profile via a few features whilst being able to discriminate different classes of spectra as in the original representations.

## 4.2 Capturing the general profile

Spectra in the same class, let alone in different classes do not necessarily have the same number of features of interest (FOI) nor do these necessarily occur at the same exact *location* in the profile. Figure 4.1 shows an example where we consider the troughs as our features of interest. If a new representation using only troughs is required we have a problem, the number of FOI is not equal! We cannot deal with the resultant vector description in the normal way for example using Euclidean distances since the representations are not in a common vector space.



Little research in machine learning is concerned with unequal sized vectors – one measure that can deal with unequal sized vectors is the Earth movers distance (EMD) commonly use in imaging [33]. When one needs to compare or document two or more images in some order it is often easier to compare their color histograms [33]. EMD has been shown to work well in such domains. The measure's basic hypothesis is to calculate the minimum amount of work required to change one image's color spectrum (often in histogram form) into the another even if the number of bins is not equal.

We do not use this measure in this thesis. If we are to use the normal vector representation (where Euclidean calculations are valid) for each spectrum, we have a number of options for this problem :

- Choose a vector length that is just more than all the classes' FOI and add zeros at the end to equate all the spectra vectors.

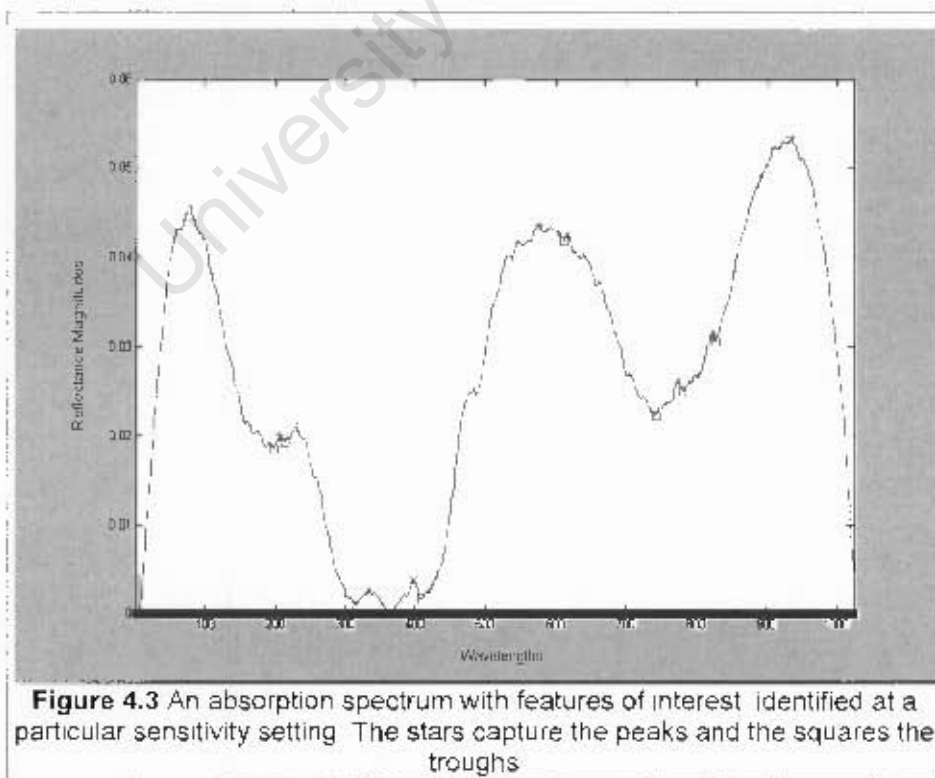
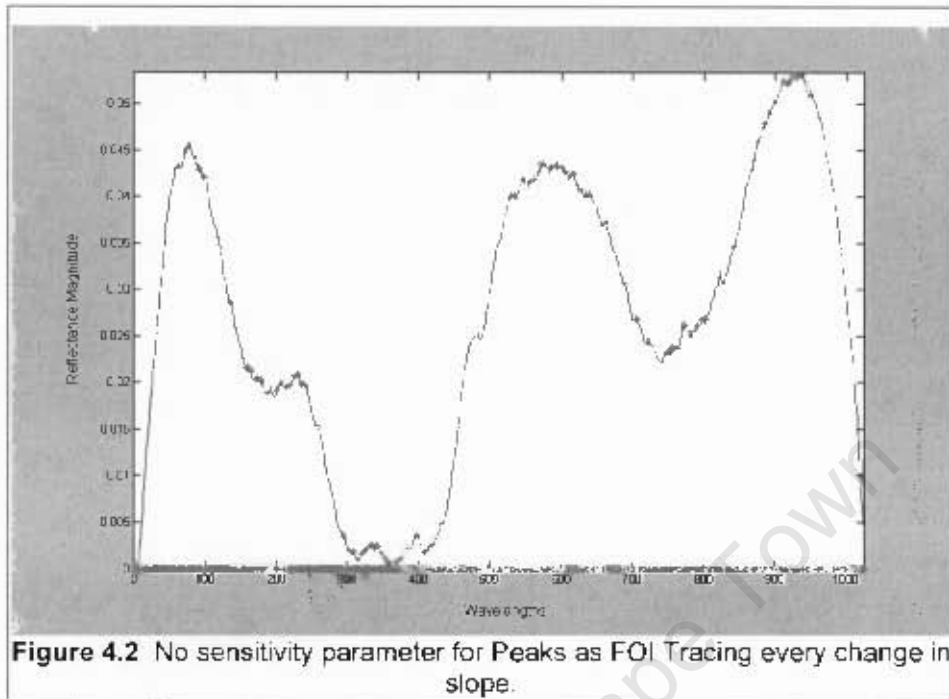
- Retain the original vector length by :
  - Listing all the FOI of a spectrum in the beginning of the vector and add zeros until the original given vector length.
  - Listing all the FOI at the positions they were found and inserting zeros in between

But if we are to emphasize the physics of spectrum it is not enough just to identify the FOI but to also capture what happens between them! All the above options neglect to model the transition between the features of interest. As mentioned in section 3.8 it important to discover the parts that explain a set of objects but their configurations has a fundamental bearing on each object's description or structure. In section 4.2.2 and 4.2.3 we explore two different ways of modeling the transitions. But firstly we discuss what we consider salient features of spectra.

#### 4.2.1 Features of Interest

We identify *peaks* and *troughs* as important visual discriminatory features for our proposed representations of spectra. We use the change in profile slope to identify features as peaks or troughs. Figure 4.2 illustrates the case where peaks are identified as features of interest. Note how every change in the sign of the slope defines a feature of interest (in this case a peak). We also incorporate a sensitivity parameter to define how significant the change has to be before a potential feature is considered interesting. Figure 4.3 illustrates a particular set of features that were found at a certain sensitivity setting.

The sensitivity parameter is a particular constant fraction (lets say  $q$ ) of each spectrum's maximum value. In order to capture more prominent peaks rather than every change in the sign of the slope as a peak we require only those peaks that are a particular magnitude ( $q$  in this case) more than the previous trough. If this magnitude is less than  $q$  then the peak is not considered to be significant. This way the smaller the threshold fraction the more profile 'noise' we capture as in figure 4.2.



The higher the sensitivity parameter the the more profile noise is traced and the smaller it is, the more coarse an approximation of the profile we should be able to regenerate. In this chapter we present two slightly different approaches to using features thus found to describe whole spectrum profiles. The differences in the proposed representations is the modeling of the transitions between these features of interest. Figure 4.4 illustrates the process we used to formulate the new spectrum representations using our features of interest.

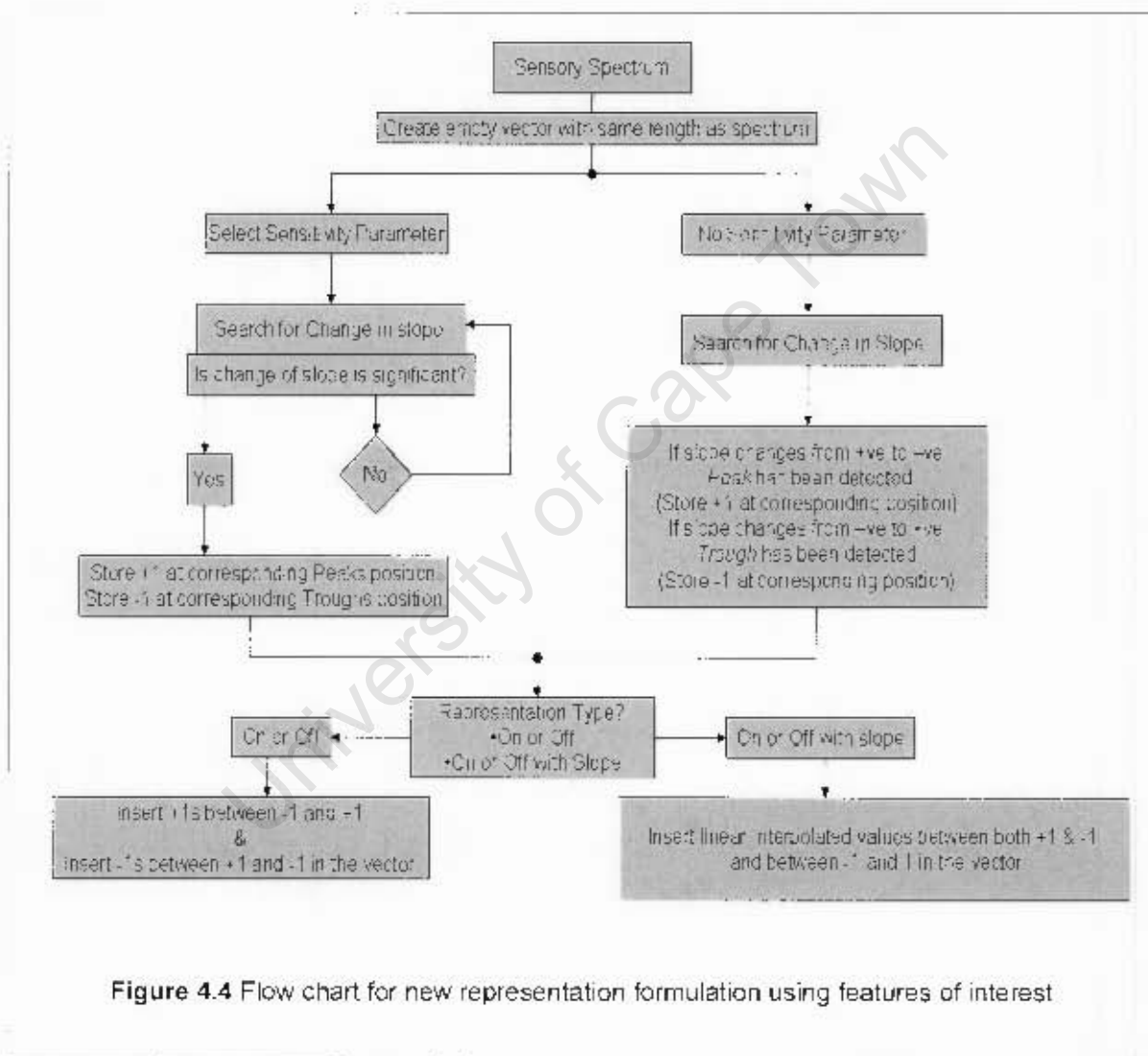


Figure 4.4 Flow chart for new representation formulation using features of interest

#### 4.2.2 On or Off representation-slope 1

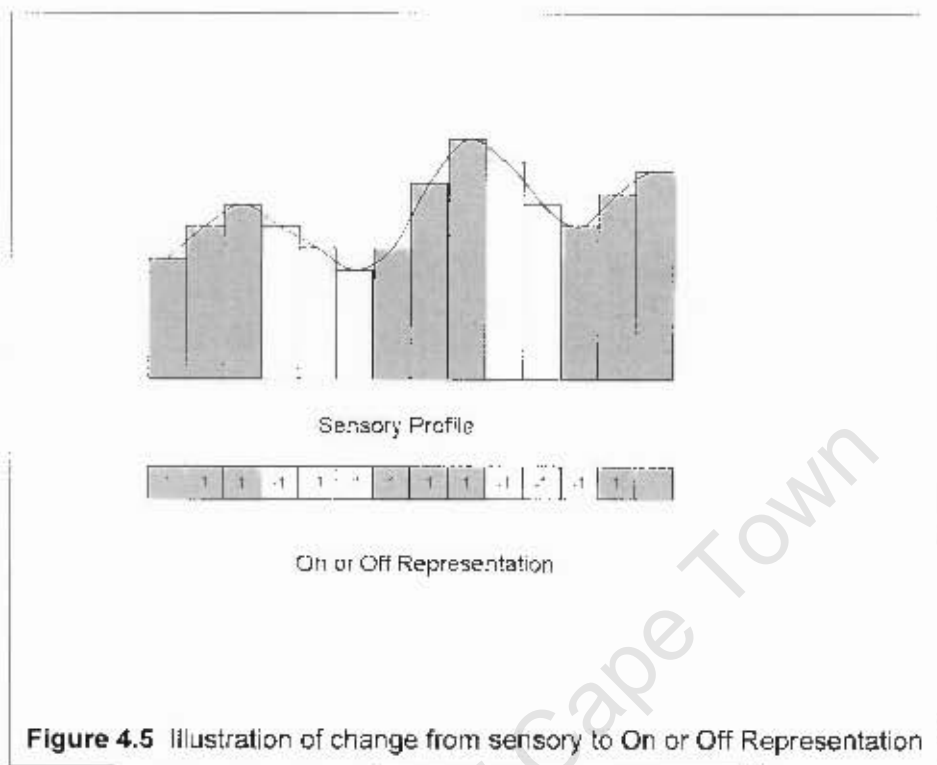
At a low level of abstraction humans can be said to look primarily only at the *general* variations of the spectrum profile and where these changes occur i.e. is the profile rising or descending and where do this occur? The magnitudes of the features are only of secondary concern if and only if the overall general profiles between the spectra are not different. A further consideration might be to focus on the minor changes in the profile if primary cues do not seem to reveal obvious differences in objects. Having identified the peaks and troughs as our features of interest for the new description we neglect<sup>7</sup> the magnitudes of the features and only consider the fact that the spectrum is either increasing towards a peak and decreasing towards a trough. We use an "on (+1) or off (-1)" analogy to capture the positive and negative gradients of the spectrum's profile. This type of representation eliminates the problem of unequal sized vectors expressed in the beginning of section 4.2 This then leads to the following sparse description of any spectrum profile  $S(x)$ :

$$S(x) = \begin{cases} +1 & \text{if } \nabla \text{ is increasing} \\ -1 & \text{if } \nabla \text{ is decreasing} \end{cases}$$

where  $\nabla$  is the slope

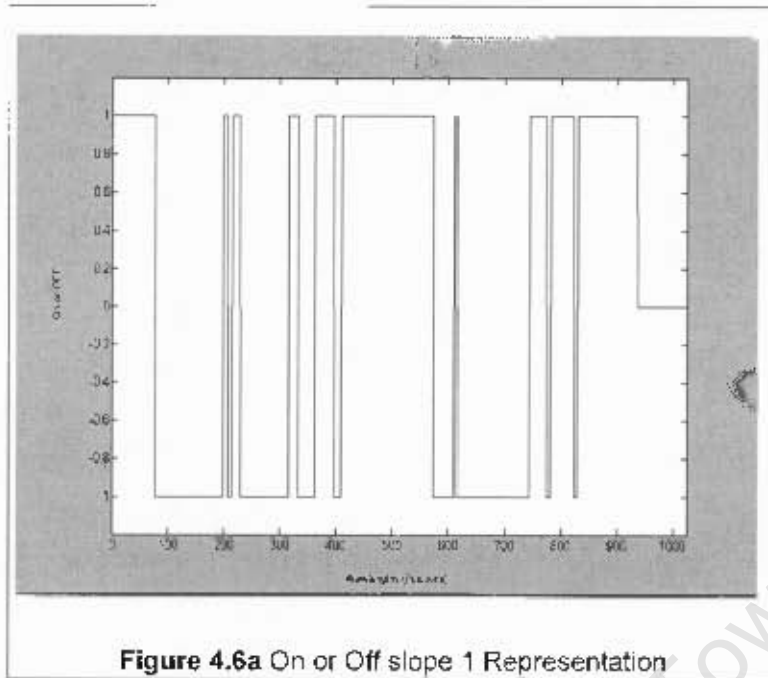
The slope changes are captured by the change in signs between the 1s in the function vector. When the gradient of 1 sign changes from positive to negative then we know the slope is decreasing and vice versa. If we plot this function we will have a positive constant value of 1 to indicate the positive slope and a constant value of -1 to indicate where the slope is decreasing in the spectrum. Figure 4.5 illustrates the general concept on how we change from the sensory to the On or Off vector representation. Note that in figure 4.5 there are actually four features of interest, from a fourteen element long signal, that *anchor/structure* the new representation, this means we strictly use  $(4/14) \times 100$  (=29%) of the original features!

<sup>7</sup>Within one class reflectance or absorption magnitudes might be different, the magnitudes only capture the abundance or percentage of the elements/substances in the object.



**Figure 4.5** Illustration of change from sensory to On or Off Representation

The regions of rapid slope variations in the reflectance representation are captured by the close vertical lines in the On or Off representation as shown in figure 4.6a. The sensitivity parameter will, as discussed, determine how significant we regard these variations. Figure 4.6a illustrates the graphical form of this type of representation when no sensitivity parameter is incorporated. This figure is the result of changing figure 4.2's representation (with troughs included as FOI) into an On or Off representation.



**Figure 4.6a** On or Off slope 1 Representation

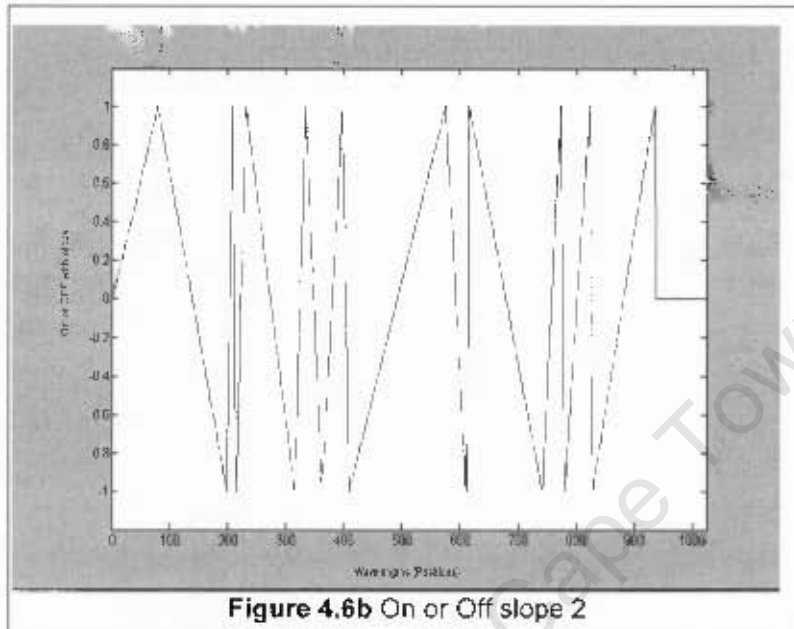
#### 4.2.3 On or Off slope2 representation

In this representation we also consider the peaks and troughs as our features of interest. The main difference is that we explicitly express the slope and neglect the magnitudes of the different features in the new spectrum description. The sparse formulation for every spectrum is expressed by

$$S(x) = \begin{cases} y_t + ((y_p - y_t) / (x_p - x_t)) x, & \text{for positive slope} \\ y_p + ((y_t - y_p) / (x_t - x_p)) x, & \text{for negative slope} \end{cases}$$

where where  $x_i$  indicates a particular point along the wavelength,  $(x_p - x_t)$  and  $(x_t - x_p)$  are the distances between the peak and trough in the current spectrum segment.  $y_t$  and  $y_p$  are the values of the trough and peak respectively. Note that each  $y_p$  is represented by a +1 and each  $y_t$  by a -1. The transition between the features of interest is modeled by a linear

interpolation between +1 and -1 or -1 and +1. Figure 4.6b shows the plot of this description of spectrum when the sensitivity parameter is not used. As mentioned before these figures are only included for general formulation clarity. In both the above descriptions the choice of using +1 or -1 is arbitrary, we could have used +1 and 0 respectively. The advantage of using the former will be evident in chapter 5.



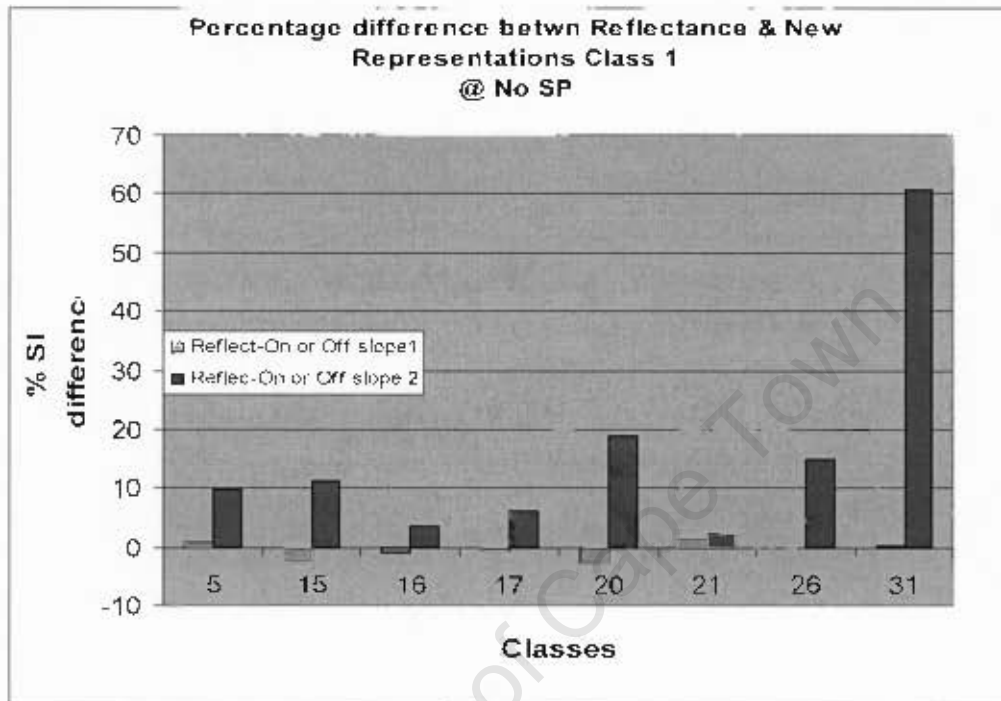
### 4.3 Experimenting with sparse spectrum descriptions

In order to determine how well these new sparse descriptions of spectrum are able to capture the information implicit in the original sensory representation we compared their ability to separate classes via the separability index. Similar to section 2.2 each class comparison is split into five "training" sets and the average separability index over the five splits is then calculated<sup>8</sup>. Figures 4.7a-c show the separability percentage difference between using the 'Reflectance' and On or Off representations (without the sensitivity parameter)<sup>9</sup>. In figure 4.7a class 1 (target class) vs 5 (non target class, NTC) for example, the percentage separability

<sup>8</sup> See Appendix C&D for the effects of changing from the Absorption to the two On or Off representations when no sensitivity parameter is used.

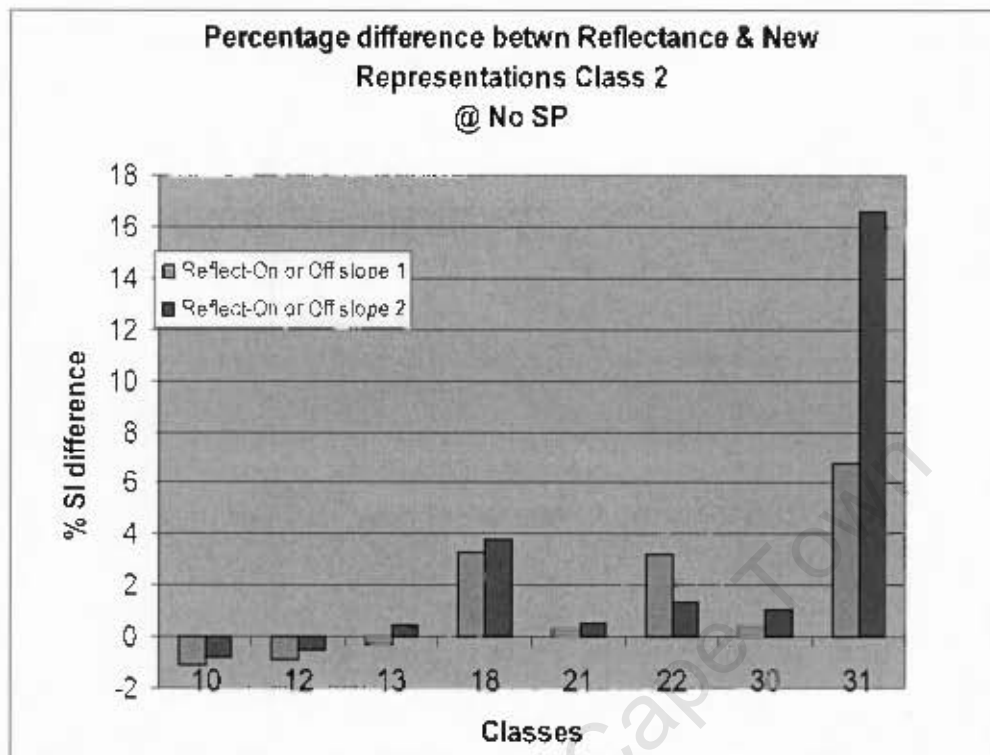
<sup>9</sup> See Appendix E for the percentage separability differences between using the On or Off and reflectance representations at different sensitivity settings.

difference between the Reflectance and On or Off slope 1 representations is 0.8% and between the Reflectance and the On or off slope 2 is 9.76%. In this case this means it is better to use the Reflectance representation. The percentage separability differences in figures 4.7a-c are generally low, significantly less than 6% except in a few classes considering the number of features used to capture the spectrum structure.

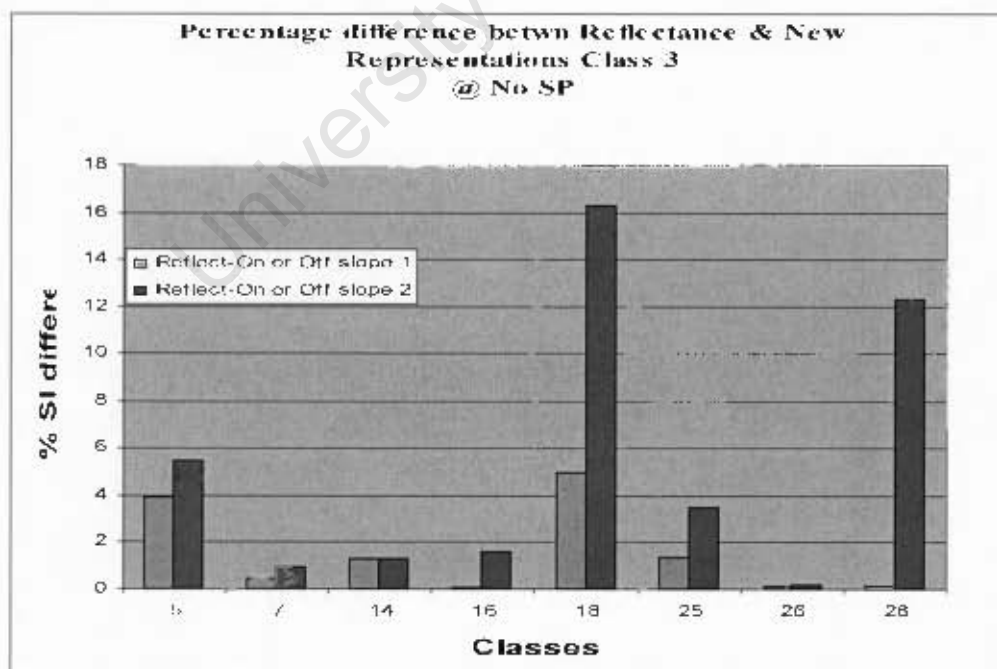


**Figure 4.7a** Class 1 vs Non target classes

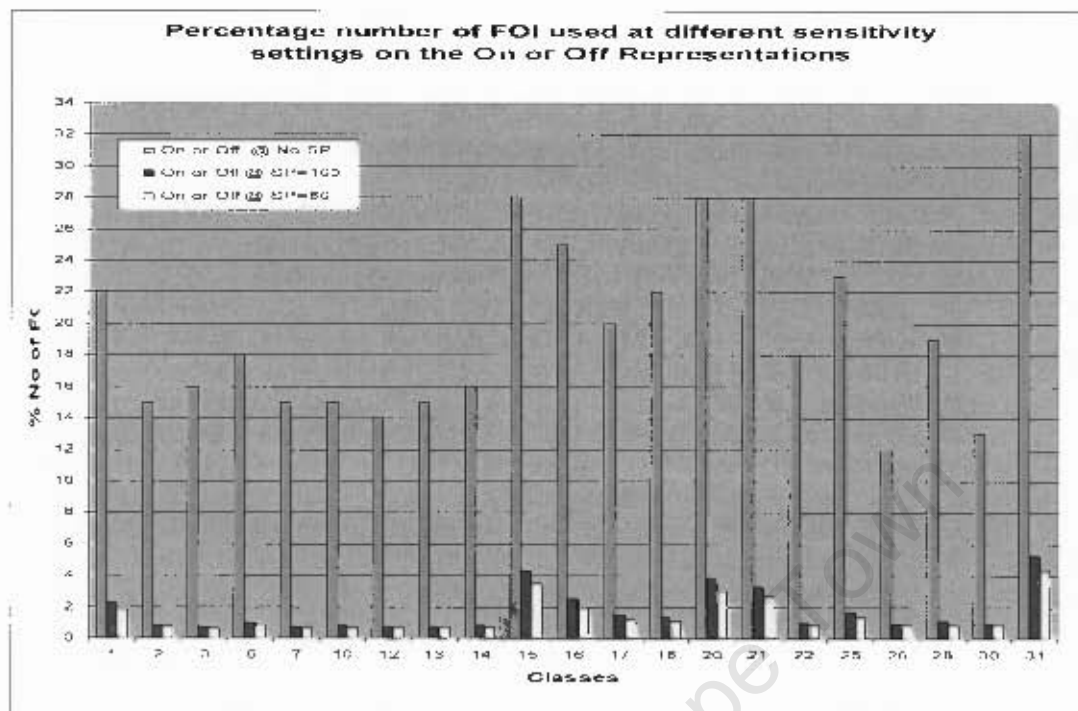
These results indicate that peaks and trough do capture discriminatory information of spectrum profiles. Figure 4.8 shows the average percentage of features used (as explained in section 4.2.2 but with a 1024 element long signal) in each class for all representations at different sensitivity parameter settings.



**Figure 4.7b** Class 2 vs Non Target Classes



**Figure 4.7c** Class 3 vs Non Target Classes



**Figure 4.8** Percentage number of FOI used in the On or Off representations at different sensitivity parameter values

As can be seen in figure 4.8 the representations without the sensitivity parameter (No SP) identified the most number of features of interest. This is because in this representation we are interested in every change of slope sign that occurs in the spectrum. Figure 4.8 thus reveals which classes have the most 'noise' or fluctuations in their profiles: classes 31, 15, 20 & 21 etc. As expected there are fewer features of interest identified as the sensitivity parameter decreases.

## Chapter 4 Discussion

We have to some extent confirmed our hypothesis that very simple sparse intuitive methods can achieve comparable performances to more complex (detailed-sensory) representations. This leads one to conclude that perhaps one can often find simple low level descriptions of objects that are normally 'clouded' in the more complex descriptions. All that is required is to identify the features of interest and re-represent our objects with these. The identification of

features of interest using the sensitivity parameter can numerically reveal interesting characteristics of spectrum profiles such as how much variation there is in the profile. The results in table 2.2 and Appendix B,C & D show that just by using peaks and troughs with a certain modeling of transitions between these, we can achieve comparably similar separability results between classes as with full sensory representations. Some classes are better represented by slope 1 and others by slope 2 representations. We do not currently have an explanation for this.

We have achieved sparsity in the sense that we have used few features to describe the whole spectrum with not too much loss of classification accuracy. Thus instead and or in addition to the normal preprocessing that is often performed in pattern recognition, it would be to the researchers interest to find simpler descriptions of the given objects or situations. This would be useful not only in the latter steps in the analysis of such data e.g. classification or clustering etc but could give more insight into the causes of the differences between given objects thus making the analysis easier and more meaningful.

In general the performances of the two new representations is similar, there is no formulation that is outright better than the other. A definitive conclusion on all the classes is not possible as the non target class (NTC) are being compared to different target classes.

In the next chapter we explore another approach to obtaining a sparse representation of spectra. This approach holistically looks at an individual spectrum and determines if the general profile or the finer details of a spectrum is sufficient to differentiate it from other spectra. This information should also allow us to re-represent a spectrum with only salient information. The difference from the approaches outlined in this chapter is that the method to be investigated is a principled multiresolution approach in that the optimal resolution scales are determined automatically rather than in a naive intuitive fashion.

*Where we consider the coarse approximations and finer details of a spectrum profile as a way to discriminate spectra*

## **Chapter 5**

### **5. Wavelets**

In this chapter we introduce and motivate the use of wavelets combined with a genetic algorithm in the discrimination of spectra. We also compare the choice of two different wavelet functions when one is given two different representations of the same object.

#### **5.1 Motivation for Wavelets**

Another approach to a sparse representation of objects could possibly be attained via a wavelet decomposition. Wavelets are a technique that is used to approximate an object (often called a signal) to particular levels of detail or resolution. This is done via a wavelet transformation process explained in section 5.2. This type of decomposition allows one to visualize the coarse and detailed decompositions of the signal. By treating these different signal resolutions as 'features' of the signal we can perform the traditional feature selection on them and use the selected 'features' to reconstruct the signal.

This will allow one to determine whether the differences between two signals can be explained by the general signal profiles or the finer details of the signals. In general we would expect signals that have completely different profiles to be easily separable by their coarse approximations and those with similar profiles to be separable by detailed approximations.

## 5.2 Theory

### 5.2.1 Wavelets

The most common wavelet transformation representation of a 1 dimensional signal is Mallet's so-called cascade/tree/pyramid algorithm [16] as shown in figure 5.1 below. A signal ( $S$ ) is approximated by two faculties - the scaling function ( $\Phi$ ) and the wavelet function ( $\Psi$ ). The scaling function acts as a low frequency filter and the wavelet function can be interpreted as the high pass filter. This means the scaling function is responsible for the rough approximation of the signal whilst the wavelet function is responsible for the details in the signal. As an example in figure 5.1 we initially have  $s_j$  an 8 element signal that we want to approximate using as few elements as possible. In the first step of the wavelet transformation analysis the signal is approximated by the scaling and wavelet functions. Thus the signal is now decomposed into two segments  $s_{j-1}$  and  $d_{j-1}$ , each half the length of the original signal. The scaling function produces  $s_{j-1}$  (the average of the signal) and the wavelet function produces  $d_{j-1}$  (the small details in the signal – actually the small changes in the signal).

In the second step of the wavelet transformation the input signal is now  $s_{j-1}$  from the previous step. This new signal is further transformed as before into two further segments ( $s_{j-2}$  and  $d_{j-2}$ ) that are each half it's length. This process is repeated until a single scaling value is reached. Note: The length of the input signal sets the limit on how many times (levels) one can transform it. The resultant components of the signal in the final step of the decomposition [ $s_{j-3}, d_{j-3}, d_{j-2}, d_{j-1}$ ] are called wavelet coefficients. Once we have obtained these one can modify them individually according to one's needs, we can set a threshold on the elements and any element below such a value be set to zero. This is akin to removing noise. The 'new' decomposed signal can then be reconstructed by the same filters as in the analysis to form a sparse signal.

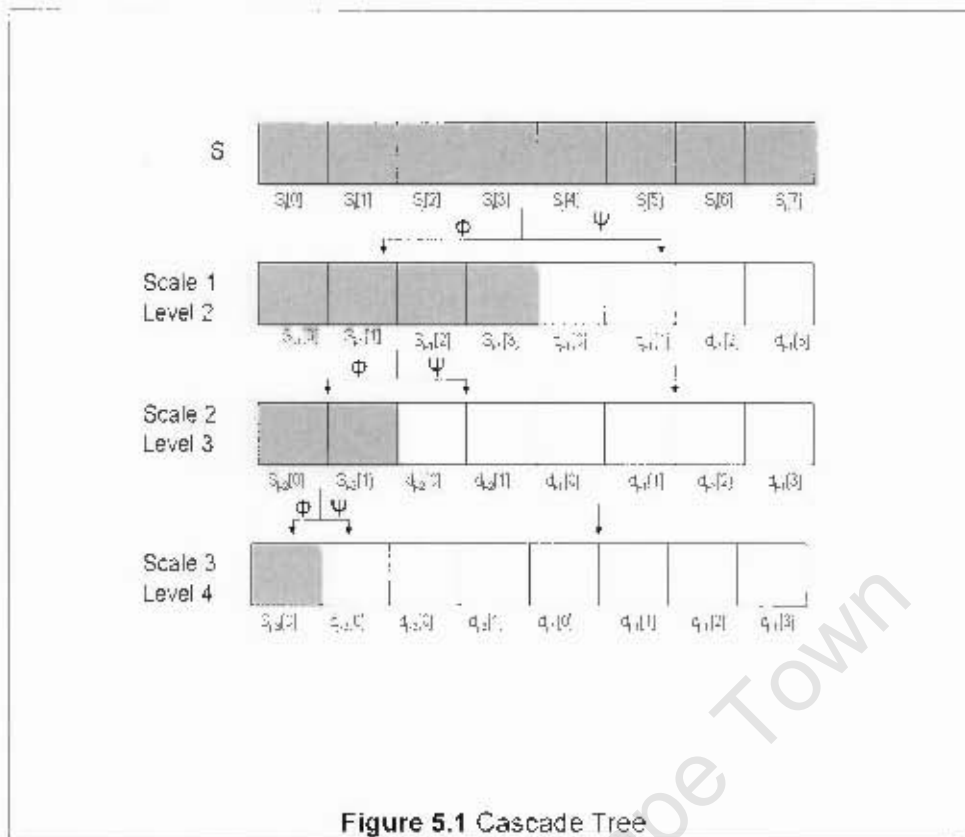
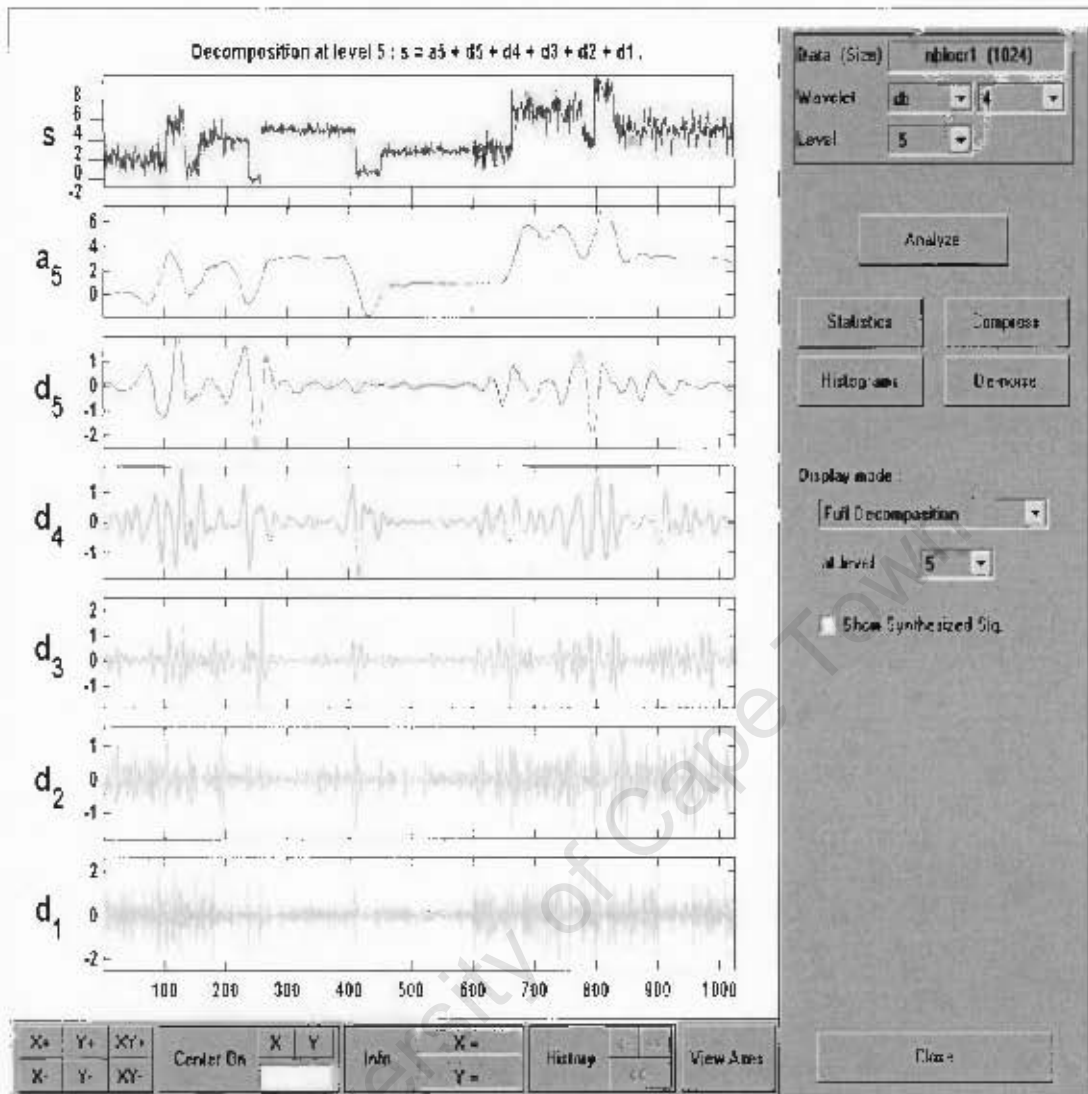


Figure 5.1 Cascade Tree

There are a number of approaches to how one can approximate a signal. This leads to the different types of wavelets. The main difference between them is the way they predict and update their signal approximation steps. In general some wavelets approximate the signal by assuming the signal elements are almost (i) equal/constant (Haar), (ii) linearly related (CDF) or have some other functional relationship. For further details refer to [5,16]. To further explain the interpretation of wavelet coefficients we plot figure 5.2. This figure illustrates the reconstruction of different wavelet coefficients of a signal ( $S$ ) in what is referred to as a Multi-resolution plot.

The signal  $S$  here has been decomposed via the Daubechies - 4 wavelet for 3 scales (4 levels). The  $a_5$  reconstruction is a good coarse approximation of the input signal and the  $d_1$  reconstruction captures the finer details in the signal. By stochastically searching for an optimal set of coefficients to sparsely represent our input spectrum we are essentially selecting different levels of spectrum detail while maintaining the signal structure. Sparsity is attained by the use of as few of these coefficients as possible.



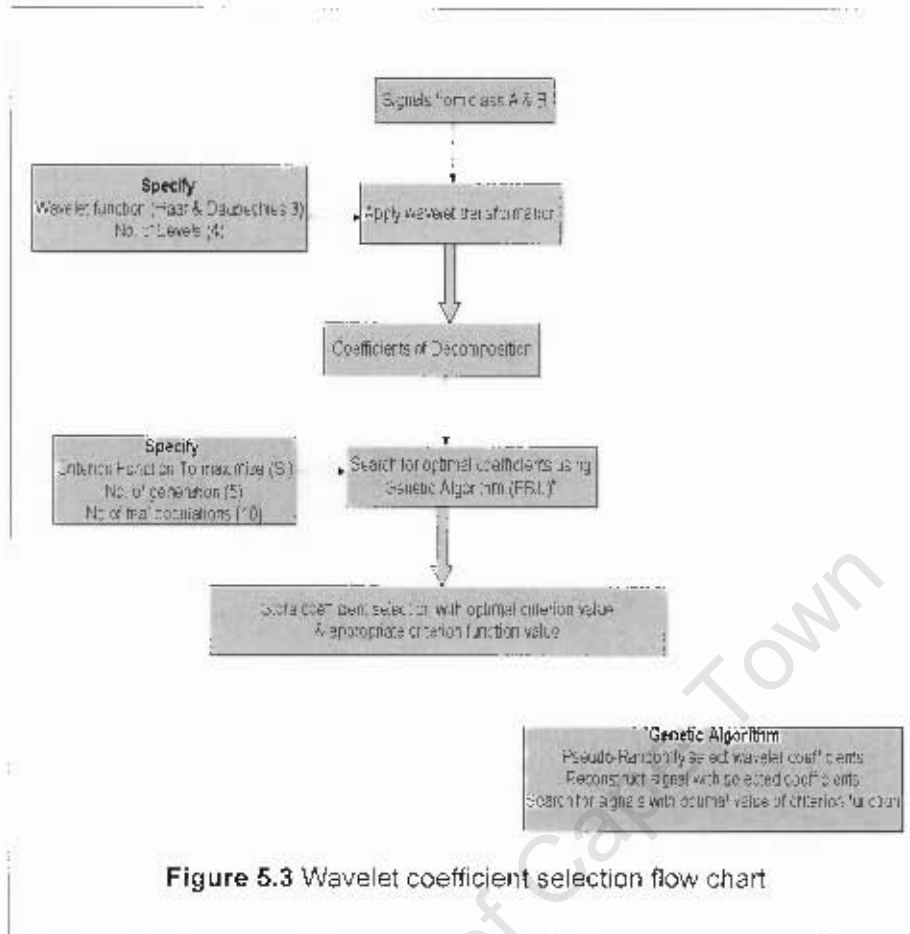
**Figure 5.2** Multiresolution decomposition of a signal  $s$ .  
 $a_5$  -Low pass (Coarse) approximation,  $d_1$ -High pass details of Signal

## 5.2.2 Genetic Algorithms

Computational genetic algorithms are based on a crude model of natural evolution. As an example a trial population of individuals in a particular generation combine to form a new set of individuals made from the genes of the former. This combination of individuals repeats itself for a number of trial populations and each time better and better individuals are produced. To prevent 'run away elitism' an element of random mutation is injected in the formation of the new set of individuals. Most of the 'stronger' individuals survive and a few weaker ones are retained. After each generation of trial populations the best individuals from that generation are used to initialize the next generation.

The cycle repeats itself again for a number of trials within that generation and all the time better sets of individuals are produced than in the previous populations [24]. By using this genetics analogy computational algorithms that efficiently search a huge space of potentially good candidate solutions to a problem have been developed. In the present problem each trial generates a population of possible wavelet coefficients and using the separability index as our goodness criterion we can select the better coefficients for each population. The best set of coefficients is then kept for the next trial generation. Since our optimization algorithm included the decomposition and reconstruction of the signal thus computationally demanding, we constrained our algorithm to only 5 generations with each having 10 different trial populations of possible candidate coefficients.

Figure 5.3 below illustrates the strategy we follow in selecting the wavelet coefficients that result in the best separability between the classes. We make use of a variation of a genetic algorithm called, Population Based Incremental Learning – PBIL [2,8], to stochastically search for the best wavelets coefficients that produce the reconstruction that best separates the classes.



### 5.3 Choice of Wavelet function

In this dissertation we chose to use the Haar and the Daubechies 3 wavelets because:

- They somewhat resemble the spectra 'profiles' we are dealing with (the On or Off slope 1 and On or Off slope 2 representations of the spectra formulated in chapter 4). This is the advantage of using the +1 and -1, for the features of interest, as the wavelets functions cross the origin.
- They will give insight into whether the choice in wavelet function can be related to the signal we are trying to approximate.

We expect the Haar wavelet will produce the best spectrum reconstruction results on the On or Off slope 1 spectrum signal developed in chapter 4 as it closely resembles it. Figure 5.4 show the haar scaling and wavelet functions. Figure 5.5 illustrates the Daubechies scaling and wavelet functions.

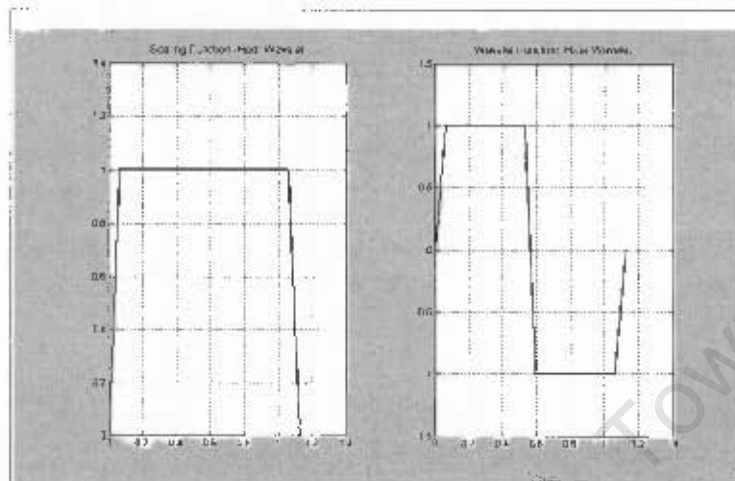


Figure 5.4 Haar Scaling and Wavelet Functions respectively.

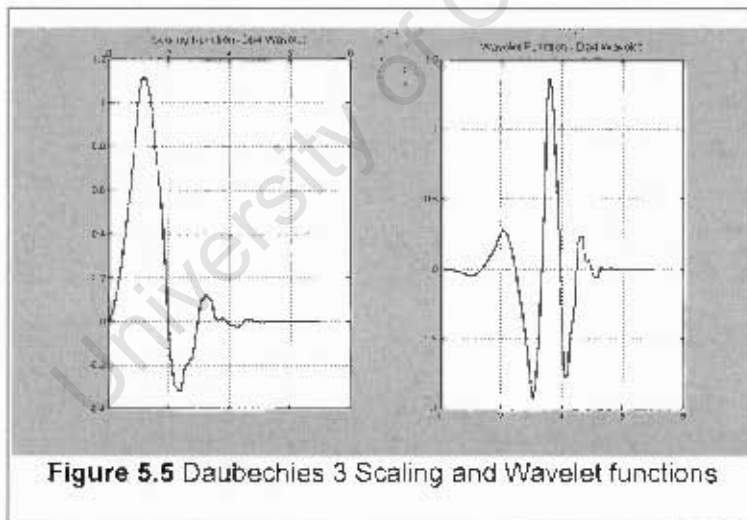


Figure 5.5 Daubechies 3 Scaling and Wavelet functions

## 5.4 Sparse features using Wavelets

It can be shown [16] that the signal length -  $2^{10}$  sensory measurements in our case - determines the number of possible coefficients (10+1 for our spectra). To minimize the computational effort required in the wavelet and genetic algorithm coefficient optimization in this space we constrain the number of wavelet decomposition levels to four. We tested the wavelets optimization algorithm (with Haar and Daubechies wavelet function) on all the different spectrum representations, the reflectance and both On or Off formulations. Better separability results were obtained for the absorption representation (Appendix G) as compared with the results of On or off representations in appendix F and the original reflectance representation.

The algorithm reveals that some classes are easily separable just by their general profiles. This is indicated in cases where only the scaling coefficient is selected. An example of such a case is shown in figure 5.6a. Appendix F tabulates the full results of the wavelet coefficient optimization approach to the On or Off sparse representation for all target classes and different sensitivity settings.

### 5.4.1 Wavelet function relation with signal representation

In general, across all class comparisons, the haar wavelet produces better separability results when it is used on the On or Off slope 1 representation. This is to be expected as the haar wavelet functions have a closer resemblance to the slope 1 function. This result is also shown in figure 5.6a-b below. The Daubechies - 3 wavelet function performed surprisingly better on the On or Off slope 1 than on the slope 2 formulation perhaps indicating that it has a closer resemblance to former formulation than the latter. In figure 5.6a the shaded in columns show where only the general coarse approximation to the spectrum profile would be sufficient to discriminate the two classes.

Haar at scale 0						
On or Off Representation (Scale 1 @ Rough Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	1	1	1	0.93
		1	0	1	0	0.93
		1	1	1	0	0.95
		1	1	1	1	0.93
		1	0	1	1	0.93
		1	1	1	1	0.93
						Average 0.91

Daub 3 at scale 0						
On or Off Representation (Scale 1 @ Rough Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	1	1	0	0.96
		1	1	0	1	0.96
		1	1	1	1	0.99
		1	1	1	0	0.96
		1	1	0	1	0.96
		1	1	1	1	0.96
						Average 0.96

Haar at scale 0						
On or Off Representation (Scale 1 @ 100 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	0	1	0	0.9
		1	0	1	0	0.9
		1	1	1	0	0.9
		1	1	1	1	0.91
		1	0	1	1	0.91
		1	1	1	1	0.91
						Average 0.9

Daub 3 at scale 0						
On or Off Representation (Scale 1 @ 100 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	1	1	0	0.9
		1	1	0	1	0.9
		1	1	1	1	0.91
		1	1	1	0	0.91
		1	1	0	1	0.91
		1	1	1	1	0.91
						Average 0.9

Haar at scale 0						
On or Off Representation (Scale 1 @ 0.5 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	0	1	1	0.91
		1	0	1	0	0.9
		1	1	1	0	0.91
		1	1	1	1	0.91
		1	0	1	1	0.91
		1	0	1	0	0.91
						Average 0.9

Daub 3 at scale 0						
On or Off Representation (Scale 1 @ 0.5 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	1	1	0	0.91
		1	1	0	1	0.91
		1	1	1	1	0.91
		1	1	1	0	0.91
		1	1	0	1	0.91
		1	1	1	1	0.91
						Average 0.91

Figure 5.6a Class 3 vs 5 On or Off slope 1 representation at no SP for Haar & Daub 3 wavelets

Haar at scale 0						
On or Off Representation (Scale 2 @ Rough Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	1	1	1	0.96
		1	1	0	1	0.96
		1	1	1	0	0.96
		1	1	0	0	0.96
		1	1	1	1	0.96
		1	1	1	1	0.96
						Average 0.94

Daub 3 at scale 0						
On or Off Representation (Scale 2 @ Rough Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	1	1	0	0.96
		1	0	1	1	0.96
		1	1	0	1	0.96
		1	1	1	0	0.96
		1	1	1	1	0.96
		1	1	1	1	0.96
						Average 0.95

Haar at scale 0						
On or Off Representation (Scale 2 @ 100 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	0	1	1	0.89
		1	0	1	0	0.89
		1	1	1	0	0.89
		1	1	0	0	0.9
		1	1	1	1	0.89
		1	0	1	1	0.89
						Average 0.88

Daub 3 at scale 0						
On or Off Representation (Scale 2 @ 100 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	0	1	0	0.88
		1	0	0	1	0.88
		1	1	1	0	0.89
		1	0	0	1	0.89
		1	0	1	1	0.89
		1	0	1	0	0.89
						Average 0.88

Haar at scale 0						
On or Off Representation (Scale 2 @ 0.5 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	0	0	1	0.89
		1	0	0	0	0.89
		1	1	1	0	0.89
		1	0	0	1	0.89
		1	1	1	1	0.89
		1	0	1	1	0.89
						Average 0.89

Daub 3 at scale 0						
On or Off Representation (Scale 2 @ 0.5 Setting)						
TC	NTC	a1	a1'	a2	a2'	Separable
3	5	1	0	1	0	0.89
		1	0	0	1	0.89
		1	1	1	0	0.89
		1	0	0	1	0.89
		1	0	1	1	0.89
		1	0	1	0	0.89
						Average 0.89

Figure 5.6b Class 3 vs 5 On or Off slope 2 representation at no SP for Haar & Daub 3 wavelets

In a few cases the general spectrum profile was not important and only the finer details were sufficient to separate the classes well. This mostly occurred with the absorption representation, see Appendix G. The two wavelet functions selected different coefficients for the same class comparisons under the same and different representations. The wavelet coefficient search that selects the fewest coefficients to form the spectrum signal would be the preferred choice.

## 5.5 Wavelet vs non-wavelet based On or Off representations

We can consolidate meaningful performance comparisons of these approaches to sparse representation by looking at their behavior for each target class. From here on we will refer to the On or Off with wavelets and genetic algorithms representation as wavelet - based representation and with no wavelets as non - wavelet based.

### 5.5.1 Target class 1

Table 5.1 below shows the performance of each method as the sensitivity parameter is varied<sup>10</sup>. The wavelet-based approach generally achieves slightly better (highlighted values) class separabilities than non - wavelet based representations (NW), this is true in all target classes. The behavior of all the slope 1 representation's separability indices (the two On or Off slope 1 wavelet based and 1 non-wavelet-based) are similar. They generally start high at no SP setting, drop at SP of 100 and increase again at an SP value of 80. The On or Off slope 2 representations do not exhibit the same behavior as the slope 1 representations, the wavelet-based approaches agree on the effect the sensitivity parameter (SP) has on the separability index (SI) but they do not exhibit the same behavior as the non-wavelet based approach.

<sup>10</sup>To get an idea on the achievable separability indices of the wavelet-based representations, we averaged across the 5 runs (as shown for example in figures 5.6a-b) for each representation even though the features selected were different.

On or Off Slope 1										
TC	NTC	At No SP			At SP=100			At SP=80		
		Separability Index			Separability Index			Separability Index		
		NW	Haar	Daub 3	NW	Haar	Daub 3	NW	Haar	Daub 3
1	5	0.9646	0.978	0.978	0.944	0.973	0.974	0.949	0.956	0.965
	15	0.9646	0.980	0.973	0.982	0.980	0.980	0.941	0.967	0.966
	16	0.9721	0.984	0.984	0.990	0.988	0.988	0.981	0.971	0.971
	17	0.9801	0.986	0.980	0.947	0.966	0.955	0.954	0.972	0.963
	20	0.9778	0.978	0.963	0.987	0.983	0.983	0.974	0.975	0.983
	21	0.9484	0.956	0.948	0.948	0.948	0.947	0.939	0.944	0.943
	25	1.0000	1.000	1.000	0.999	0.996	0.997	0.998	0.998	0.998
31	0.9982	0.999	0.999	0.999	1.000	1.000	0.999	1.000	0.999	

On or Off Slope 2										
TC	NTC	At No SP			At SP=100			At SP=80		
		Separability Index			Separability Index			Separability Index		
		NW	Haar	Daub 3	NW	Haar	Daub 3	NW	Haar	Daub 3
1	5	0.874	0.925	0.925	0.943	0.941	0.941	0.954	0.956	0.959
	15	0.897	0.959	0.959	0.987	0.972	0.985	0.988	0.977	0.971
	18	0.936	0.941	0.940	0.994	0.988	0.985	0.987	0.984	0.989
	17	0.951	0.965	0.969	0.948	0.952	0.958	0.957	0.963	0.969
	20	0.786	0.888	0.898	0.933	0.933	0.933	0.938	0.938	0.941
	21	0.958	0.958	0.940	0.942	0.947	0.944	0.944	0.938	0.960
	25	0.991	1.000	1.000	0.998	0.998	0.998	1.000	1.000	1.000
31	0.992	0.996	0.997	0.998	0.997	0.997	0.998	0.998	0.991	

Table 5.1 Separability Index comparison between wavelets (Haar & Daub) and No wavelets(NW) for TC =1at different SP values

### 5.5.2 Target class 2

The two On or Off slope 1 wavelet - based representations also project consistent SI behavior as the SP is varied for each non - target class. The On or Off Slope 2 wavelet - based representations exhibit similar results for the change in SP value but this behavior is not consistent with the non-wavelet based method.

On or Off Slope 1										
TC	NTC	At No SP			At SP=100			At SP=80		
		Separability Index			Separability Index			Separability Index		
		NW	Haar	Daub 3	NW	Haar	Daub 3	NW	Haar	Daub 3
2	10	0.995	0.992	0.992	0.998	0.998	0.998	0.965	0.965	0.965
	15	0.998	0.992	0.992	0.983	0.988	0.988	0.967	0.965	0.966
	13	0.987	0.988	0.988	0.984	0.983	0.985	0.981	0.988	0.980
	16	0.984	0.984	0.984	0.987	0.986	0.988	0.988	0.967	0.968
	21	0.988	0.988	0.988	0.994	0.996	0.996	0.984	0.988	0.988
	28	0.988	0.987	0.987	0.993	0.994	0.998	0.993	0.995	0.993
	30	0.981	0.988	0.988	0.998	0.998	0.995	0.977	0.989	0.978
31	0.988	1.000	1.000	0.947	0.975	0.968	0.988	0.960	0.962	

On or Off Slope 2										
TC	NTC	At No SP			At SP=100			At SP=80		
		Separability Index			Separability Index			Separability Index		
		NW	Haar	Daub 3	NW	Haar	Daub 3	NW	Haar	Daub 3
2	10	0.99	0.978	0.980	0.982	0.984	0.984	0.978	0.980	0.980
	12	0.99	0.984	0.984	0.981	0.982	0.981	0.980	0.982	0.981
	13	0.98	0.984	0.980	0.982	0.982	0.988	0.978	0.980	0.978
	18	0.98	0.984	0.984	0.984	0.985	0.985	0.988	0.988	0.988
	21	0.98	0.983	0.984	0.988	0.987	0.996	0.985	0.988	0.988
	22	0.98	0.982	0.982	0.988	0.989	0.988	0.985	0.987	0.985
	30	0.98	0.982	0.982	0.988	0.978	0.978	0.978	0.978	0.978
31	0.98	0.982	0.982	0.988	0.986	0.984	0.978	0.987	0.984	

Table 5.2 Separability Index comparison between wavelets (Haar & Daub) and non wavelet-based representations(NW) for TC =2 at different SP values

### 5.5.3 Target class 3

In table 5.3 the wavelet - based representations agree on the influence of the sensitivity parameter on the separability index i.e similar behavior is observed when the sensitivity parameter is varied. The non - wavelet based representation does not quite exhibit similar behavior.

On or Off Slope 1										
TC	NTC	At No SP			At SP = 100			At SP=80		
		Separability Index			Separability Index			Separability Index		
3		NW	Haar	Daub 3	NW	Haar	Daub 3	NW	Haar	Daub 3
	5	0.946	0.993	0.963	0.997	0.998	0.998	0.997	0.905	0.908
	7	0.965	0.998	0.965	0.994	0.994	0.993	0.994	0.985	0.984
	14	0.976	0.994	0.992	0.922	0.908	0.907	0.905	0.922	0.925
	16	0.983	0.989	0.991	0.978	0.908	0.981	0.978	0.907	0.985
	18	0.937	0.963	0.980	0.947	0.944	0.942	0.941	0.922	0.927
	26	0.969	0.982	0.991	0.981	0.972	0.971	0.968	0.977	0.974
	28	0.969	1.000	1.000	0.996	0.972	0.997	0.997	0.996	0.998
	28	0.964	0.977	0.976	0.910	0.915	0.917	0.917	0.915	0.917

On or Off Slope 2										
TC	NTC	At No SP			At SP = 100			At SP=80		
		Separability Index			Separability Index			Separability Index		
3		NW	Haar	Daub 3	NW	Haar	Daub 3	NW	Haar	Daub 3
	5	0.933	0.942	0.954	0.897	0.892	0.893	0.887	0.892	0.893
	7	0.950	0.968	0.984	0.981	0.988	0.986	0.982	0.988	0.985
	14	0.975	0.975	0.974	0.901	0.899	0.897	0.891	0.899	0.898
	16	0.967	0.968	0.970	0.900	0.974	0.974	0.970	0.974	0.974
	18	0.824	0.917	0.928	0.843	0.945	0.944	0.941	0.945	0.944
	26	0.948	0.987	0.970	0.961	0.970	0.967	0.964	0.970	0.967
	28	0.998	1.000	1.000	0.998	0.997	0.998	0.995	0.997	0.998
	28	0.842	0.892	0.957	0.925	0.926	0.924	0.921	0.926	0.924

**Table 5.3** Separability Index comparison between wavelet (Haar & Daub) and non wavelet-based representations(NW) for TC =3 at different SP values

In all target classes the discrepancy in the results between the wavelet - based and non-wavelet based representations is difficult to dissect. This could be due to the different features which the methods are focused on at different sensitivity parameter settings;

- the non - wavelet based approach of the On or Off representation only uses the peaks and troughs as the features thus it does not have a global picture of the spectrum but only these features while
- the wavelet - based representation considers the peaks and troughs as perhaps one 'feature' among other features such as the general change of the whole spectrum. This provides the wavelet - based approach with an upper hand when considering different combinations of these features at different resolutions.

## 5.6 Chapter 5 Discussion

In this chapter we have broadened the concept of “parts of a spectrum” to be the coarse and finer details across the whole spectrum measurement range. We have explored the use of wavelets combined with a genetic algorithm to formulate sparse representations of spectrum. This paradigm has revealed that certain classes can be efficiently discriminated between by using just their profile approximations others require full high pass details, that is, most of the details that are present in the sensory signal (see Appendix G class 2 and 3).

We explored the influence of the wavelet function choice on the reconstruction of a signal when given different representations of the same signal under the above mentioned setting. The signal representation frequently had a significant influence on the performance of wavelet function used. The Haar wavelet function has a visually closer resemblance to the On or Off slope 1 signal and it provided better signal reconstruction in terms of the resultant class separability. In general the wavelet approach to a sparse representation produces slightly better separability indices between classes than the sensory representation. This can be attributed to the use of global stochastic search for the best combination of wavelet coefficients to reconstruct a signal. Unfortunately this approach also presented an inconsistent feature set which makes it difficult to determine which coefficient features are optimal.

*Where we summaries the main ideas of thesis and describe each chapters contribution*

## **Chapter 6**

### **6. Conclusion**

#### **6.1 Discussion**

The main hypothesis of the thesis is that objects dealt with in machine learning could be better represented using simple, human - interpretable descriptions. These descriptions should automatically capture the intuitively salient underlying structure of the objects in question and this we hypothesize will provide the researcher with better insights into not only the data but the designing of interpretable classifiers and clustering algorithms. Common paradigms (for example 'blind' feature selection, data projections(PCA) etc) to this goal do not explicitly reveal the underlying structure of objects but tend to provide more computationally efficient models of representing objects which often do not have a physical interpretability. We observed that human classifiers of images and spectra extract meaningful features when describing such objects and hypothesize that this might also be a helpful strategy for inductive machine classifiers. In this regard we considered three paradigms of meaningful feature discovery.

We reviewed and analyzed a method called Non Negative matrix factorization (NMF), on account of its ability to automatically discover intuitive parts of objects, as a plausible way of extracting such features. Careful investigation of NMF on synthetic problems in the original 'image' context showed that the reality is more complex than this and in general independent object parts are not found. We investigated the relevance of NMF on real spectra. In chapter 4 we explored a more empirical approach to extracting sparse, intuitive visual features from spectra. The features of interests thereby extracted were used to re-describe spectra and this new formulation's efficacy was investigated in terms of class separation of spectra. The final chapter explored wavelets as a more traditional and more principled approach to multiresolution feature extraction and investigated its effect on class separability.

## 6.2 Section conclusions

### 6.2.1 Sparse spectrum representation using NMF

We explored the applicability of a method called Non negative matrix factorization (NMF) in finding parts of spectra when one is given a database of spectra. This was motivated by its applicability in a number of domains (especially images). Unfortunately this method was found not to work well with spectrum type data. The parts found were somewhat holistic, in the sense that it was difficult to distinguish the parts discovered by the method from whole spectra. This limitation of NMF was explained by a synthetic example that revealed what type of problems NMF would be better suited for. This was our novel contribution in this section of the thesis.

### 6.2.2 Sparse re-representation of spectrum using features of interest

By identifying sparse salient features of a spectrum profile we were able to compress the description of the spectrum into simple mathematical models. We chose peaks and troughs as our salient features. We modeled the transition between the features in two simple ways; in one model if the slope of the spectrum profile increased we had a constant positive value and if it decreased we had a constant negative value. The other model interpolated between the peaks and troughs. This type of re-description for spectra produces class separabilities that are in general comparable to the original(sensory) description of spectrum even though they used few 'features'.

This goes some way to show that simple, sparse features can capture important information latent in full sensory formulations of spectrum. A similar argument of using sparse features to describe detailed objects in other domains (facial images) can be drawn by identifying the discriminatory features and forming new descriptions of such images with them one can for example determine how different facial images vary. Two main advantages of this formulation are that is a *simple* and *intuitive* approach to capturing the structure of the objects while giving comparable results to more complex representations. Our novel contribution in this section is the re-representation of spectra using simple mathematical formulations that are intuitively attractive and practical.

### 6.2.3 Sparse representation using wavelets

In this chapter we explored the use of wavelets to determine if the spectrum classes could be better discriminated by coarse approximations or detailed formulations of spectra. By using the coarse and detailed approximations of the wavelet transform as features we used a genetic algorithm, PBIL, to search for the best sparse representation in terms of class separability. Since the class separabilities were initially high with the original reflectance spectrum only a slight improvement was noticeable in some classes especially with the absorption formulation.

On average the wavelet formulation improved the separability indices between the classes *but* this was a computationally expensive process. It consisted of the following processes: wavelet decomposition of signal, representation of wavelet coefficients as features and class separability optimization with these features using genetic algorithm (see figure 5.3) as is frequently the case in feature selection. The method was often not consistent in the selected optimal features for any of the representations over the trial generations (see Appendix F & G). One of the primary motivations of this study is to discover simple interpretable features to describe spectra such that they can assist us in later processing, we would thus prefer simple and quick guides to how we can achieve this. The class separability gains achieved with the wavelet approach do not justify the computational costs incurred over the non wavelet approach presented in chapter 4.

### 6.3 Representation Conclusion

In general, for the approaches considered in this thesis, there is no clearly 'overall best' approach to achieving a sparse spectrum representation. This can be attributed to the following factors:

- The target classes are different and
- Most of the non-target classes are not common to all the target classes and this makes it difficult to succinctly generate a good characterization of the classes.
- The different approaches to sparsity achieve quite similar separability results.

But in terms of providing *slightly* better class separabilities wavelet representation is better. This is shown at the end of chapter 5. What is clear is that the results of the different approaches are quite similar and the main differences are in implementation practicality and result presentation. Perhaps then we can only evaluate these approaches by considering their strengths and weaknesses:

#### Advantages of wavelets with genetic algorithm approach

- Slightly better class separability which can be attributed to the genetic algorithm's optimal search of the huge solution space.
- Ability to automatically reveal which features are is important in object discrimination.
- Method allows global visualization of the optimal features using multiresolution analysis.

#### Disadvantages of wavelet with genetic algorithm approach

- Huge computational cost due to a number of processes: signal decomposition, stochastic search and signal reconstruction.
- Too many free (user specified) parameters: Number of decomposition levels, wavelet function to use, number of trials and generations in the genetic algorithm.
- Non consistent optimal feature set.

#### Advantages of non-wavelet-based approach

- Single user parameter (the sensitivity parameter) – This results in quick and simple experiments.

#### Disadvantages of non-wavelet-based approach

- User defined features of interest – this limits the method to exploit *only* these.

Taking computational and method - result-presentation into account we would not recommend the wavelet approach as a simple, initial preprocessing, exercise to explore dataset structures. This can be better achieved by simpler and quicker methods such as those presented in chapter 4. If a significant amount of knowledge about data objects is required for long term projects then wavelet based simulations could be worth the computational burden.

#### **6.4 Open problems/Future work**

A possible extension to this work could be having identified the important discriminatory features in objects to actually determine how they are *inter-related*. Just as in the synthetic Sticks problem or facial images; if the features (sticks,eyes,nose etc) are identified and their possible positions in the images are determined, one could have an overall description of how complete objects in the images are formed. This we believe could lead one to formulate a powerful new representation of objects.

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**Appendix**

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## Appendix A

### Separability Index of combined classes on Reflectance data

1=[1 to 2], 2=[3to12], 3 =[13 to 14] and [15-42] relabeled as classes [4-31].

Amanda* Combined		
TC	NTC	SI
1	2	0.997
1	3	0.997
1	4	0.985
1	5	0.972
1	6	0.938
1	7	0.938
1	8	0.995
1	9	0.995
1	10	0.996
1	11	0.994
1	12	0.994
1	13	1.000
1	14	0.989
1	15	0.939
1	16	0.962
1	17	0.974
1	18	0.982
1	19	0.996
1	20	0.943
1	21	0.953
1	22	0.901
1	23	0.993
1	24	0.986
1	25	0.986
1	26	1.000
1	27	0.997
1	28	0.968
1	29	0.978
1	30	0.993
1	31	1.000

Amanda 1 Combined		
TC	NTC	SI
2	3	0.996
2	4	0.996
2	5	0.983
2	6	0.982
2	7	0.982
2	8	0.993
2	9	0.992
2	10	0.973
2	11	0.992
2	12	0.961
2	13	0.984
2	14	0.991
2	15	0.998
2	16	0.995
2	17	0.997
2	18	0.987
2	19	0.966
2	20	0.999
2	21	0.998
2	22	0.989
2	23	0.994
2	24	0.968
2	25	0.992
2	26	0.991
2	27	0.993
2	28	0.982
2	29	0.980
2	30	0.966
2	31	1.000

Amanda 1 Combined		
TC	NTC	SI
3	4	0.996
3	5	0.987
3	6	0.998
3	7	0.999
3	8	0.995
3	9	0.997
3	10	0.994
3	11	0.995
3	12	0.997
3	13	0.998
3	14	0.989
3	15	0.994
3	16	0.983
3	17	0.998
3	18	0.987
3	19	0.995
3	20	0.996
3	21	0.995
3	22	0.990
3	23	0.991
3	24	0.990
3	25	0.983
3	26	1.000
3	27	0.998
3	28	0.965
3	29	0.990
3	30	0.993
3	31	1.000

TC :-Target Class

NTC :- Non Target Class

SI :-Separability Index

## Appendix B

### Effect of Changing Representation from Reflectance to Absorption Representation on the Separability index

<i>Reflectance Representation</i>				<i>Reflectance Representation</i>				<i>Reflectance Representation</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>		<i>TC</i>	<i>NTC</i>	<i>S.I</i>		<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.972		2	10	0.9786		3	5	0.9872
1	15	0.9389		2	12	0.9814		3	7	0.9988
1	16	0.9615		2	13	0.9843		3	14	0.9889
1	17	0.9737		2	18	0.987		3	16	0.9834
1	20	0.9491		2	21	0.9982		3	18	0.9868
1	21	0.9577		2	22	0.9894		3	25	0.9832
1	26	1		2	30	0.9858		3	26	1
1	31	1		2	31	1		3	28	0.9653
<i>Absorption Representation</i>				<i>Absorption Representation</i>				<i>Absorption Representation</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>		<i>TC</i>	<i>NTC</i>	<i>S.I</i>		<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.9713		2	10	0.981		3	5	0.9849
1	15	0.9674		2	12	0.9809		3	7	0.9968
1	16	0.9683		2	13	0.9838		3	14	0.9894
1	17	0.9827		2	18	0.9877		3	16	0.9829
1	20	0.9749		2	21	0.9981		3	18	0.9889
1	21	0.9385		2	22	0.9896		3	25	0.9827
1	26	1		2	30	0.9885		3	26	1
1	31	1		2	31	0.9997		3	28	0.9599

**Note:**

Reflectance Representation : = Original Given Data.

Absorption Representation : = Original Data with Convex Hull Removed.

Sepindex (S.I) : = Average Separability index over 5 'fold cross validation'

TC : = Target Class

NTC : = Non Target Class

## Appendix C

### Effect of Changing Representation from Absorption to On or Off slope1 Representation on the separability index -with no sensitivity parameter

<i>Reflectance Representation</i>			<i>Reflectance Representation</i>			<i>Reflectance Representation</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.972	2	10	0.9786	3	5	0.9872
1	15	0.9389	2	12	0.9814	3	7	0.9988
1	16	0.9615	2	13	0.9843	3	14	0.9889
1	17	0.9737	2	18	0.987	3	16	0.9834
1	20	0.9491	2	21	0.9982	3	18	0.9868
1	21	0.9577	2	22	0.9894	3	25	0.9832
1	26	1	2	30	0.9858	3	26	1
1	31	1	2	31	1	3	28	0.9653
<i>Absorption Data</i>			<i>Absorption Data</i>			<i>Absorption Data</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.9713	2	10	0.981	3	5	0.9849
1	15	0.9674	2	12	0.9809	3	7	0.9968
1	16	0.9683	2	13	0.9838	3	14	0.9894
1	17	0.9827	2	18	0.9877	3	16	0.9829
1	20	0.9749	2	21	0.9981	3	18	0.9889
1	21	0.9385	2	22	0.9896	3	25	0.9827
1	26	1	2	30	0.9885	3	26	1
1	31	1	2	31	0.9997	3	28	0.9599
<i>On or Off slope1</i>			<i>On or Off slope1</i>			<i>On or Off slope1</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.964	2	10	0.9894	3	5	0.9478
1	15	0.964	2	12	0.99	3	7	0.9948
1	16	0.9721	2	13	0.9871	3	14	0.9762
1	17	0.9801	2	18	0.9539	3	16	0.9829
1	20	0.977	2	21	0.9951	3	18	0.937
1	21	0.9404	2	22	0.9577	3	25	0.9694
1	26	1	2	30	0.9814	3	26	0.9987
1	31	0.9982	2	31	0.9319	3	28	0.9637

**Note:**

Reflectance Representation: = Original Given Data.

Absorption Representation : = Original Data with Convex Hull Removed.

On or Off Representation : = Spectrum defined by peaks (+1),troughs(-1) and transition modeled by constant positive (slope increasing) or negative value (slope decreasing)

Sepindex (S.I) : = Average Separability index over 5 'fold cross validation'

TC : = Target Class & NTC : = Non Target Class

## Appendix D

### Effect of changing from Absorption to On or Off slope 2 Representation on the separability index – No sensitivity parameter

<i>Reflectance Representation</i>			<i>Reflectance Representation</i>			<i>Reflectance Representation</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.972	2	10	0.9786	3	5	0.9872
1	15	0.9389	2	12	0.9814	3	7	0.9988
1	16	0.9615	2	13	0.9843	3	14	0.9889
1	17	0.9737	2	18	0.987	3	16	0.9834
1	20	0.9491	2	21	0.9982	3	18	0.9868
1	21	0.9577	2	22	0.9894	3	25	0.9832
1	26	1	2	30	0.9858	3	26	1
1	31	1	2	31	1	3	28	0.9653
<i>Absorption Data</i>			<i>Absorption Data</i>			<i>Absorption Data</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.9713	2	10	0.981	3	5	0.9849
1	15	0.9674	2	12	0.9809	3	7	0.9968
1	16	0.9683	2	13	0.9838	3	14	0.9894
1	17	0.9827	2	18	0.9877	3	16	0.9829
1	20	0.9749	2	21	0.9981	3	18	0.9889
1	21	0.9385	2	22	0.9896	3	25	0.9827
1	26	1	2	30	0.9885	3	26	1
1	31	1	2	31	0.9997	3	28	0.9599
<i>On or Off Slope 2</i>			<i>On or Off Slope 2</i>			<i>On or Off Slope 2</i>		
<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>	<i>TC</i>	<i>NTC</i>	<i>S.I</i>
1	5	0.8744	2	10	0.9865	3	5	0.9327
1	15	0.8268	2	12	0.9864	3	7	0.9896
1	16	0.926	2	13	0.9796	3	14	0.9762
1	17	0.9135	2	18	0.9493	3	16	0.9673
1	20	0.7596	2	21	0.9929	3	18	0.8239
1	21	0.9375	2	22	0.9763	3	25	0.9481
1	26	0.8509	2	30	0.9756	3	26	0.9983
1	31	0.3921	2	31	0.8342	3	28	0.8422

**Note:**

Reflectance Representation : = Original Given Data.

Absorption Representation : = Original Data with Convex Hull Removed.

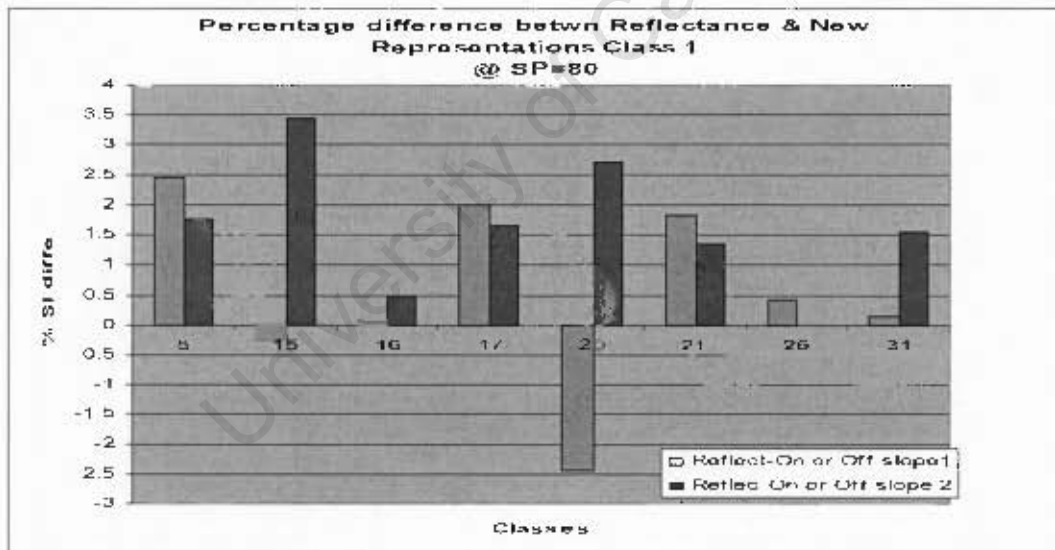
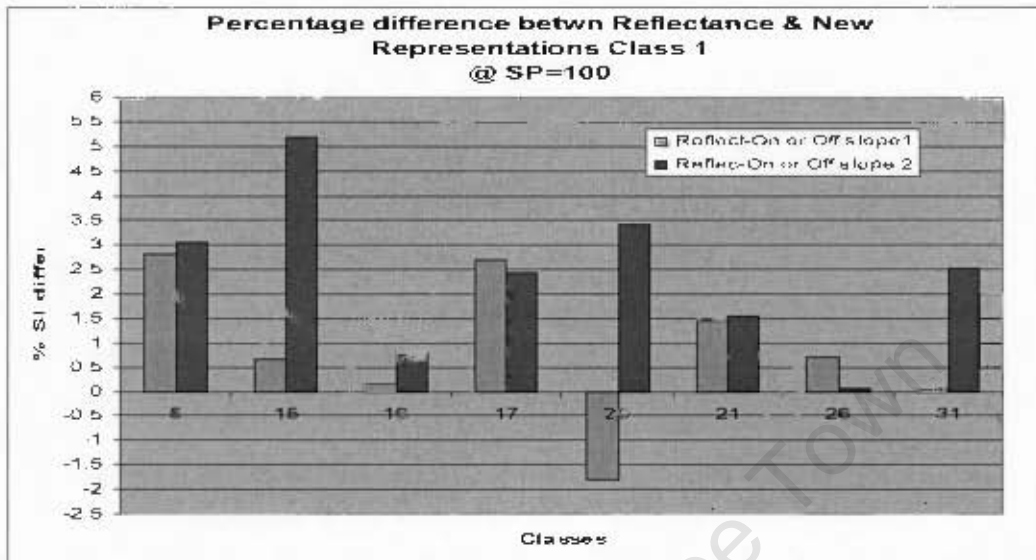
On or Off slope 2 Representation : = Spectrum defined by peaks and troughs and transition between these modeled by linear interpolation

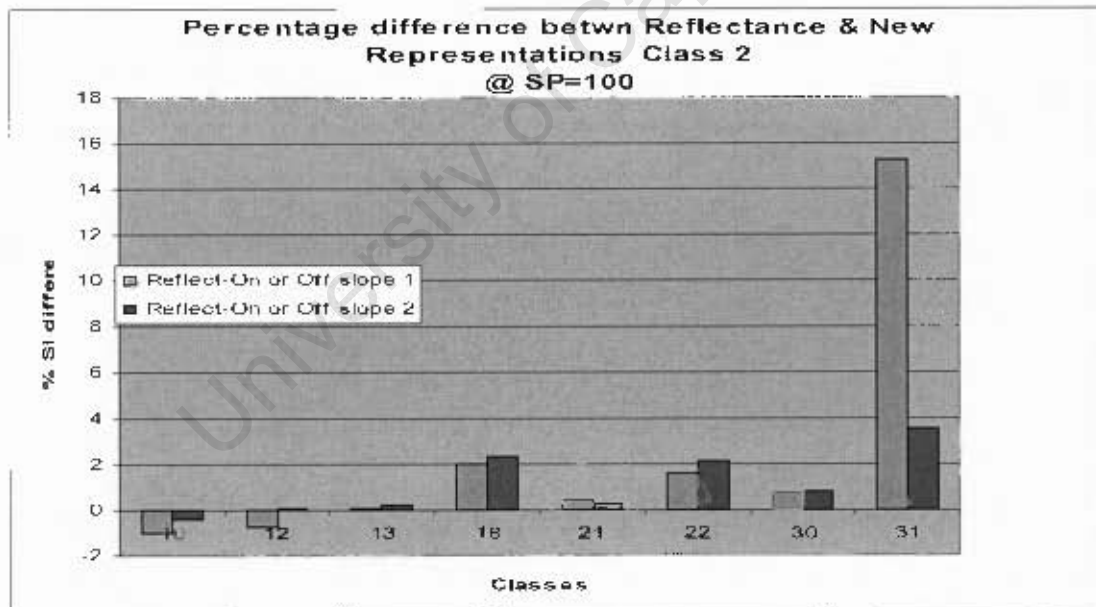
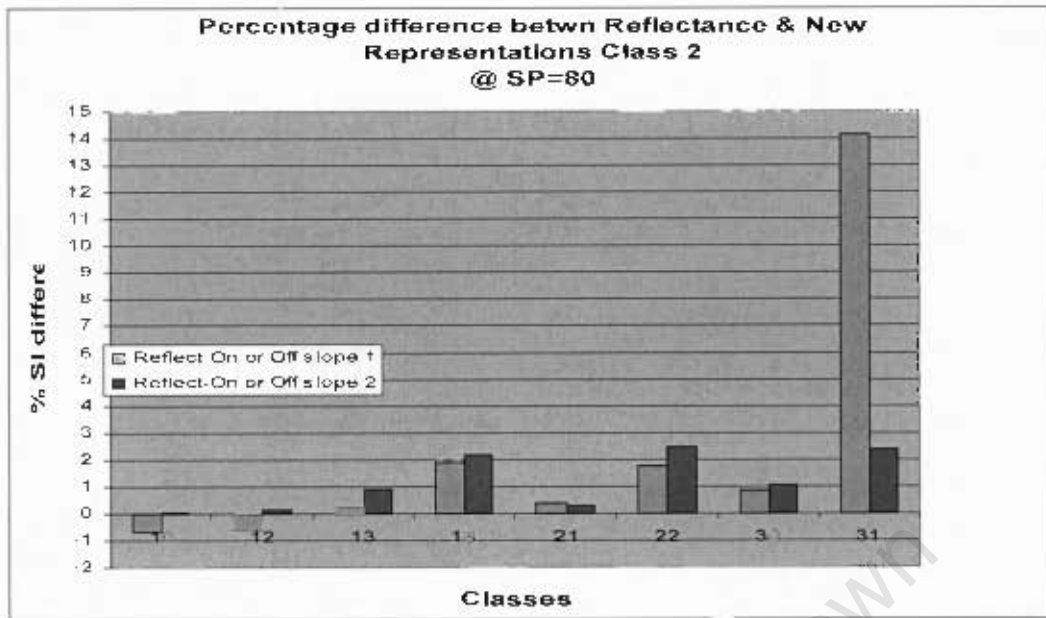
Sepindex (S.I) : = Average Separability index over 5 'fold cross validation'.

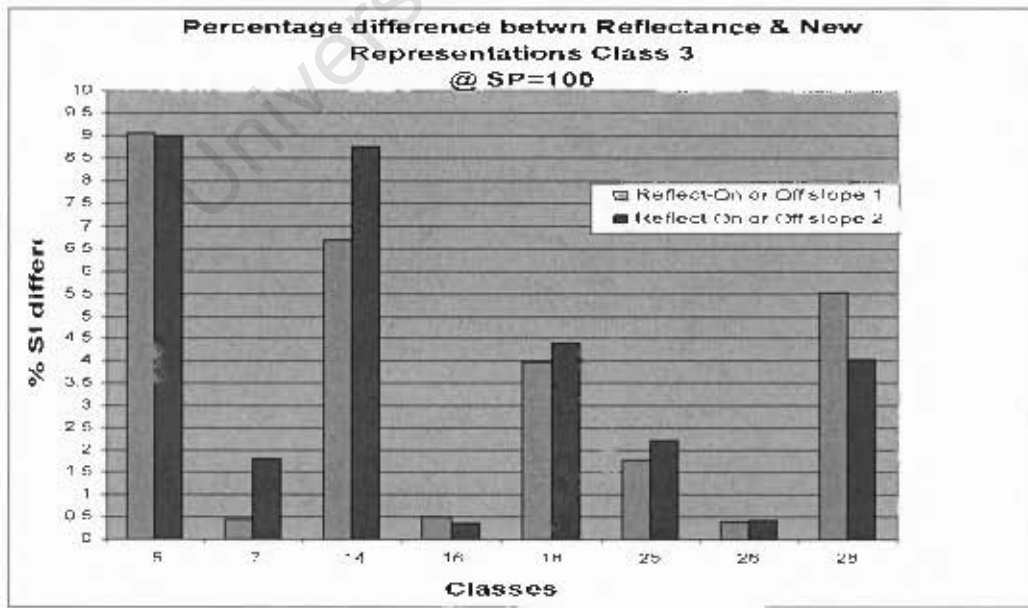
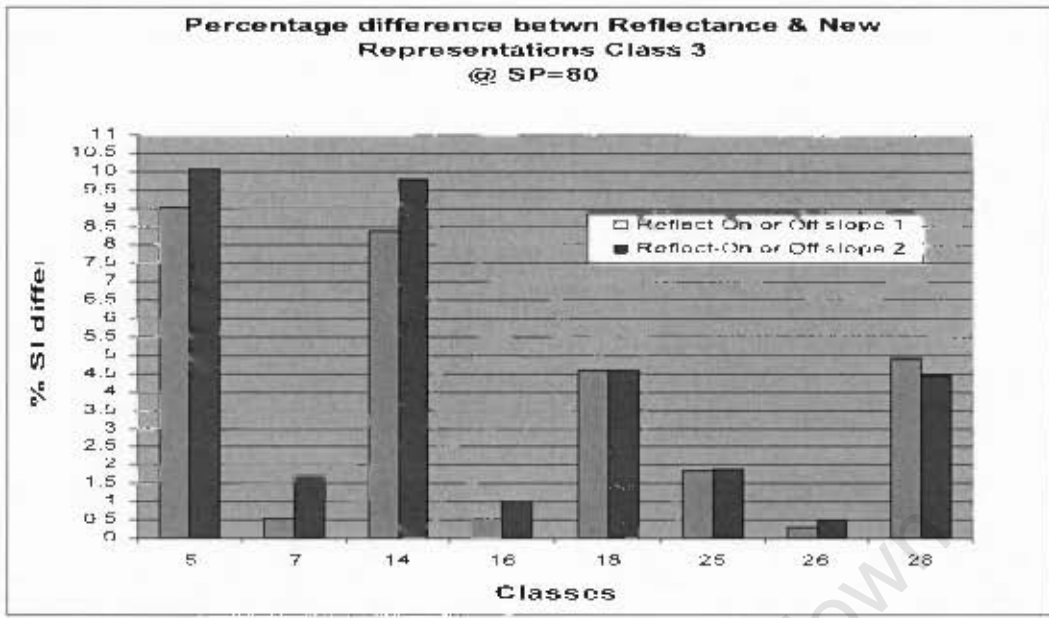
TC : = Target Class and NTC : = Non Target Class

## Appendix E

**Percentage Separability difference between using Reflectance & On or Off Representations at different Sensitivity Parameter (SP) settings**











**Target Class= 3 Non Target Class =14  
Haar & Daubechies 3 Wavelets**

Haar scale of 3

On or Off Representation Slope 1 @ SP=0						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	-0.922	0.350	0.922	0.922	0.992
		-0.922	0.350	0.922	0.922	0.994
		-0.922	0.350	0.922	0.922	0.996
		-0.922	0.350	0.922	0.922	0.997
		-0.922	0.350	0.922	0.922	0.998
		-0.922	0.350	0.922	0.922	0.998
		Average				0.998

Daubechies scale of 3

On or Off Representation Slope 1 @ SP=0						
TC	NTC	a1	a2	a3	a4	Separation
3.500	14.000	-0.922	0.500	0.000	0.922	0.985
		-0.922	0.500	0.000	0.922	0.984
		-0.922	0.500	0.000	0.922	0.984
		-0.900	0.500	0.000	0.922	0.987
		-0.922	0.500	0.000	0.922	0.990
		Average				0.989

Haar scale of 3

On or Off Representation Slope 1 @ SP=10						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.000	0.922	0.922	0.992
		1.000	0.000	0.922	0.922	0.994
		1.000	0.000	0.922	0.922	0.996
		1.000	0.000	0.922	0.922	0.997
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		Average				0.998

Daubechies scale of 3

On or Off Representation Slope 1 @ SP=10						
TC	NTC	a1	a2	a3	a4	Separation
3.500	14.000	1.000	0.500	1.000	0.000	0.994
		1.000	0.500	0.000	0.000	0.992
		1.000	0.500	0.000	0.922	0.993
		1.000	0.500	1.000	0.922	0.995
		1.000	0.500	0.000	0.922	0.995
		1.000	0.500	0.000	0.922	0.995
		Average				0.997

Haar scale of 3

On or Off Representation Slope 1 @ SP=50						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		Average				0.998

Daubechies scale of 3

On or Off Representation Slope 1 @ SP=50						
TC	NTC	a1	a2	a3	a4	Separation
3.500	14.000	1.000	0.500	0.000	0.922	0.992
		1.000	0.500	0.000	0.922	0.993
		1.000	0.500	0.000	0.922	0.993
		1.000	0.500	0.000	0.922	0.993
		1.000	0.500	0.000	0.922	0.993
		1.000	0.500	0.000	0.922	0.993
		Average				0.993

On or Off slope 1 at different SP values

Haar scale of 3

On or Off Representation Slope 2 @ SP=0						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.000	1.000	0.922	0.993
		1.000	0.000	1.000	0.922	0.995
		1.000	0.000	1.000	0.922	0.991
		1.000	0.000	1.000	0.922	0.993
		1.000	0.000	1.000	0.922	0.995
		1.000	0.000	1.000	0.922	0.995
		Average				0.993

Daubechies scale of 3

On or Off Representation Slope 2 @ SP=0						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	1.000	0.922	0.000	0.994
		1.000	0.922	0.922	0.000	0.997
		1.000	1.000	0.922	0.500	0.993
		1.000	1.000	0.922	0.500	0.997
		1.000	1.000	0.922	0.000	0.997
		1.000	1.000	0.922	0.000	0.997
		Average				0.994

Haar scale of 3

On or Off Representation Slope 2 @ SP=10						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.000	0.922	0.922	0.998
		1.000	0.000	1.000	0.922	0.992
		1.000	0.000	0.922	0.922	0.997
		1.000	0.000	1.000	0.922	0.996
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		Average				0.998

Daubechies scale of 3

On or Off Representation Slope 2 @ SP=10						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.000	0.922	0.000	0.993
		1.000	0.000	0.922	1.000	0.995
		1.000	1.000	0.922	0.000	0.997
		1.000	0.000	0.922	1.000	0.996
		1.000	0.000	0.922	0.000	0.994
		1.000	0.000	0.922	0.000	0.994
		Average				0.997

Haar scale of 3

On or Off Representation Slope 2 @ SP=50						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.000	0.922	0.922	0.998
		1.000	0.000	1.000	0.922	0.992
		1.000	0.000	0.922	0.922	0.997
		1.000	0.000	1.000	0.922	0.996
		1.000	0.000	0.922	0.922	0.998
		1.000	0.000	0.922	0.922	0.998
		Average				0.998

Daubechies scale of 3

On or Off Representation Slope 2 @ SP=50						
TC	NTC	a1	a2	a3	a4	Separation
3.000	14.000	1.000	0.500	0.922	1.000	0.993
		1.000	0.000	0.922	1.000	0.994
		1.000	1.000	0.922	0.000	0.992
		1.000	0.922	0.922	1.000	0.996
		1.000	0.000	0.922	0.000	0.993
		1.000	0.000	0.922	0.000	0.993
		Average				0.993

On or Off slope 2 at different SP values

**Target Class= 3 Non Target Class =16  
Haar & Daubechies 3 Wavelets**

Haar at scale of 3

On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.990
1.00	0.50	1.00	1.00	1.00	0.987
1.00	1.00	0.50	1.00	1.00	0.987
1.00	0.50	1.00	1.00	1.00	0.980
1.00	1.00	0.50	1.00	1.00	0.976
Average					0.988

Daub 3 at scale of 3

On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.990
1.00	0.50	1.00	1.00	1.00	0.992
1.00	1.00	0.50	1.00	1.00	0.995
1.00	0.50	1.00	1.00	1.00	0.988
1.00	1.00	0.50	1.00	1.00	0.982
Average					0.991

Haar at scale of 1

On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.998
1.00	0.50	1.00	1.00	1.00	0.994
1.00	1.00	0.50	1.00	1.00	0.996
1.00	0.50	1.00	1.00	1.00	0.997
1.00	1.00	0.50	1.00	1.00	0.999
Average					0.998

Daub 3 at scale of 1

On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.998
1.00	0.50	1.00	1.00	1.00	0.992
1.00	1.00	0.50	1.00	1.00	0.995
1.00	0.50	1.00	1.00	1.00	0.996
1.00	1.00	0.50	1.00	1.00	0.998
Average					0.991

Haar at scale of 3

On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.986
1.00	0.50	1.00	1.00	1.00	0.987
1.00	1.00	0.50	1.00	1.00	0.980
1.00	0.50	1.00	1.00	1.00	0.987
1.00	1.00	0.50	1.00	1.00	0.982
Average					0.984

Daub 3 at scale of 3

On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.985
1.00	0.50	1.00	1.00	1.00	0.982
1.00	1.00	0.50	1.00	1.00	0.986
1.00	0.50	1.00	1.00	1.00	0.985
1.00	1.00	0.50	1.00	1.00	0.982
Average					0.983

On or Off slope 1 at different SP values

Haar at scale of 3

On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.992
1.00	0.50	1.00	1.00	1.00	0.987
1.00	1.00	0.50	1.00	1.00	0.990
1.00	0.50	1.00	1.00	1.00	0.990
1.00	1.00	0.50	1.00	1.00	0.987
Average					0.989

Daub 3 at scale of 3

On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.990
1.00	0.50	1.00	1.00	1.00	0.987
1.00	1.00	0.50	1.00	1.00	0.992
1.00	0.50	1.00	1.00	1.00	0.992
1.00	1.00	0.50	1.00	1.00	0.992
Average					0.990

Haar at scale of 1

On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.997
1.00	0.50	1.00	1.00	1.00	0.992
1.00	1.00	0.50	1.00	1.00	0.995
1.00	0.50	1.00	1.00	1.00	0.996
1.00	1.00	0.50	1.00	1.00	0.997
Average					0.994

Daub 3 at scale of 1

On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.998
1.00	0.50	1.00	1.00	1.00	0.998
1.00	1.00	0.50	1.00	1.00	0.998
1.00	0.50	1.00	1.00	1.00	0.998
1.00	1.00	0.50	1.00	1.00	0.998
Average					0.998

Haar at scale of 3

On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.992
1.00	0.50	1.00	1.00	1.00	0.992
1.00	1.00	0.50	1.00	1.00	0.995
1.00	0.50	1.00	1.00	1.00	0.995
1.00	1.00	0.50	1.00	1.00	0.992
Average					0.994

Daub 3 at scale of 3

On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a1	a2	Significance
1.00	15.00	1.00	0.50	1.00	0.992
1.00	0.50	1.00	1.00	1.00	0.992
1.00	1.00	0.50	1.00	1.00	0.997
1.00	0.50	1.00	1.00	1.00	0.997
1.00	1.00	0.50	1.00	1.00	0.997
Average					0.994

On or Off slope 2 at different SP values

**Target Class= 3 Non Target Class =18  
Haar & Daubechies 3 Wavelets**

Data Sample #1		On or Off Representation Slope 1 @ No SP					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	18.000	1.000	0.000	1.000	0.000	0.975	
		1.000	0.000	0.000	0.000	0.994	
		1.000	0.000	0.000	0.000	0.992	
		1.000	0.000	1.000	0.000	0.977	
		1.000	0.000	0.000	0.000	0.971	
		Average					0.983

Data Sample #1		On or Off Representation Slope 1 @ SP					
TC	NTC	a1	a2	a3	a4	Separator	
3.000	15.000	1.000	0.000	0.000	0.000	0.971	
		1.000	0.000	0.000	0.000	0.975	
		1.000	0.000	0.000	0.000	0.962	
		1.000	0.000	0.000	0.000	0.972	
		1.000	0.000	0.000	0.000	0.986	
		Average					0.969

Data Sample #2		On or Off Representation Slope 1 @ No SP					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	15.000	1.000	0.000	1.000	0.000	0.928	
		1.000	0.000	0.000	0.000	0.947	
		1.000	0.000	0.000	0.000	0.951	
		1.000	0.000	0.000	0.000	0.940	
		1.000	0.000	0.000	0.000	0.952	
		Average					0.944

Data Sample #2		On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a2	a3	a4	Separator	
3.000	18.000	1.000	1.000	0.000	0.000	0.926	
		1.000	1.000	1.000	1.000	0.951	
		1.000	0.000	0.000	1.000	0.940	
		1.000	1.000	1.000	1.000	0.930	
		1.000	1.000	0.000	0.000	0.916	
		Average					0.942

Data Sample #3		On or Off Representation Slope 1 @ SP=50					
TC	NTC	a1	a2	a3	a4	Separator	
3.000	15.000	1.000	0.000	0.000	1.000	0.959	
		1.000	0.000	0.000	0.000	0.959	
		1.000	0.000	0.000	0.000	0.951	
		1.000	0.000	0.000	0.000	0.956	
		1.000	0.000	0.000	0.000	0.959	
		Average					0.958

Data Sample #3		On or Off Representation Slope 1 @ SP=50					
TC	NTC	a1	a2	a3	a4	Separator	
3.000	15.000	1.000	0.000	0.000	1.000	0.955	
		1.000	0.000	1.000	0.000	0.985	
		1.000	0.000	0.000	1.000	0.951	
		1.000	0.000	0.000	0.000	0.953	
		1.000	1.000	0.000	1.000	0.959	
		Average					0.967

On or Off slope 1 at different SP values

Data Sample #4		On or Off Representation Slope 2 @ No SP					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	15.000	1.000	0.000	1.000	0.000	0.921	
		1.000	0.000	1.000	0.000	0.907	
		1.000	0.000	1.000	0.000	0.910	
		1.000	0.000	1.000	0.000	0.902	
		1.000	1.000	1.000	0.000	0.921	
		Average					0.917

Data Sample #4		On or Off Representation Slope 2 @ SP					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	18.000	1.000	1.000	1.000	0.000	0.928	
		1.000	1.000	1.000	0.000	0.938	
		1.000	1.000	1.000	0.000	0.919	
		1.000	0.000	1.000	0.000	0.908	
		1.000	1.000	1.000	0.000	0.944	
		Average					0.939

Data Sample #5		On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	15.000	1.000	0.000	1.000	1.000	0.991	
		1.000	0.000	0.000	0.000	0.944	
		1.000	0.000	1.000	1.000	0.945	
		1.000	0.000	1.000	1.000	0.967	
		1.000	0.000	0.000	0.000	0.940	
		Average					0.945

Data Sample #5		On or Off Representation Slope 2 @ SP=100					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	15.000	1.000	1.000	0.000	0.000	0.940	
		1.000	1.000	0.000	0.000	0.924	
		1.000	0.000	0.000	0.000	0.951	
		1.000	0.000	1.000	1.000	0.967	
		1.000	0.000	1.000	1.000	0.962	
		Average					0.944

Data Sample #6		On or Off Representation Slope 2 @ SP=50					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	15.000	1.000	0.000	0.000	1.000	0.944	
		1.000	0.000	0.000	0.000	0.934	
		1.000	0.000	1.000	0.000	0.949	
		1.000	0.000	0.000	1.000	0.907	
		1.000	0.000	1.000	1.000	0.940	
		Average					0.945

Data Sample #6		On or Off Representation Slope 2 @ SP=50					
TC	NTC	a1	a2	a3	a4	Separator	
1.000	15.000	1.000	1.000	0.000	0.000	0.948	
		1.000	1.000	0.000	0.000	0.934	
		1.000	0.000	0.000	0.000	0.950	
		1.000	0.000	1.000	0.000	0.909	
		1.000	0.000	1.000	1.000	0.942	
		Average					0.944

On or Off slope 2 at different SP values

**Target Class= 3 Non Target Class =25  
Haar & Daubechies 3 Wavelets**

		Haar at scale of 3				
		On or Off Representation Slope 1 @ SP=50				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	1.000	* 0.000	1.000	0.988
		1.000	0.000	0.000	0.000	0.988
		1.000	0.000	* 0.000	0.000	0.988
		1.000	0.000	* 0.000	0.000	0.988
		1.000	* 0.000	0.000	0.000	0.988
						<b>Average 0.988</b>

		Daub 3 at scale of 3				
		On or Off Representation Slope 1 @ SP=50				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	* 0.000	* 0.000	1.000	1.000	0.988
		* 0.000	0.000	0.000	1.000	0.988
		* 0.000	* 0.000	0.000	0.000	0.988
		* 0.000	* 0.000	0.000	0.000	0.988
		* 0.000	0.000	0.000	0.000	0.988
						<b>Average 0.988</b>

		Haar at scale of 3				
		On or Off Representation Slope 1 @ SP=100				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	0.000	0.000	0.000	0.975
		1.000	0.000	0.000	0.000	0.975
		1.000	1.000	0.000	0.000	0.973
		1.000	0.000	0.000	0.000	0.978
		1.000	0.000	0.000	* 0.000	0.950
						<b>Average 0.972</b>

		Daub 3 at scale of 3				
		On or Off Representation Slope 1 @ SP=100				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	0.000	* 0.000	0.000	0.970
		1.000	0.000	* 0.000	1.000	0.973
		1.000	* 0.000	0.000	* 0.000	0.970
		* 0.000	0.000	* 0.000	0.000	0.978
		1.000	0.000	0.000	0.000	0.955
						<b>Average 0.971</b>

		Haar at scale of 3				
		On or Off Representation Slope 1 @ SP=500				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	0.000	0.000	0.000	0.973
		1.000	0.000	0.000	0.000	0.953
		1.000	1.000	0.000	* 0.000	0.975
		1.000	0.000	0.000	0.000	0.953
		1.000	0.000	0.000	0.000	0.970
						<b>Average 0.977</b>

		Daub 3 at scale of 3				
		On or Off Representation Slope 1 @ SP=500				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	0.000	0.000	0.000	0.975
		1.000	0.000	0.000	* 0.000	0.978
		* 0.000	0.000	0.000	0.000	0.973
		1.000	0.000	0.000	0.000	0.978
		1.000	0.000	0.000	0.000	0.958
						<b>Average 0.974</b>

On or Off slope 1 at different SP values

		Haar at scale of 3				
		On or Off Representation Slope 2 @ SP=50				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	* 0.000	0.000	0.000	0.000	0.988
		* 0.000	* 0.000	* 0.000	0.000	0.983
		* 0.000	0.000	0.000	0.000	0.958
		* 0.000	0.000	0.000	0.000	0.965
		* 0.000	* 0.000	* 0.000	0.000	0.973
						<b>Average 0.988</b>

		Daub 3 at scale of 3				
		On or Off Representation Slope 2 @ SP=50				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	* 0.000	* 0.000	0.000	0.000	0.988
		* 0.000	* 0.000	* 0.000	0.000	0.983
		* 0.000	* 0.000	0.000	0.000	0.963
		* 0.000	* 0.000	* 0.000	0.000	0.975
		* 0.000	* 0.000	0.000	0.000	0.958
						<b>Average 0.968</b>

		Haar at scale of 3				
		On or Off Representation Slope 2 @ SP=100				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	* 0.000	* 0.000	0.000	0.000	0.971
		* 0.000	* 0.000	1.000	1.000	0.970
		* 0.000	0.000	1.000	1.000	0.973
		* 0.000	* 0.000	1.000	1.000	0.974
		0.000	* 0.000	1.000	0.000	0.953
						<b>Average 0.970</b>

		Daub 3 at scale of 3				
		On or Off Representation Slope 2 @ SP=100				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	* 0.000	1.000	0.000	0.000	0.981
		* 0.000	* 0.000	1.000	0.000	0.968
		1.000	0.000	0.000	1.000	0.976
		* 0.000	1.000	0.000	0.000	0.978
		0.000	1.000	1.000	1.000	0.958
						<b>Average 0.967</b>

		Haar at scale of 3				
		On or Off Representation Slope 2 @ SP=500				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	1.000	0.000	0.000	0.988
		1.000	1.000	1.000	1.000	0.988
		1.000	0.000	1.000	1.000	0.988
		1.000	0.000	1.000	0.000	0.978
		0.000	0.000	1.000	1.000	0.958
						<b>Average 0.988</b>

		Daub 3 at scale of 3				
		On or Off Representation Slope 2 @ SP=500				
TC	NTC	a1	a2	a3	a4	Separation
3.000	25.000	1.000	1.000	1.000	0.000	0.981
		1.000	1.000	1.000	* 0.000	0.985
		1.000	0.000	0.000	0.000	0.975
		1.000	1.000	0.000	0.000	0.976
		1.000	0.000	0.000	* 0.000	0.958
						<b>Average 0.967</b>

On or Off slope 2 at different SP values





**Target Class= 1 Non Target Class =5  
Haar & Daubechies 3 Wavelets**

Haar at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	1.250	0.000	1.000	0.250
		1.250	0.250	1.000	0.000	0.250
		1.250	0.250	0.000	0.000	0.250
		1.250	0.250	1.000	0.000	0.250
		1.250	0.250	0.000	1.000	0.250
		1.250	0.250	0.000	0.000	0.250
		Average				0.250

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.000	0.250	0.000	1.000	0.250
		1.250	0.250	0.000	1.000	0.250
		1.250	0.250	0.000	0.000	0.250
		1.250	0.250	0.000	0.000	0.250
		1.250	0.250	0.000	0.000	0.250
		1.250	0.250	0.000	0.000	0.250
		Average				0.250

Haar at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	0.250	0.000	1.000	0.250
		1.250	0.000	0.000	1.000	0.250
		1.250	0.000	0.000	0.000	0.250
		1.250	0.000	1.000	1.000	0.250
		1.250	0.000	0.000	0.000	0.250
		1.250	0.000	0.000	0.000	0.250
		Average				0.250

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	0.250	0.000	1.000	0.250
		1.250	0.250	0.000	1.000	0.250
		1.250	0.250	0.000	1.000	0.250
		1.250	0.250	0.000	0.000	0.250
		1.250	0.250	0.000	0.000	0.250
		1.250	0.250	0.000	0.000	0.250
		Average				0.250

Haar at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	0.000	0.000	1.000	0.250
		1.250	0.000	0.000	1.000	0.250
		1.250	0.000	0.000	1.000	0.250
		1.250	0.000	1.000	0.000	0.250
		1.250	0.000	1.000	0.000	0.250
		1.250	0.000	0.000	0.000	0.250
		Average				0.250

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	0.000	0.000	1.000	0.250
		1.250	0.000	0.000	1.000	0.250
		1.250	0.000	0.000	0.000	0.250
		1.250	0.000	1.000	0.000	0.250
		1.250	0.000	1.000	0.000	0.250
		1.250	0.000	0.000	0.000	0.250
		Average				0.250

On or Off slope 1 at different SP values

Haar at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	a2	d2	d3	Standard
1.000	5.000	1.000	0.000	1.000	0.000	0.250
		1.000	0.000	1.000	0.000	0.250
		1.000	1.000	1.000	0.000	0.250
		1.000	0.000	1.000	0.000	0.250
		1.000	1.000	0.000	0.000	0.250
		1.000	1.000	0.000	0.000	0.250
		Average				0.250

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	0.250	0.000	1.250	0.250
		1.250	0.250	0.000	1.250	0.250
		1.250	0.250	0.000	1.250	0.250
		1.250	0.250	0.000	1.250	0.250
		1.250	0.250	0.000	1.250	0.250
		1.250	0.250	0.000	1.250	0.250
		Average				0.250

Haar at scale of 1						
On or Off Representation Slope 2 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.000	1.000	1.000	0.000	0.250
		1.000	0.000	0.000	0.000	0.250
		1.000	0.000	0.000	0.000	0.250
		1.000	0.000	0.000	1.000	0.250
		1.000	0.000	1.000	0.000	0.250
		1.000	0.000	1.000	0.000	0.250
		Average				0.250

Daub 3 at scale of 1						
On or Off Representation Slope 2 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	1.250	0.000	1.000	0.250
		1.250	1.250	0.000	1.000	0.250
		1.250	0.250	1.250	1.000	0.250
		1.250	1.250	1.000	0.000	0.250
		1.250	0.250	0.250	1.000	0.250
		1.250	0.250	0.250	1.000	0.250
		Average				0.250

Haar at scale of 1						
On or Off Representation Slope 2 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.000	1.000	1.250	0.000	0.250
		1.000	1.000	1.250	1.250	0.250
		1.000	1.000	1.250	1.250	0.250
		1.000	0.000	1.250	1.250	0.250
		1.000	0.000	1.250	1.250	0.250
		1.000	0.000	1.250	1.250	0.250
		Average				0.250

Daub 3 at scale of 1						
On or Off Representation Slope 2 @ SP=100						
TC	NTC	a1	d1	d2	d3	Standard
1.000	5.000	1.250	0.000	0.000	2.000	0.250
		1.250	0.250	1.000	1.000	0.250
		1.250	1.000	1.000	1.000	0.250
		1.250	1.000	1.000	1.000	0.250
		1.250	1.000	1.000	1.000	0.250
		1.250	1.000	1.000	1.000	0.250
		Average				0.250

On or Off slope 2 at different SP values

**Target Class= 1 Non Target Class =16  
Haar & Daubechies 3 Wavelets**

Haar at scale of 3					
On or Off Representation Slope 1 @ SP=0					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	1.000	1.000	0.988
		1.000	0.000	1.000	0.989
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.991
		Average			0.989

Daub 3 at scale of 3					
On or Off Representation Slope 1 @ SP=0					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	1.000	0.000	0.988
		1.000	1.000	0.000	0.989
		1.000	1.000	0.000	0.990
		1.000	1.000	0.000	0.990
		1.000	1.000	0.000	0.990
		1.000	1.000	0.000	0.991
		Average			0.989

Haar at scale of 3					
On or Off Representation Slope 1 @ SP=10					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	1.000	0.988
		1.000	0.000	1.000	0.989
		1.000	0.000	1.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.989

Daub 3 at scale of 3					
On or Off Representation Slope 1 @ SP=10					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	1.000	0.988
		1.000	0.000	1.000	0.989
		1.000	0.000	1.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.989

Haar at scale of 3					
On or Off Representation Slope 1 @ SP=50					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	1.000	0.987
		1.000	0.000	0.000	0.989
		1.000	0.000	1.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.989

Daub 3 at scale of 3					
On or Off Representation Slope 1 @ SP=50					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	1.000	0.987
		1.000	0.000	0.000	0.989
		1.000	0.000	1.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.989

On or Off slope 1 at different SP values

Haar at scale of 3					
On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	1.000	0.987
		1.000	0.000	0.000	0.988
		1.000	0.000	1.000	0.989
		1.000	0.000	0.000	0.990
		1.000	0.000	1.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.988

Daub 3 at scale of 3					
On or Off Representation Slope 1 @ SP=100					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	1.000	0.000	0.988
		0.000	1.000	0.000	0.989
		0.000	0.000	1.000	0.990
		1.000	1.000	0.000	0.990
		0.000	0.000	0.000	0.991
		0.000	0.000	1.000	0.991
		Average			0.989

Haar at scale of 3					
On or Off Representation Slope 2 @ SP=10					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	0.000	0.987
		1.000	0.000	0.000	0.989
		1.000	0.000	0.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	0.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.987

Daub 3 at scale of 3					
On or Off Representation Slope 2 @ SP=10					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	0.000	0.987
		1.000	0.000	0.000	0.989
		1.000	0.000	0.000	0.990
		1.000	0.000	0.000	0.990
		1.000	0.000	0.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.987

Haar at scale of 3					
On or Off Representation Slope 2 @ SP=50					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	0.000	0.986
		1.000	0.000	0.000	0.988
		1.000	0.000	0.000	0.989
		1.000	0.000	0.000	0.990
		1.000	0.000	0.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.987

Daub 3 at scale of 3					
On or Off Representation Slope 2 @ SP=50					
TC	NTC	a1	a2	a3	Standard
1.000	16.000	1.000	0.000	0.000	0.986
		1.000	0.000	0.000	0.988
		1.000	0.000	0.000	0.989
		1.000	0.000	0.000	0.990
		1.000	0.000	0.000	0.991
		1.000	0.000	0.000	0.991
		Average			0.988

On or Off slope 2 at different SP values

Target Class= 1 Non Target Class =17  
Haar & Daubechies 3 Wavelets

Table 1: Haar 1

W	SP	d1	d2	d3	Average
1.00	0.00	0.00	1.25	1.25	0.887
1.50	0.00	0.80	1.20	1.20	0.776
1.00	0.00	0.00	2.25	2.25	0.772
1.50	0.00	0.00	2.00	2.00	0.774
Average	0.00	0.00	1.60	1.60	0.814

Table 2: Haar 2

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.20	1.20	0.767
1.50	0.00	1.00	1.00	1.00	0.834
1.00	0.00	1.00	1.00	1.00	0.814
1.50	0.00	1.00	1.00	1.00	0.792
Average	0.00	1.10	1.10	1.10	0.801

Table 3: Haar 3

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.00	1.00	0.767
1.50	0.00	1.20	1.00	1.00	0.829
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.848
Average	0.00	1.10	1.00	1.00	0.844

Table 4: Haar 4

W	SP	d1	d2	d3	Average
1.00	0.00	1.00	1.00	1.00	0.814
1.50	0.00	1.00	1.00	1.00	0.863
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.822
Average	0.00	1.00	1.00	1.00	0.840

Table 5: Haar 5

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.20	1.20	0.767
1.50	0.00	1.20	1.20	1.20	0.829
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.848
Average	0.00	1.10	1.10	1.10	0.844

Table 6: Haar 6

W	SP	d1	d2	d3	Average
1.00	0.00	1.00	1.00	1.00	0.814
1.50	0.00	1.00	1.00	1.00	0.863
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.822
Average	0.00	1.00	1.00	1.00	0.840

On or Off slope 1 at different SP values

Table 7: Haar 1

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.00	1.00	0.887
1.50	0.00	1.20	1.00	1.00	0.776
1.00	0.00	1.00	1.00	1.00	0.772
1.50	0.00	1.00	1.00	1.00	0.774
Average	0.00	1.10	1.00	1.00	0.814

Table 8: Haar 2

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.20	1.20	0.767
1.50	0.00	1.20	1.20	1.20	0.829
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.848
Average	0.00	1.10	1.10	1.10	0.844

Table 9: Haar 3

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.00	1.00	0.767
1.50	0.00	1.20	1.00	1.00	0.829
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.848
Average	0.00	1.10	1.00	1.00	0.844

Table 10: Haar 4

W	SP	d1	d2	d3	Average
1.00	0.00	1.00	1.00	1.00	0.814
1.50	0.00	1.00	1.00	1.00	0.863
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.822
Average	0.00	1.10	1.00	1.00	0.840

Table 11: Haar 5

W	SP	d1	d2	d3	Average
1.00	0.00	1.20	1.00	1.00	0.887
1.50	0.00	1.20	1.00	1.00	0.776
1.00	0.00	1.00	1.00	1.00	0.772
1.50	0.00	1.00	1.00	1.00	0.774
Average	0.00	1.10	1.00	1.00	0.814

Table 12: Haar 6

W	SP	d1	d2	d3	Average
1.00	0.00	1.00	1.00	1.00	0.814
1.50	0.00	1.00	1.00	1.00	0.863
1.00	0.00	1.00	1.00	1.00	0.848
1.50	0.00	1.00	1.00	1.00	0.822
Average	0.00	1.10	1.00	1.00	0.840

On or Off slope 2 at different SP values

Target Class= 1 Non Target Class =20  
Haar & Daubechies 3 Wavelets

Haar at scale of 1						
On or Off Representation Slope 1 @ SP= 10						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	1.000	1.000	0.976
		1.000	0.000	1.000	0.000	0.983
		1.000	0.000	0.000	1.000	0.985
		1.000	1.000	0.000	0.000	0.970
		1.000	1.000	0.000	0.000	0.982
Average						0.983

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP= 10						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	1.000	0.000	0.000	0.976
		1.000	1.000	0.000	0.000	0.982
		1.000	1.000	0.000	0.000	0.973
		1.000	1.000	0.000	1.000	0.960
		1.000	1.000	0.000	1.000	0.979
Average						0.981

Haar at scale of 1						
On or Off Representation Slope 1 @ SP= 100						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.973
		1.000	0.000	0.000	0.000	0.983
		1.000	0.000	1.000	1.000	0.970
		1.000	1.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.973
Average						0.981

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP= 100						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.980
		1.000	0.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.976
		1.000	0.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.985
Average						0.984

Haar at scale of 1						
On or Off Representation Slope 1 @ SP= 1000						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	1.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.985
		1.000	1.000	0.000	0.000	0.985
		1.000	0.000	1.000	0.000	0.985
		1.000	0.000	0.000	1.000	0.985
Average						0.985

Daub 3 at scale of 1						
On or Off Representation Slope 1 @ SP= 1000						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	1.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.985
		1.000	0.000	0.000	0.000	0.985
Average						0.985

On or Off slope 1 at different SP values

Haar at scale of 1						
On or Off Representation Slope 2 @ SP= 10						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.982
		1.000	0.000	1.000	0.000	0.982
		1.000	0.000	1.000	0.000	0.984
		1.000	0.000	1.000	0.000	0.982
		1.000	0.000	1.000	0.000	0.984
Average						0.985

Daub 3 at scale of 1						
On or Off Representation Slope 2 @ SP= 10						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.982
Average						0.982

Haar at scale of 1						
On or Off Representation Slope 2 @ SP= 100						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.983
		1.000	0.000	0.000	0.000	0.984
		1.000	0.000	0.000	0.000	0.980
		1.000	0.000	0.000	0.000	0.981
		1.000	0.000	0.000	0.000	0.981
Average						0.983

Daub 3 at scale of 1						
On or Off Representation Slope 2 @ SP= 100						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.981
		1.000	0.000	0.000	0.000	0.982
		1.000	0.000	0.000	0.000	0.981
		1.000	0.000	0.000	0.000	0.981
Average						0.982

Haar at scale of 1						
On or Off Representation Slope 2 @ SP= 1000						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.981
		1.000	0.000	0.000	0.000	0.984
		1.000	0.000	0.000	0.000	0.980
		1.000	0.000	0.000	0.000	0.981
		1.000	0.000	0.000	0.000	0.981
Average						0.982

Daub 3 at scale of 1						
On or Off Representation Slope 2 @ SP= 1000						
TC	NTC	$\alpha^1$	$\alpha^2$	$\alpha^3$	$\alpha^4$	Separate
1.00	20.00	1.000	0.000	0.000	0.000	0.984
		1.000	0.000	0.000	0.000	0.984
		1.000	0.000	0.000	0.000	0.984
		1.000	0.000	0.000	0.000	0.984
		1.000	0.000	0.000	0.000	0.984
Average						0.984

On or Off slope 2 at different SP values





Target Class= 1 Non Target Class =31  
Haar & Daubechies 3 Wavelets

Haar wavelet				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	0.55	1.00
1.00	0.02	1.00	0.00	0.95
1.00	0.00	1.00	0.25	1.00
1.00	0.00	1.00	0.25	0.84
1.00	0.00	1.00	0.00	1.00
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.94
Average 0.94				

Haar wavelet				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	0.55	1.00
1.00	0.02	1.00	0.00	0.95
1.00	0.00	1.00	0.25	1.00
1.00	0.00	1.00	0.25	0.46
1.00	0.00	1.00	0.00	1.00
1.00	0.02	1.00	0.00	0.95
1.00	0.02	1.00	0.00	0.95
Average 0.95				

Haar wavelet				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	0.25	1.00
1.00	0.02	1.00	0.25	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
Average 1.00				

Haar wavelet				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	0.25	1.00
1.00	0.02	1.00	0.25	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
Average 1.00				

Haar wavelet				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.50	1.00
1.00	0.02	1.00	2.50	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
Average 1.00				

Haar wavelet				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	0.55	1.00
1.00	0.02	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.00	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
1.00	0.02	1.00	0.00	1.00
Average 0.99				

On or Off slope 1 at different SP values

Daubechies 3				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.00	0.94
1.00	0.02	1.00	0.00	0.94
1.00	0.00	1.00	0.00	0.87
1.00	0.00	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
Average 0.84				

Daubechies 3				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.00	0.94
1.00	0.02	1.00	0.00	0.94
1.00	0.00	1.00	0.00	0.87
1.00	0.00	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
Average 0.84				

Daubechies 3				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.00	0.94
1.00	0.02	1.00	0.00	0.94
1.00	0.00	1.00	0.00	0.87
1.00	0.00	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
Average 0.84				

Daubechies 3				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.00	0.94
1.00	0.02	1.00	0.00	0.94
1.00	0.00	1.00	0.00	0.87
1.00	0.00	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
Average 0.84				

Daubechies 3				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.00	0.94
1.00	0.02	1.00	0.00	0.94
1.00	0.00	1.00	0.00	0.87
1.00	0.00	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
Average 0.84				

Daubechies 3				
On or Off Representation Score (Q-Score)				
Q	SP	Q1	Q2	Average
1.00	0.02	1.00	1.00	0.94
1.00	0.02	1.00	0.00	0.94
1.00	0.00	1.00	0.00	0.87
1.00	0.00	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
1.00	0.02	1.00	0.00	0.84
Average 0.84				

On or Off slope 2 at different SP values



# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =10

Hair at scale 1						
TC	NTC	d1	d2	d3	d4	Signific
2.000	10.000	1	0	0	0	0.9962
		1	0	0	0	0.9962
		1	0	0	0	0.9962
		1	0	0	0	0.9962
		1	0	0	1	0.9962
Average						0.9962

Dau 1 at Scale 1						
TC	NTC	a1	d1	d2	d3	Signific
2.000	10.000	1	0	0	0	0.9902
		1	0	0	1	0.9973
		1	0	0	0	0.9910
		1	0	0	0	0.9959
		1	0	0	0	0.9942
Average						0.9917

Hair at scale 3						
TC	NTC	d1	d2	d3	d4	Signific
2.000	10.000	1	0	1	0	0.9878
		1	0	0	1	0.9857
		1	0	1	1	0.9832
		1	0	1	1	0.9854
		1	0	0	1	0.9874
Average						0.9858

Dau 2 at Scale 3						
TC	NTC	a1	d1	d2	d3	Signific
2.000	10.000	1	0	1	0	0.9818
		1	0	1	0	0.9837
		1	0	1	0	0.9830
		1	0	1	0	0.9868
		1	0	1	0	0.9890
Average						0.9867

Hair at scale 3						
TC	NTC	d1	d2	d3	d4	Signific
2.000	10.000	1	0	0	0	0.9880
		1	1	1	0	0.9820
		1	0	0	0	0.9874
		1	0	0	0	0.9874
		1	0	0	0	0.9867
Average						0.9850

Dau 1 at Scale 3						
TC	NTC	a1	d1	d2	d3	Signific
2.000	10.000	1	0	0	1	0.9835
		1	0	0	0	0.9825
		1	0	0	0	0.9858
		1	1	0	1	0.9825
		1	0	0	1	0.9878
Average						0.9854

Hair at Scale 2						
TC	NTC	d1	d2	d3	d4	Signific
2.000	10.000	1	0	0	0	0.9729
		1	0	0	0	0.9668
		1	0	0	0	0.9779
		1	0	0	0	0.9795
		1	0	0	0	0.9810
Average						0.9776

Dau 3 at Scale 3						
TC	NTC	a1	d1	d2	d3	Signific
2.000	10	1	1	0	0	0.9735
	10	1	0	0	0	0.9578
	10	1	0	0	0	0.9756
	10	1	0	0	0	0.9783
	10	1	0	0	0	0.9802
Average						0.9789

Hair at Scale 2						
TC	NTC	d1	d2	d3	d4	Signific
2.000	10.000	1	0	1	0	0.9787
		1	1	1	1	0.9916
		1	0	1	0	0.9803
		1	1	2	1	0.9808
		1	0	1	0	0.9872
Average						0.9827

Dau 1 at Scale 2						
TC	NTC	a1	d1	d2	d3	Signific
2.000	10	1	0	0	1	0.9802
		1	0	0	0	0.9804
		1	0	0	0	0.9792
		1	0	1	1	0.9802
		1	0	0	0	0.9878
Average						0.9835

Hair at Scale 2						
TC	NTC	d1	d2	d3	d4	Signific
2.000	10.000	1	0	1	1	0.9770
		1	1	1	1	0.9880
		1	0	1	0	0.9740
		1	0	1	0	0.9790
		1	0	1	1	0.9850

Dau 3 at Scale 2						
TC	NTC	a1	d1	d2	d3	Signific
2	10	1	1	0	0	0.9785
	10	1	0	0	0	0.9786
	10	1	0	0	0	0.9786
	10	1	0	0	0	0.9782
	10	1	0	0	0	0.9781

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =12

Level at Scale 0

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	0	0	0	0.9587
		1	0	0	0	0.9548
		1	0	0	0	0.9597
		1	0	0	0	0.9597
		1	0	0	0	0.9562
						<b>Average</b> 0.9620

Level 1 at Scale 0

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	0	0	0	0.9891
		1	0	0	0	0.9840
		1	0	0	0	0.9897
		1	0	0	0	0.9897
		1	0	0	0	0.9952
						<b>Average</b> 0.9920

Level at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	1	0	0	0.9530
		1	1	0	0	0.9541
		1	1	0	0	0.9507
		1	0	1	0	0.9576
		1	1	0	0	0.9549
						<b>Average</b> 0.9577

Level 2 at Scale 0

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	1	1	0	0.9658
		1	1	0	0	0.9687
		1	1	0	0	0.9685
		1	0	1	0	0.9670
		1	1	0	0	0.9670
						<b>Average</b> 0.9677

Level at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	0	1	0	0.9527
		1	0	0	0	0.9570
		1	0	0	0	0.9536
		1	0	0	1	0.9560
		1	0	0	1	0.9503
						<b>Average</b> 0.9560

Level 3 at Scale 0

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	0	0	0	0.9608
		1	0	0	0	0.9670
		1	0	0	1	0.9627
		1	0	1	1	0.9670
		1	0	1	0	0.9657
						<b>Average</b> 0.9649

Level 4 at Scale 0

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	0	0	0	1	0.9784
		0	0	0	0	0.9837
		0	1	0	0	0.9802
		0	0	0	0	0.9816
		0	0	0	0	0.9800
						<b>Average</b> 0.9816

Level 3 at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12	1	1	1	0	0.9756
	12	1	1	0	0	0.9314
	12	0	1	1	0	0.9800
	12	1	1	0	0	0.9827
	12	1	0	0	0	0.9800
						<b>Average</b> 0.9642

Level at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	0	0	1	0.9808
		1	0	1	0	0.9801
		0	1	1	0	0.9790
		1	0	0	0	0.9800
		1	1	0	0	0.9804
						<b>Average</b> 0.9806

Level 4 at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12	1	0	1	0	0.9758
		1	1	1	1	0.9811
		1	0	1	1	0.9757
		1	0	1	0	0.9802
		1	0	0	0	0.9802
						<b>Average</b> 0.9811

Level at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2.0000	12.0000	1	0	1	1	0.9500
		1	0	0	0	0.9613
		1	0	1	0	0.9750
		1	0	1	0	0.9600
		1	1	1	1	0.9670
						<b>Average</b> 0.9602

Level 5 at Scale 1

TC	NTC	a1	a1	a2	a3	Separator
2	12	1	0	0	1	0.9795
	12	0	0	0	0	0.9614
	12	0	0	0	0	0.9600
	12	0	0	0	0	0.9627
	12	0	0	0	0	0.9670
						<b>Average</b> 0.9642

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =13

Wavelet Scale 1						
On or Off Slope 1 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	1	0	0	0.9658
		1	5	0	0	0.9602
		1	1	5	0	0.9857
		1	5	5	0	0.9844
		1	0	5	0	0.9653
Average						0.9675

Wavelet Scale 1						
On or Off Slope 1 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	5	0	0	0.9628
		1	5	5	0	0.9923
		1	0	0	0	0.9687
		1	0	0	1	0.9644
		1	0	0	0	0.9603
Average						0.9676

Wavelet Scale 2						
On or Off Slope 1 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	5	5	0	0.9801
		1	1	1	1	0.9871
		1	1	1	1	0.9817
		1	1	0	1	0.9587
Average						0.9833

Wavelet Scale 2						
On or Off Slope 1 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	0	0	5	0.9790
		1	1	0	0	0.9707
		1	1	0	0	0.9871
		1	1	1	1	0.9817
		1	1	0	1	0.9857
Average						0.9833

Wavelet Scale 2						
On or Off Slope 1 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	0	0	0	0.9788
		1	1	1	1	0.9779
		1	0	0	1	0.9817
		1	0	1	0	0.9755
		1	1	0	0	0.9828
Average						0.9786

Wavelet Scale 2						
On or Off Slope 1 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	0	1	0	0.9774
		1	0	1	0	0.9771
		1	0	1	1	0.9817
		1	0	1	0	0.9792
		1	0	1	1	0.9817
Average						0.9796

Wavelet Scale 3						
On or Off Slope 2 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	0	0	0	0.9774
		1	0	0	0	0.9705
		1	0	0	0	0.9801
		1	0	0	1	0.9782
		1	0	0	0	0.9780
Average						0.9784

Wavelet Scale 3						
On or Off Slope 2 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13	1	0	1	0	0.9820
	13	1	0	0	0	0.9811
	13	1	0	5	1	0.9826
	13	1	0	0	0	0.9779
	13	1	0	0	0	0.9730
Average						0.9796

Wavelet Scale 3						
On or Off Slope 2 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	5	0	0	0.9822
		0	1	1	0	0.9812
		1	0	0	0	0.9871
		0	1	1	0	0.9750
		1	0	0	5	0.9822
Average						0.9899

Wavelet Scale 3						
On or Off Slope 2 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13	1	1	0	0	0.9822
	13	1	1	0	0	0.9779
	13	1	1	1	0	0.9870
	13	1	1	1	0	0.9788
	13	1	5	1	0	0.9862
Average						0.9823

Wavelet Scale 3						
On or Off Slope 2 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2.000	13.000	1	1	0	0	0.9730
		0	1	1	0	0.9730
		1	0	1	1	0.9820
		0	0	5	1	0.9752
		0	1	0	1	0.9800
Average						0.9671

Wavelet Scale 3						
On or Off Slope 2 @ SF=10						
TC	NTC	a1	d1	d2	d3	Separation
2	13	1	5	1	0	0.9806
	13	1	5	0	0	0.9501
	13	1	0	0	1	0.9806
	13	1	1	1	0	0.9779
	13	1	0	0	0	0.9700
Average						0.9794

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =18

Wavelet at scale 1  
On or Off Slope 1 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	0	0	0.9808
		1	0	0	0	0.9873
		1	0	0	0	0.9730
		1	0	0	0	0.9830
		1	0	0	0	0.9822
		Average				0.9844

Wavelet at Scale of 1  
On or Off Slope 1 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	0	0	0.9802
		1	0	0	0	0.9833
		1	0	0	0	0.9790
		1	0	0	0	0.9830
		1	0	0	0	0.9822
		Average				0.9844

Wavelet at scale 2  
On or Off Slope 2 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	1	1	0	0.9744
		1	1	0	1	0.9629
		1	0	0	0	0.9619
		1	0	0	0	0.9723
		1	1	0	0	0.9613
		Average				0.9670

Wavelet at Scale of 2  
On or Off Slope 2 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	1	1	0	0.9707
		1	1	0	0	0.9631
		1	0	0	1	0.9629
		1	0	0	0	0.9727
		1	0	0	1	0.9600
		Average				0.9678

Wavelet at scale 3  
On or Off Slope 3 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	1	1	0	0.9748
		1	1	0	1	0.9620
		1	0	0	0	0.9608
		1	0	0	1	0.9729
		1	1	0	0	0.9643
		Average				0.9688

Wavelet at Scale of 3  
On or Off Slope 3 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	1	1	0	0.9744
		1	1	0	1	0.9624
		1	0	0	0	0.9646
		1	0	0	1	0.9719
		1	1	0	0	0.9628
		Average				0.9678

Wavelet at Scale of 5  
On or Off Slope 5 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	1	0	0.9888
		1	0	0	0	0.9897
		1	0	1	0	0.9746
		1	0	1	0	0.9804
		1	0	0	0	0.9712
		Average				0.9774

Wavelet at Scale of 5  
On or Off Slope 5 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	1	0	0.9884
		1	0	0	0	0.9712
		1	0	1	0	0.9780
		1	0	1	0	0.9876
		1	0	1	0	0.9754
		Average				0.9797

Wavelet at Scale of 1  
On or Off Slope 2 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	1	1	0.9871
		1	0	1	0	0.9882
		1	0	0	0	0.9827
		1	0	0	1	0.9850
		1	0	1	0	0.9855
		Average				0.9851

Wavelet at Scale of 1  
On or Off Slope 2 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	0	1	0.9877
		1	0	1	0	0.9880
		1	0	0	0	0.9830
		1	0	0	1	0.9830
		1	0	0	0	0.9843
		Average				0.9843

Wavelet at Scale of 2  
On or Off Slope 2 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	0	0	0.9760
		1	0	0	0	0.9530
		1	1	1	0	0.9830
		1	0	0	1	0.9710
		1	1	0	0	0.9811
		Average				0.9688

Wavelet at Scale of 2  
On or Off Slope 2 @ SP=10

TC	NTC	a1	a1	a2	a3	Support
2000	15000	1	0	1	0	0.9884
		1	0	1	0	0.9812
		1	0	1	0	0.9780
		1	0	1	0	0.9827
		1	0	1	0	0.9854
		Average				0.9797

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =21

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9959
		0	0	0	0	0.9960
		0	0	0	0	0.9961
		0	0	0	0	1.0000
		0	0	0	0	0.9960
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		0	0	0	0	0.9961
		0	0	0	0	0.9962
		0	0	0	0	1.0000
		0	0	0	0	0.9960
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2	21	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2	21	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2.000	21.000	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

Hair at scale 3		On or Off Representation Slope 1 @ No SP				
TC	NTC	a1	a2	a3	a4	Separability
2	21	1	0	0	0	0.9960
		1	0	0	0	0.9961
		1	0	0	0	0.9962
		1	0	0	0	0.9963
		1	0	0	0	0.9964
		1	0	0	0	0.9965
		Average				0.9960

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =22

		Haar at scale 1				
TC	NTC	Order Of Slope 1 @ SP=0				SeprIndex
2.0000	22.0000	1	0	0	0	0.9404
		1	0	0	0	0.9359
		1	0	0	0	0.9264
		1	0	0	0	0.9535
		1	0	0	0	0.9711
		Average				0.9667

		Daub 3 at Scale of 3				
TC	NTC	Order Of Slope 1 @ No SP				SeprIndex
2.0000	22.0000	-	0	0	0	0.9254
		-	0	0	0	0.9459
		-	0	0	0	0.9284
		-	0	0	0	0.9435
		-	0	0	0	0.9511
		Average				0.9467

		Haar at scale 3				
TC	NTC	Order Of Slope 1 @ SP=0				SeprIndex
2	22	1	0	0	0	0.9705
		-	0	0	-	0.9705
		-	0	1	-	0.9703
		-	0	0	-	0.9713
		-	0	0	-	0.9729
		Average				0.9726

		Daub 3 at Scale of 5				
TC	NTC	Order Of Slope 1 @ SP=0				SeprIndex
2.0000	22.0000	-	1	1	1	0.9300
		-	1	0	1	0.9350
		-	1	1	1	0.9304
		-	1	0	0	0.9304
		-	0	0	1	0.9300
		Average				0.9300

		Haar at scale 3				
TC	NTC	Order Of Slope 1 @ SP=0				SeprIndex
2.0000	22.0000	1	0	0	0	0.9709
		-	0	0	1	0.9710
		-	0	1	0	0.9703
		-	1	0	1	0.9713
		-	0	0	0	0.9729
		Average				0.9720

		Daub 3 at Scale of 3				
TC	NTC	Order Of Slope 1 @ SP=0				SeprIndex
2	22	1	1	0	0	0.9765
		1	1	0	1	0.9714
		1	1	0	0	0.9709
		1	1	0	0	0.9729
		1	0	1	0	0.9724
		Average				0.9732

		Haar at Scale of 3				
TC	NTC	Order Of Slope 2 @ No SP				SeprIndex
2.0000	22.0000	-	0	0	0	0.9254
		-	0	0	0	0.9459
		-	0	0	0	0.9284
		-	0	0	0	0.9435
		-	0	0	0	0.9511
		Average				0.9415

		Daub 3 at Scale of 3				
TC	NTC	Order Of Slope 2 @ No SP				SeprIndex
2.0000	22	1	1	1	0	0.9408
	22	1	0	1	0	0.9391
	22	1	0	0	0	0.9397
	22	1	1	0	0	0.9390
	22	1	1	1	0	0.9375
		Average				0.9418

		Haar at Scale of 3				
TC	NTC	Order Of Slope 2 @ SP=0				SeprIndex
2.0000	22.0000	-	0	1	1	0.9408
		-	0	1	1	0.9404
		-	0	0	0	0.9408
		-	0	0	0	0.9393
		-	0	0	0	0.9407
		Average				0.9404

		Daub 3 at Scale of 3				
TC	NTC	Order Of Slope 2 @ SP=0				SeprIndex
2.0000	22	-	0	0	0	0.9404
		-	0	0	-	0.9571
		-	0	0	0	0.9574
		-	1	1	-	0.9703
		-	0	0	0	0.9507
		Average				0.9488

		Haar at Scale of 3				
TC	NTC	Order Of Slope 2 @ SP=0				SeprIndex
2.0000	22.0000	1	0	0	0	0.9703
		1	0	0	1	0.9660
		1	0	1	0	0.9620
		1	0	0	0	0.9670
		1	0	0	1	0.9650
		Average				0.9668

		Daub 3 at Scale of 1				
TC	NTC	Order Of Slope 2 @ SP=0				SeprIndex
2	22	-	0	1	0	0.9703
		1	1	1	-	0.9570
		1	0	0	0	0.9035
		-	0	0	0	0.9667
		-	0	0	0	0.9650
		Average				0.9667

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =30

Haar at Scale 0

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9857
		1	0	0	0	0.9257
		1	0	0	0	0.9494
		1	0	0	0	0.9547
		1	0	0	0	0.9872
Average						0.9662

Daube at Scale 0

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9857
		1	0	0	0	0.9857
		1	0	0	0	0.9894
		1	0	0	0	0.9911
		1	0	0	0	0.9976
Average						0.9962

Haar at scale 1

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9895
		1	0	0	0	0.9894
		1	0	0	0	0.9799
		1	0	0	0	0.9899
		1	0	0	0	0.9899
Average						0.9795

Daube at Scale 1

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9976
		1	0	0	0	0.9938
		1	0	0	0	0.9809
		1	0	0	0	0.9799
		1	0	0	0	0.9751
Average						0.9797

Haar at scale 2

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9875
		1	0	0	0	0.9754
		1	0	0	0	0.9759
		1	0	0	0	0.9788
		1	0	0	0	0.9759
Average						0.9799

Daube at Scale 2

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9915
		1	0	0	0	0.9757
		1	0	0	0	0.9782
		1	0	0	0	0.9772
		1	0	0	0	0.9757
Average						0.9752

Haar at Scale 3

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9894
		1	0	0	0	0.9894
		1	0	0	0	0.9899
		1	0	0	0	0.9899
		1	0	0	0	0.9899
Average						0.9899

Daube at Scale 3

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9909
		1	0	0	0	0.9856
		1	0	0	0	0.9894
		1	0	0	0	0.9894
		1	0	0	0	0.9894
Average						0.9899

Haar at Scale 4

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9794
		1	0	0	0	0.9794
		1	0	0	0	0.9799
		1	0	0	0	0.9799
		1	0	0	0	0.9799
Average						0.9794

Daube at Scale 4

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9792
		1	0	0	0	0.9792
		1	0	0	0	0.9794
		1	0	0	0	0.9794
		1	0	0	0	0.9794
Average						0.9777

Haar at Scale 5

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9799
		1	0	0	0	0.9799
		1	0	0	0	0.9799
		1	0	0	0	0.9799
		1	0	0	0	0.9799
Average						0.9792

Daube at Scale 5

TC	NTC	a1	a1'	a2	a2'	Separation
20000	300000	1	0	0	0	0.9792
		1	0	0	0	0.9792
		1	0	0	0	0.9794
		1	0	0	0	0.9794
		1	0	0	0	0.9794
Average						0.9761

# Sparse features with Wavelets on On or Off representations

Target Class= 2 Non Target Class =31

Hear at Scale 1						
On or Off Slope 1 @ No SP						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	1	0	0	0.9900
Average						0.9907

Hear at Scale 1						
On or Off Slope 1 @ No SP						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	1.0000
		1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	0	0	0	0.9900
		1	1	0	0	1.0000
Average						0.9907

Hear at Scale 2						
On or Off Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Sepr index
2	31	1	0	0	0	0.9922
		1	0	0	0	0.9918
		1	0	0	0	0.9918
		1	0	0	0	0.9958
		1	0	0	0	0.9918
		1	0	0	0	0.9918
Average						0.9907

Hear at Scale 2						
On or Off Slope 1 @ SP=100						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	0.9710
		1	0	0	0	0.9656
		1	0	0	0	0.9742
		1	0	0	0	0.9656
		1	0	0	0	0.9654
		1	0	0	0	0.9654
Average						0.9661

Hear at Scale 1						
On or Off Slope 1 @ SP=80						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	0.9922
		1	0	0	0	0.9940
		1	0	0	0	0.9938
		1	0	0	0	0.9985
		1	0	0	0	0.9985
		1	0	0	0	0.9985
Average						0.9907

Hear at Scale 1						
On or Off Slope 1 @ SP=80						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	0.9930
		1	0	0	0	0.9947
		1	0	0	0	0.9976
		1	0	0	0	0.9903
		1	0	0	0	0.9930
		1	0	0	0	0.9930
Average						0.9916

Hear at Scale 1						
On or Off Slope 2 @ No SP						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	0.9948
		1	0	0	0	0.9975
		1	0	0	0	0.9928
		1	0	0	0	0.9917
		1	0	0	0	0.9901
		1	0	0	0	0.9901
Average						0.9910

Hear at Scale 1						
On or Off Slope 2 @ No SP						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31	1	0	0	0	0.9945
		1	0	0	0	0.9976
		1	0	0	0	0.9900
		1	0	0	0	0.9922
		1	0	0	0	0.9982
		1	0	0	0	0.9982
Average						0.9940

Hear at Scale 3						
On or Off Slope 2 @ SP=100						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31.000	1	0	0	0	0.9988
		1	0	0	0	0.9988
		1	0	0	0	0.9988
		1	0	0	0	0.9988
		1	0	0	0	0.9988
		1	0	0	0	0.9988
Average						0.9988

Hear at Scale 3						
On or Off Slope 2 @ SP=100						
TC	NTC	a1	d1	d2	d3	Sepr index
2.000	31	1	0	0	0	0.9949
		1	0	0	0	0.9936
		1	0	0	0	0.9945
		1	0	0	0	0.9940
		1	0	0	0	0.9940
		1	0	0	0	0.9936
Average						0.9939

Hear at Scale 2						
On or Off Slope 2 @ SP=80						
TC	NTC	a1	d1	d2	d3	Sepr index
2	31	1	0	0	0	0.9926
		1	0	0	0	0.9917
		1	0	0	0	0.9940
		1	0	0	0	0.9940
		1	0	0	0	0.9912
		1	0	0	0	0.9912
Average						0.9927

Hear at Scale 2						
On or Off Slope 2 @ SP=80						
TC	NTC	a1	d1	d2	d3	Sepr index
2	31	1	0	0	0	0.9912
		1	0	0	0	0.9899
		1	0	0	0	0.9922
		1	0	0	0	0.9917
		1	0	0	0	0.9900
		1	0	0	0	0.9900
Average						0.9904

## Appendix G

### Sparse features with Wavelets on Absorption representation

#### Target Class= 1 vs Non Target Classes Haar & Daubechies 3 Wavelets

Haar at scale of 3 Absorption Representation						
TC	NTC	a1	a1'	a2	a3	Separator
1	0	1	1	-	0	0.9834
		1	1	-	0	0.9801
		0	1	0	0	0.9758
		1	0	-	-	0.9720
		0	1	0	0	0.9728
Average						0.9707

Daub 3 at scale of 3 Absorption Representation						
TC	NTC	a1	a1'	a2	a3	Separator
10020	0	1	0	-	0	0.9634
		1	0	-	0	0.9651
		1	0	-	0	0.9728
		1	1	0	0	0.9720
		1	1	0	0	0.9728
Average						0.9701

TC	NTC	a1	a1'	a2	a3	Separator
1	15	0	1	0	-	0.9500
		1	1	0	0	0.9702
		1	0	0	-	0.9800
		0	1	-	0	0.9804
		0	1	0	0	0.9811
Average						0.9719

TC	NTC	a1	a1'	a2	a3	Separator
1	15	1	0	-	1	0.9661
		1	0	0	0	0.9800
		1	0	-	0	0.9800
		1	0	0	0	0.9800
		1	1	-	0	0.9807
Average						0.9721

TC	NTC	a1	a1'	a2	a3	Separator
1	17	1	1	-	0	0.9660
		1	1	-	0	0.9845
		1	0	-	-	0.9872
		1	0	0	0	0.9872
		1	1	0	0	0.9880
Average						0.9888

TC	NTC	a1	a1'	a2	a3	Separator
1	17	1	1	-	0	0.9860
		1	0	0	0	0.9842
		1	0	-	0	0.9872
		1	1	0	1	0.9885
		1	1	0	0	0.9842
Average						0.9898

TC	NTC	a1	a1'	a2	a3	Separator
1	20	1	1	-	-	0.9865
		1	0	0	-	0.9890
		1	0	1	-	0.9895
		1	0	1	-	0.9900
		1	1	0	-	0.9900
Average						0.9902

TC	NTC	a1	a1'	a2	a3	Separator
1	20	1	1	-	1	0.9865
		1	0	0	0	0.9895
		1	0	0	1	0.9900
		1	0	0	1	0.9900
		1	1	0	0	0.9900
Average						0.9902

TC	NTC	a1	a1'	a2	a3	Separator
1	21	1	0	-	-	0.9813
		1	0	1	0	0.9813
		0	0	1	-	0.9871
		1	1	1	-	0.9823
		0	0	1	0	0.9790
Average						0.9850

TC	NTC	a1	a1'	a2	a3	Separator
1	21	1	0	-	-	0.9813
		1	0	0	1	0.9871
		1	0	0	1	0.9823
		1	0	0	1	0.9823
		1	0	0	1	0.9823
Average						0.9890

TC	NTC	a1	a1'	a2	a3	Separator
1	26	0	0	1	-	1.0000
		1	0	1	0	1.0000
		0	1	0	-	1.0000
		0	1	1	-	1.0000
		1	0	1	-	1.0000
Average						1.0000

TC	NTC	a1	a1'	a2	a3	Separator
1	26	1	0	-	0	1.0000
		1	0	-	0	1.0000
		1	1	-	0	1.0000
		1	1	-	0	1.0000
		1	0	1	0	1.0000
Average						1.0000

TC	NTC	a1	a1'	a2	a3	Separator
1	31	0	1	-	-	1.0000
		1	1	0	-	1.0000
		0	0	1	-	1.0000
		0	1	1	-	1.0000
		1	0	1	0	1.0000
Average						1.0000

TC	NTC	a1	a1'	a2	a3	Separator
1	31	1	1	0	1	1.0000
		1	0	-	1	1.0000
		1	1	0	0	1.0000
		1	0	0	0	1.0000
		1	0	0	0	1.0000
Average						1.0000

TC	NTC	a1	a1'	a2	a3	Separator
1	15	1	1	1	0	0.9833
		1	1	-	-	0.9745
		1	0	0	0	0.9883
		1	0	0	-	0.9745
		1	1	0	0	0.9876
Average						0.9816

TC	NTC	a1	a1'	a2	a3	Separator
1	15	1	0	0	0	0.9833
		1	1	-	1	0.9745
		1	0	0	1	0.9883
		1	1	-	1	0.9745
		1	1	0	0	0.9876
Average						0.9816

Target Class 1 vs Non Target Classes using the Absorption Representation

**Target Class= 2 vs Non Target Classes  
Absorption Representation  
Haar & Daubechies 3 Wavelets**

Level 3 of scale 1						
Absorption Representation						
TC	NTC	a1	a1	a2	a3	Separation
2	TC	0	C	1	0	0.9870
		0	C	1	-	0.9965
		0	C	1	C	0.9963
		C	C	1	C	0.9973
		0	1	0	-	0.9884
					<b>Average</b>	<b>0.9878</b>

Level 3 of scale 2						
Absorption Representation						
TC	NTC	a1	a1	a2	a3	Separation
2	0	1	1	C	1	C.9910
		1	1	-	1	C.9921
		1	1	0	0	C.9881
		1	1	1	0	C.9897
		1	0	0	1	C.9902
					<b>Average</b>	<b>0.9886</b>

TC	NTC	a1	a1	a2	a3	Separation
2	12	0	0	1	C	0.9807
		C	0	1	C	0.9908
		0	0	1	C	0.9963
		C	1	0	C	0.9957
		0	0	-	1	0.9954
					<b>Average</b>	<b>0.9946</b>

TC	NTC	a1	a1	a2	a3	Separation
2	12	0	-	1	0	0.9876
		0	-	0	0	0.9897
		0	-	0	0	0.9880
		0	-	0	0	0.9908
		0	-	0	0	0.9910
					<b>Average</b>	<b>0.9892</b>

TC	NTC	a1	a1	a2	a3	Separation
2	13	0	0	-	0	0.9902
		C	0	-	0	0.9957
		0	1	0	0	0.9953
		0	0	-	0	0.9914
		0	0	-	1	0.9852
					<b>Average</b>	<b>0.9871</b>

TC	NTC	a1	a1	a2	a3	Separation
2	10	0	-	0	0	0.9852
		0	-	0	0	0.9903
		1	-	1	0	0.9814
		0	1	1	C	0.9854
		0	-	1	C	0.9847
					<b>Average</b>	<b>0.9856</b>

TC	NTC	a1	a1	a2	a3	Separation
2	14	1	1	C	0	0.9953
		0	1	C	1	0.9927
		0	0	1	0	0.9889
		0	1	C	1	0.9863
		0	-	1	1	0.9927
					<b>Average</b>	<b>0.9941</b>

TC	NTC	a1	a1	a2	a3	Separation
2	14	1	1	1	C	0.9944
		1	1	0	-	0.9900
		1	1	0	-	0.9890
		1	0	1	-	0.9816
		-	0	0	C	0.9907
					<b>Average</b>	<b>0.9907</b>

TC	NTC	a1	a1	a2	a3	Separation
2	21	1	0	1	-	0.9881
		1	-	1	1	0.9875
		-	C	0	0	0.9884
		1	C	0	0	0.9885
		1	C	0	-	0.9878
					<b>Average</b>	<b>0.9874</b>

TC	NTC	a1	a1	a2	a3	Separation
2	21	-	0	C	C	0.9804
		-	0	C	0	0.9878
		-	0	0	0	0.9884
		-	1	0	0	0.9885
		-	1	-	0	0.9878
					<b>Average</b>	<b>0.9881</b>

TC	NTC	a1	a1	a2	a3	Separation
2	22	0	C	1	-	0.9917
		0	C	1	C	0.9911
		0	0	1	C	0.9886
		0	0	1	C	0.9922
		0	C	1	C	0.9919
					<b>Average</b>	<b>0.9916</b>

TC	NTC	a1	a1	a2	a3	Separation
2	22	1	1	-	0	0.9901
		1	1	C	1	0.9854
		1	1	C	1	0.9850
		1	0	C	0	0.9850
		1	1	C	1	0.9875
					<b>Average</b>	<b>0.9880</b>

TC	NTC	a1	a1	a2	a3	Separation
2	23	0	1	0	-	0.9930
		0	1	0	C	0.9908
		C	1	0	C	0.9902
		0	0	1	C	0.9947
		0	1	0	C	0.9958
					<b>Average</b>	<b>0.9954</b>

TC	NTC	a1	a1	a2	a3	Separation
2	20	1	0	1	0	0.9884
		1	-	1	1	0.9854
		1	0	0	0	0.9889
		1	-	0	1	0.9884
		1	-	0	1	0.9868
					<b>Average</b>	<b>0.9886</b>

TC	NTC	a1	a1	a2	a3	Separation
2	31	-	0	0	1	1.0000
		-	0	0	1	0.9946
		-	0	0	1	0.9991
		-	0	0	1	1.0000
		-	1	-	0	0.9986
					<b>Average</b>	<b>0.9987</b>

TC	NTC	a1	a1	a2	a3	Separation
2	31	1	C	1	0	1.0000
		1	-	0	0	0.9950
		1	-	1	-	0.9995
		1	C	0	0	1.0000
		1	C	1	-	0.9956
					<b>Average</b>	<b>0.9980</b>

Target Class 2 vs Non Target Classes using the Absorption Representation

**Target Class= 3 vs Non Target Classes  
Absorption Representation  
Haar & Daubechies 3 Wavelets**

Haar at scale n=3		Absorption Representation				
TC	NTC	a1	a2	a3	a4	Sparsity
3	5	0	0	1	1	0.988
		0	0	1	1	0.940
		0	0	0	1	0.958
		0	0	1	0	0.940
		0	0	1	1	0.968
		Average				0.964

TC	NTC	a1	a2	a3	a4	Sparsity
3	7	1	0	0	1	0.988
		1	0	0	1	0.958
		1	0	0	1	0.998
		1	0	0	0	0.998
		1	0	0	0	0.998
		Average				0.988

TC	NTC	a1	a2	a3	a4	Sparsity
3	14	1	0	0	0	0.984
		1	0	0	0	0.996
		1	0	0	0	0.996
		1	0	0	0	0.984
		1	0	0	0	0.996
		Average				0.995

TC	NTC	a1	a2	a3	a4	Sparsity
3	15	1	1	1	0	0.982
		1	1	0	0	0.991
		1	0	0	0	0.982
		1	1	0	0	0.988
		1	0	0	0	0.987
		Average				0.986

TC	NTC	a1	a2	a3	a4	Sparsity
3	18	1	1	1	0	0.989
		0	0	1	0	0.968
		0	1	1	1	0.948
		0	0	1	0	0.968
		0	1	0	0	0.948
		Average				0.987

TC	NTC	a1	a2	a3	a4	Sparsity
3	21	0	0	1	0	0.980
		0	0	1	1	0.978
		0	0	1	0	0.980
		0	0	1	0	0.981
		0	1	0	0	0.980
		Average				0.989

TC	NTC	a1	a2	a3	a4	Sparsity
3	26	0	0	0	0	0.940
		0	0	0	0	0.940
		0	0	1	1	0.930
		0	0	1	1	0.930
		0	0	1	0	0.930
		Average				1.005

TC	NTC	a1	a2	a3	a4	Sparsity
3	27	0	0	0	0	0.990
		0	0	0	0	0.977
		0	0	0	0	0.996
		0	0	0	0	0.981
		0	0	0	0	0.975
		Average				0.983

Haar at scale n=3		Absorption Representation				
TC	NTC	a1	a2	a3	a4	Sparsity
3	5	1	1	0	0	0.977
		1	1	1	0	0.980
		1	1	0	0	0.971
		1	1	1	0	0.971
		1	0	0	0	0.975
		Average				0.981

TC	NTC	a1	a2	a3	a4	Sparsity
3	7	1	1	1	0	0.988
		1	0	0	0	0.988
		1	0	1	1	0.981
		1	0	0	0	0.981
		1	1	0	0	0.980
		Average				0.988

TC	NTC	a1	a2	a3	a4	Sparsity
3	14	1	0	0	0	0.992
		1	1	0	1	0.994
		1	1	1	0	0.996
		1	1	1	0	0.992
		1	1	0	0	0.994
		Average				0.993

TC	NTC	a1	a2	a3	a4	Sparsity
3	15	1	1	1	0	0.982
		1	1	0	1	0.980
		1	1	0	1	0.980
		1	0	1	1	0.980
		1	0	1	0	0.987
		Average				0.984

TC	NTC	a1	a2	a3	a4	Sparsity
3	18	1	1	1	0	0.984
		1	0	0	0	0.982
		1	0	0	0	0.984
		1	0	0	0	0.988
		1	0	0	0	0.982
		Average				0.991

TC	NTC	a1	a2	a3	a4	Sparsity
3	21	0	0	0	0	0.980
		0	0	0	1	0.978
		0	0	0	0	0.981
		0	0	0	0	0.981
		0	0	0	0	0.980
		Average				0.986

TC	NTC	a1	a2	a3	a4	Sparsity
3	26	1	0	1	0	0.990
		1	1	1	0	0.984
		1	0	0	0	0.990
		1	1	0	0	0.990
		1	1	0	0	0.990
		Average				1.002

TC	NTC	a1	a2	a3	a4	Sparsity
3	27	1	0	1	0	0.991
		1	1	0	0	0.971
		1	1	1	1	0.985
		1	0	0	0	0.990
		1	0	1	1	0.985
		Average				0.973

Target Class 3 vs Non Target Classes using the Absorption Representation